



Scaling of rough-wall turbulence by the roughness height and steepness

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A roughness scaling behaviour is tested by performing the direct numerical simulation (DNS) of a turbulent channel flow over three-dimensional sinusoidal rough walls. By systematically varying the roughness height k^+ and the roughness steepness S , the results for three groups of cases are considered and compared with those for flat-wall turbulence. The results show that the mean velocity and Reynolds stresses are highly dependent on both k^+ and S . To describe these specific relationships, we define a coupling scale k^+S . With this coupling scale, all the simulated data for the roughness function (ΔU^+), the ratio of the pressure drag to the total wall resistance (γ_p), the normalized bulk mean velocity (U_b^+) and the peak of the streamwise turbulent velocity fluctuations ($\overline{u_p^+}$) collapse onto single curves, which shows that there is a strong direct correlation between them, i.e. $\Delta U^+, \gamma_p, U_b^+, \overline{u_p^+} \propto f(k^+S)$. Furthermore, a model for the prediction of wall resistance based on the roughness function can be established by defining a drag increasing ratio (DI). Accordingly, the wall resistance coefficient C_f can be estimated directly from k^+S of a given rough surface. These results suggest that this coupling scale provides a useful alternative to the equivalent sand grain roughness k_s .

Key words: turbulence simulation, turbulent boundary layers

1. Introduction

Rough-wall turbulence is commonplace in nature and engineering problems. In recent decades, fluid mechanics studies in this area have mainly focused on the following aspects: (i) roughness parametric characterization, including the scaling of the roughness function and equivalent sand grain roughness (Napoli, Armenio & De Marchis 2008; Flack & Schultz 2010; Forooghi *et al.* 2017); (ii) the prediction of rough-wall friction resistance (Flack & Schultz 2010; Yang *et al.* 2016); (iii) the modification of near-wall turbulent coherent structures by roughness (Chan *et al.* 2018; Stroh *et al.* 2020); and (iv) the

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verification of the outer-layer similarity hypothesis (Jimenez 2004; Lee, Sung & Krogstad 2011; Squire *et al.* 2016). Turbulent flows over rough walls almost always undergo higher drag than those over smooth walls. This increase in drag is often quantified with the Hama roughness function ΔU^+ , which reflects the downward shift of the mean streamwise velocity profile of the flow over a rough wall when compared with a smooth wall. In practice, increased drag usually results in efficiency losses, so predicting the drag due to a rough wall is crucial to the management of most engineering flows.

The parameterization of rough surfaces is fundamental to the prediction of wall resistance. The selection of suitable roughness parameters enables the construction of meaningful rules. Nikuradse (1933) carried out experiments on uniform sand grain roughness and proposed the concept of equivalent sand grain roughness height k_s as characteristic of the fully rough regime: different roughness types, such as spherical, square and wedge-shaped roughness elements, can have equivalent k_s values. Further roughness parameters have been proposed. For instance, Schlichting (1936) defined the roughness solidity Λ as the ratio of the total projected frontal roughness area to the wall-parallel projected area, which is now considered an important parameter for the characterization of roughness density. Sigal & Danberg (1990) and Van Rij, Belnap & Ligrani (2002) modified this definition by taking into account the roughness shape and the irregular roughness form, respectively. Recently, the effective slope ES , which is defined as the mean absolute streamwise gradient of the surface (Napoli *et al.* 2008), was proposed as a roughness parameter, and is now widely used. In the present study, this definition is extended to three dimensions as the roughness steepness (S). In addition, the root-mean-square (r.m.s.) of the local surface slope angle can be used to characterize the roughness shape (Yuan & Piomelli 2014). Flack & Schultz (2010) summarized the roughness function correlation models that have been proposed based on these roughness parameters. Some of these models have shown promise in the task of scaling the equivalent sand grain roughness k_s in the fully rough regime for certain classes of rough surfaces, but none has proven universally reliable.

The dependence of the roughness function ΔU^+ on the roughness height k^+ and other geometric features, such as the roughness density and shape, has been explored in many studies. Most of these studies have focused on investigating the individual influence of these parameters. Napoli *et al.* (2008) numerically investigated the influence of ES on the roughness function for a wide range of irregular rough walls and found that $\Delta U^+ \sim f(ES)$ is linear for $ES < 0.15$ and smoothly nonlinear for $ES \geq 0.15$. Schultz & Flack (2009) examined the waviness regime ($ES < 0.35$), in which ΔU^+ scales entirely with ES of the pyramids and has little dependence on the roughness height, and the roughness regime ($ES > 0.35$), in which ΔU^+ is sensitive to the roughness height but is independent of ES . On the other hand, Mejia-Alvarez & Christensen (2013) defined the waviness regime ($ES < 0.15$) and the transition regime ($0.15 < ES < 0.35$), where $ES = 0.35$ represents a limit between slope-dependent and height-dependent regimes. The viscous drag dominates over the pressure drag in the waviness regime, and the roughness function ΔU^+ is dependent on both ES and k^+ . Meanwhile, Flack, Schultz & Rose (2012) studied the roughness scale for predicting the onset of roughness effects in the transitionally rough regime and suggested the peak-to-trough roughness height (k_r^+) for scaling the roughness function of different painted surfaces, instead of the r.m.s. roughness height (k_{rms}^+). Recently, Chan *et al.* (2015) systematically studied the effects of the roughness average height (k_a^+) and the wavelength (or the surface slope) on flows in a three-dimensional sinusoidal rough-wall pipe and concluded that ΔU^+ is strongly dependent on both k_a^+ and ES . Thakkar, Busse & Sandham (2017) showed a linear fit of the

roughness function ΔU^+ based on the solidity parameter, which was further extended to higher-order scaling models by considering more roughness parameters for more realistic random roughness, e.g. the streamwise correlation length, the r.m.s. roughness height and the skewness of surface elevation probability density function, etc. Similarly, the second-order turbulence statistics of a rough-wall flow depend strongly on the topological features of the surface. For example, MacDonald *et al.* (2016) found that increasing the solidity Λ results in a reduction in the peak of the streamwise velocity fluctuations and moves the peak location away from the wall in the sparse roughness regime. However, the scaling of roughness with respect to second-order statistics has not yet been established.

The aim of the present study was to predict the roughness function directly from the roughness parameters of a given rough surface, and to thereby predict the rough-wall resistance. To this end, we performed a direct numerical simulation (DNS) of a fully developed turbulent channel flow with three-dimensional sinusoidal roughness and at the same time systematically varied the roughness height k^+ and the roughness steepness S . A coupling scale k^+S is proposed, which accounts for both the roughness Reynolds number and the steepness of the wall roughness, in order to parameterize the first- and second-order turbulence statistics.

2. Problem formulation and numerical method

The system under consideration is a fully developed turbulent channel flow over three-dimensional sinusoidal rough walls. A schematic diagram of the channel is shown in figure 1. A right-handed Cartesian frame fixed in physical space is employed with x , y and z axes along the streamwise, vertical and spanwise coordinates, respectively. As can be seen in figure 1, k is the semiamplitude of the sinusoidal roughness and λ is the wavelength of the roughness elements. The mean height of the rough surfaces is set at zero, thus the coordinate $y = 0$ is used in what follows as the virtual origin of the bottom wall. The governing equations are the dimensionless Navier–Stokes and continuity equations:

$$\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} = -\frac{\partial p}{\partial x_i} + \frac{1}{Re_b} \Delta u_i, \tag{2.1}$$

$$\frac{\partial u_i}{\partial x_i} = 0, \tag{2.2}$$

where u_i ($i = 1, 2, 3$) = (u, v, w) are the velocity components in the x_i ($i = 1, 2, 3$) = (x, y, z) directions, respectively, p is the pressure normalized by ρU_b^2 with ρ the fluid density, $Re_b = U_b \delta / \nu$ is the bulk Reynolds number where U_b is the bulk mean velocity, ν is the kinematic viscosity, δ is the half-channel height and Δ is the Laplacian operator. The characteristic friction velocity defined by the averaged total drag at the rough surface including the friction drag and pressure drag can be expressed as $u_\tau = \sqrt{(\tau_w / \rho)}$, where τ_w is calculated from the time-averaged mean pressure gradient. The friction Reynolds number (Re_τ) based on u_τ and δ is approximately 540 in all the simulations. Hereafter, the superscript ‘+’ denotes the the physical quantities normalized by the friction velocity u_τ and the wall viscous length scale δ_v ($= \nu / u_\tau$).

For numerical simulation, an irregular physical domain is transformed into a rectangular computational domain based on a boundary-fitted system, by adopting the following

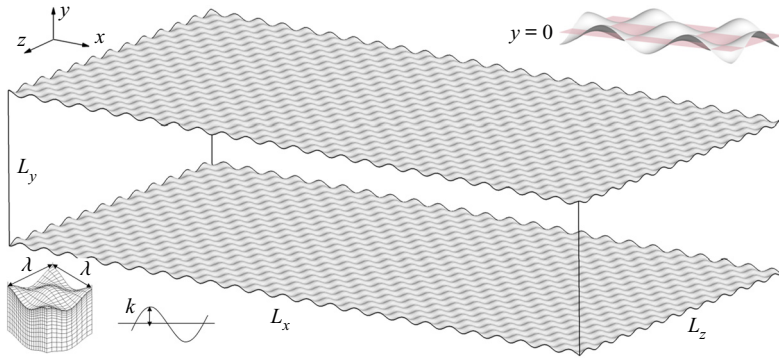


FIGURE 1. Schematic diagram of the turbulent channel flow over three-dimensional sinusoidal rough walls.

algebraic mapping:

$$t = \tau, \quad x_1 = \xi_1, \quad x_2 = \xi_2(1 - \eta_d) + \eta_d, \quad x_3 = \xi_3, \quad (2.3a-d)$$

where ξ_1, ξ_2, ξ_3 and τ are the space and time coordinates in the computational domain, and η_d is the rough surface elevation, expressed as $\eta_d = k \cos(2\pi x/\lambda) \cos(2\pi z/\lambda)$. In the computational space, the bottom and top boundaries are represented by $\xi_2 = 0$ and $\xi_2 = 2\delta$, respectively. With this coordinate transformation, the governing equations (2.1) and (2.2) are rewritten in terms of the curvilinear coordinates $(\tau, \xi_1, \xi_2, \xi_3)$. For the spatial discretization, we applied the pseudo-spectral method in the ξ_1 and ξ_3 directions, along with the second-order finite-difference method on the staggered grids in the ξ_2 direction. The governing equations are integrated in time by the third-order time-splitting method. The computational domain size is $L_x \times L_y \times L_z = 2\pi\delta \times 2\delta \times \pi\delta$, and the corresponding grid number is $N_x \times N_y \times N_z = 288 \times 191 \times 288$. The grid sizes in the streamwise and spanwise directions are uniform with resolutions of $\Delta\xi_1^+ \approx 11$ and $\Delta\xi_3^+ \approx 5.5$, respectively. The grid points along the y -axis follow a cosine distribution with $\Delta\xi_{2,min}^+ \approx 0.1$ near the rough walls to $\Delta\xi_{2,max}^+ \approx 8.9$ near the channel centreline. The no-slip condition is applied to the walls of the channel and a periodic boundary condition is applied in the x and z directions. The flow is driven by a mean pressure gradient, which is dynamically adjusted to keep the flow rate constant in time. Further details of the numerical method can be found in Ge, Xu & Cui (2010) and Zhang, Huang & Xu (2019).

In this study, three groups of numerical cases were simulated as follows: (1) in group A, k^+ is varied while k/λ is kept constant; (2) in group B, λ^+ is varied while k^+ is kept constant; and (3) in group C, k^+ is varied while λ^+ is kept constant. A summary of the flow and roughness parameters is listed in table 1. In fact, in the latter two groups of cases the roughness steepness is changed, which is defined as follows:

$$S = \frac{1}{L_x L_z} \int_0^{L_z} \int_0^{L_x} \left| \frac{\partial \eta_d(x, z)}{\partial x} \right| dx dz. \quad (2.4)$$

Substituting the expression for η_d into the above definition, we can obtain $S = (\pi/8)k/\lambda$. Moreover, it can be easily derived that the roughness steepness has a relation with the traditional solidity parameter, i.e. $S = 2\Lambda$ (Schlichting 1936; MacDonald *et al.* 2016).

Case	Re_τ	k^+	λ^+	N_{wx}	N_{wz}	S	U_b^+	ΔU^+
Group A	542	10	71	48	24	0.36	13.74	4.562
	543	20	141	24	12	0.36	11.98	6.351
	542	30	212	16	8	0.36	10.70	7.598
	547	40	283	12	6	0.36	9.88	8.497
	544	60	424	8	4	0.36	8.53	9.933
	538	80	565	6	3	0.36	7.61	10.863
Group B	544	30	188	18	9	0.405	10.48	7.773
	542	30	212	16	8	0.36	10.70	7.598
	545	30	283	12	6	0.27	11.03	7.35
	537	30	424	8	4	0.18	11.86	6.448
	540	30	565	6	3	0.135	13.10	5.214
	541	30	848	4	2	0.09	15.17	3.191
Group C	541	10	212	16	8	0.12	15.70	2.666
	540	15	212	16	8	0.18	14.07	4.267
	539	20	212	16	8	0.24	12.59	5.768
	541	25	212	16	8	0.30	11.47	6.804
	542	30	212	16	8	0.36	10.70	7.598

TABLE 1. Flow and roughness parameters. N_{wx} and N_{wz} denote the numbers of roughness elements in the streamwise and spanwise directions, respectively.

3. Results and discussion

3.1. Determination of k_s^+

The presence of roughness causes a downward shift in the viscous-scaled mean velocity profile. The logarithmic law for a smooth wall can be expressed as

$$U_s^+ = \frac{1}{\kappa} \ln(y^+) + C, \quad (3.1)$$

where κ denotes the Kármán constant and C is the offset constant. The exact values of these constants are the subject of vigorous debate, and those for channel flows are also slightly different from those of pipe flows and boundary-layer flows (Marusic *et al.* 2013). Here, κ and C were set at 0.40 and 5.3, respectively. For a rough wall, the logarithmic law can be expressed as

$$U_r^+ = \frac{1}{\kappa} \ln(y^+) + C - \Delta U^+ = \frac{1}{\kappa} \ln\left(\frac{y}{k}\right) + C - \Delta U^+ + \frac{1}{\kappa} \ln\left(\frac{k}{\delta_v}\right). \quad (3.2)$$

Specifically, in the fully rough regime, it needs to meet the condition (Hama 1954):

$$C - \Delta U^+ + \frac{1}{\kappa} \ln(k^+) = B, \quad (3.3)$$

where the intercept constant B depends on the specific roughness form.

Figure 2 shows the mean velocity profiles for various rough-wall conditions. In general, these mean velocity profiles satisfy the logarithmic law beyond a certain position. For the first-order statistics, the hypothesis of outer-layer similarity holds for all conditions.

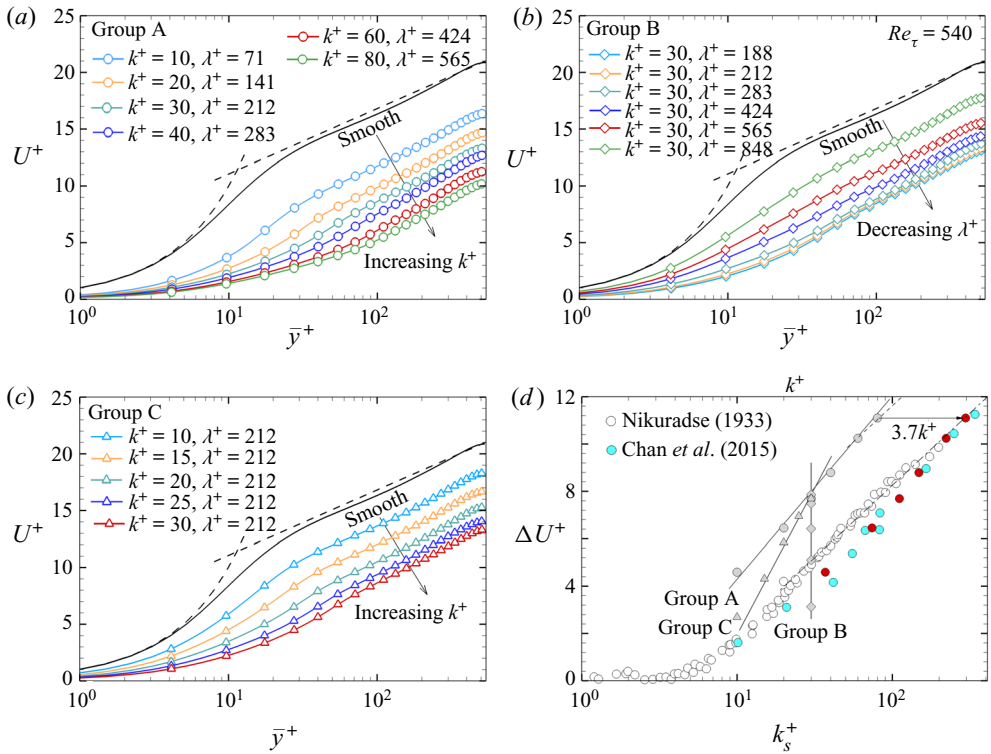


FIGURE 2. Profiles of U^+ for (a) group A, (b) group B, (c) group C and (d) ΔU^+ versus k^+ (grey) and ΔU^+ versus k_s^+ (red).

Figure 2(a) shows the effects of varying the roughness size on the velocity profile. The roughness function ΔU^+ increases with increase in the roughness size. Figures 2(b) and 2(c) show that decreasing the roughness wavelength (with fixed k^+) and increasing the roughness height (with fixed λ^+) both lead to an increase in ΔU^+ . Both of these results can be interpreted in terms of the roughness steepness S . An increase in S corresponds to an increase in the roughness solidity, which can be represented as the frontal area divided by the plane area. The increment in ΔU^+ gradually decreases as S increases.

We used the mean offsets in the range $y^+ = 100-200$ to calculate the roughness function ΔU^+ . Figure 2(d) plots the variation of ΔU^+ with k^+ and also the equivalent sand grain roughness height k_s^+ . For a uniform sand grain surface, the intercept B in (3.3), which is known as Nikuradse's constant (Flack & Schultz 2010), is approximately 8.5. The equivalent sand grain roughness height k_s^+ can then be determined from the roughness function ΔU^+ in the fully rough regime:

$$C - \Delta U^+ + \frac{1}{\kappa} \ln(k_s^+) = 8.5. \quad (3.4)$$

In figure 2(d), the dashed line indicates $\Delta U^+ = (1/\kappa) \ln(k^+) + C - B$, and the dash-dotted line indicates Nikuradse's fully rough asymptote $\Delta U^+ = (1/\kappa) \ln(k_s^+) + C - B$. In the fully rough regime, the roughness function follows a logarithmic dependence on the roughness Reynolds number. From figure 2(d), it is seen that the dashed line approaches Nikuradse's fully rough asymptote by shifting a distance of 3.7 along the

logarithmic abscissa. Thus, we obtain the relation $k_s^+ = 3.7k^+$ for the current sinusoidal roughness type, which is a typical k -type roughness (Leonardi, Orlandi & Antonia 2007). Note that only the two cases ($k^+ = 60$ and $k^+ = 80$) in group A fall onto the fully rough asymptote, whereas the other cases belong to the transitional rough regime. According to the different slopes in the profiles of ΔU^+ versus k^+ , the relation $k_s^+ = 3.7k^+$ cannot be applied to groups B and C, and thus the profile of ΔU^+ versus k_s^+ is only plotted for group A. For group B, even if k^+ increases further, ΔU^+ does not reach Nikuradse's fully rough asymptote. This result is mainly attributed to the limited roughness height ($k^+ = 30$). An appropriate roughness height (at least $k^+ > 30$) is required to produce the fully rough regime. For group C, if we continue to increase the roughness height, it will reach the fully rough asymptote. The rough-pipe DNS data of Chan *et al.* (2015) are also included for comparison in figure 2(d), for which $k_s^+ = 4.1k^+$, a value close to the present data. For $k^+ > 60$, the variation of ΔU^+ with k_s^+ falls onto the fully rough asymptote. The present sinusoidal roughness reaches the fully rough regime for $k_s^+ > 200$, which is much larger than that obtained by considering Nikuradse's sand grain roughness, i.e. $k_s^+ > 70$. This difference may be caused by the difference in the local roughness steepness between Nikuradse's sand grain surface and the current sinusoidal roughness.

3.2. Scaling of the roughness function

The roughness function depends on both the roughness height and the roughness steepness, which can be understood from the above analysis about the downward shift of the mean velocity profile. The roughness function ΔU^+ is plotted against k^+S in figure 3(a). All the data collapse onto a single line, i.e.

$$\Delta U_{est}^+ = 2.66 [\log(k^+S)] + 1.46, \quad (3.5)$$

where ΔU_{est}^+ is the predicted roughness function of k^+S fitted with a linear logarithm function. The goodness-of-fit R^2 is close to 0.97 for the above fitting function equation (3.5). This fit shows that rough walls constructed with different roughness heights and roughness wavelengths exhibit similar behaviour: ΔU^+ increases monotonically with increases in k^+S . According to (3.5), the slope equals 2.66 and is slightly different from $1/\kappa$ as dictated in (3.4). This difference could be related to the fact that these cases are mainly in the transitional rough regime. Note that similar coupling scales were explored in the previous studies. For instance, k_{rms}^+S was considered in Flack *et al.* (2012), and Chan *et al.* (2015) proposed a more general log-linear fitting model based on k^+ and S . The present coupling scale can be regarded as a special case of those of Chan *et al.* (2015).

To further examine the physical meaning of the coupling scale k^+S , the ratio γ_p of the pressure drag to the total drag force is plotted in figure 3(b) as a function of k^+S . A good fit also arises for γ_p , which indicates that ΔU^+ is strongly dependent on γ_p . Note that when k^+S is small, the frictional drag dominates, whereas when k^+S is higher, in the fully rough regime, the pressure drag dominates. In addition, the scaling property of the normalized bulk mean velocity U_b^+ is plotted in figure 3(c) as a function of k^+S . The normalized bulk mean velocity U_b^+ actually reflects the variation of $1/u_\tau$. The result shows that U_b^+ scales well with k^+S . In figure 3(d), ΔU_{est}^+ obtained from (3.5) is compared with the actual ΔU^+ from the present simulations, together with some published data. Several roughness forms were chosen: a three-dimensional 'egg-carton' rough pipe (Chan *et al.* 2015), irregular random two-dimensional sinusoidal roughness (Napoli *et al.* 2008), close-packed right-angle pyramids (Schultz & Flack 2009) and random sand grain roughness (Yuan & Piomelli 2014). Moreover, the average roughness height (Napoli *et al.* 2008; Yuan &

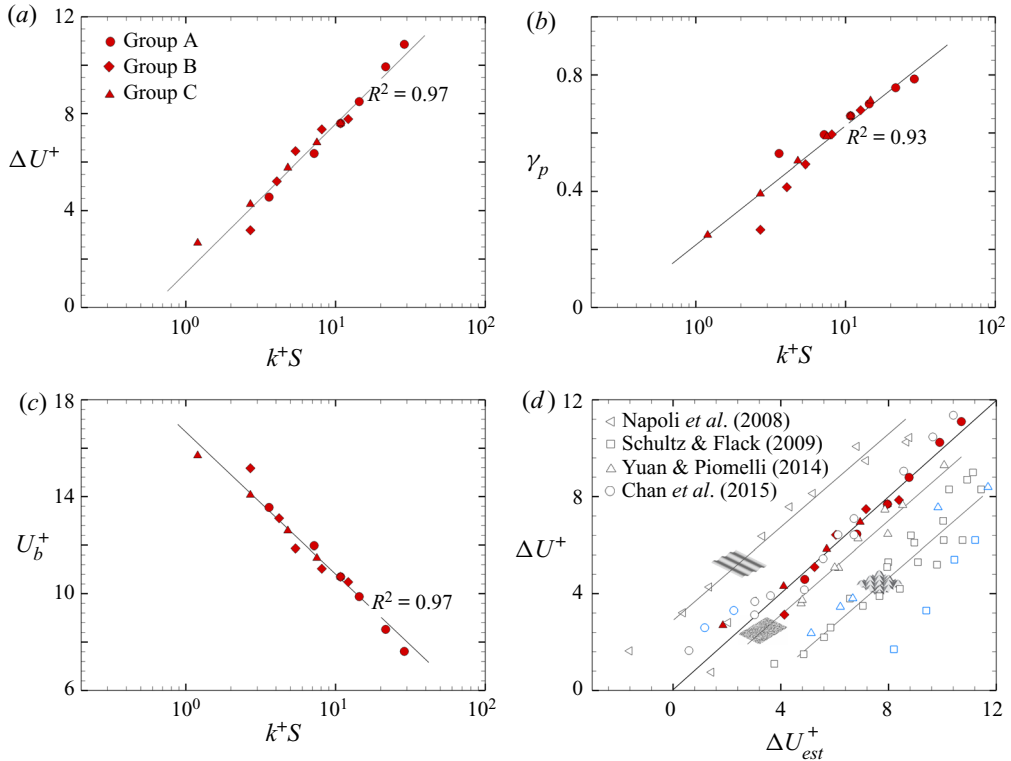


FIGURE 3. Variations of (a) ΔU^+ , (b) γ_p , (c) U_b^+ with k^+S and (d) ΔU^+ versus ΔU_{est}^+ .

Piomelli 2014) and the peak-to-trough roughness height (Schultz & Flack 2009) were chosen as in the literature. These results clearly show that the roughness function for all these rough surfaces, both regular and random, two-dimensional and three-dimensional, depends on k^+S . The differences among these different roughness forms arise in the intercepts of (3.5). In addition, data scattering in the comparison between the roughness function of different roughness forms and the proposed prediction model can also be observed in figure 3(d), as marked by blue symbols. Further discussion will be given in the conclusions.

3.3. Scaling of the drag coefficient

The roughness function exhibits a good scaling behaviour with k^+S , and the roughness function is closely related to the increase in wall resistance. Figure 4(a) shows the relationship between the wall drag coefficient and k^+S . The vertical coordinate is defined as the drag increase ratio $DI = (C_f - C_{f,0})/C_{f,0}$, where $C_{f,0}$ denotes the smooth-wall drag coefficient. In this figure, DI is fitted with a second-order polynomial. Almost all the data points fall on the fitting asymptote, and the goodness-of-fit R^2 is close to 0.99. Note that C_f approaches the smooth-wall result of $C_{f,0} = 0.0059$ (Moser, Kim & Mansour 1999) for $k^+S = 0$, i.e. DI tends to zero as k^+S decreases. In addition, an expression for DI can also be derived from its definition, which is often used in drag reduction designs (Garcia-Mayoral, Gómez-de Segura & Fairhall 2019), while in the present study it is considered in the prediction of drag increase of rough walls. The friction Reynolds number is assumed to be constant in both smooth- and rough-wall flows, and $U_{b,0}^+ - U_b^+$ is

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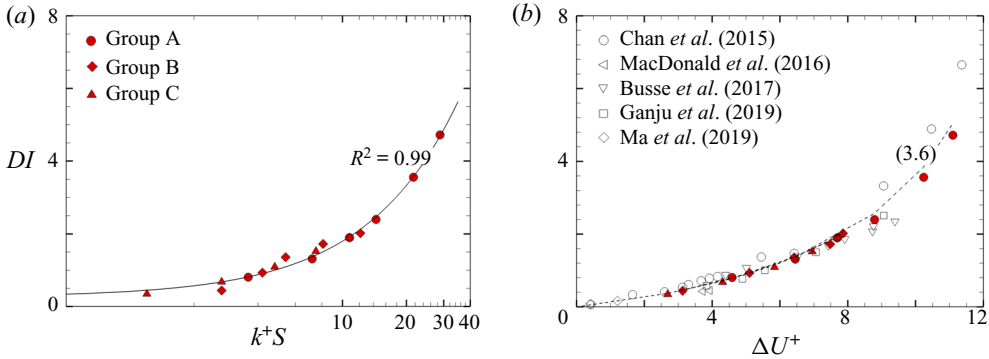


FIGURE 4. Variations of (a) DI with k^+S and (b) DI with ΔU^+ .

assumed to be equal to ΔU^+ , where $U_{b,0}^+$ is the viscous-scaled bulk velocity of the smooth wall and U_b^+ is that of the rough wall. Note that this is an approximation since ΔU^+ is usually determined within the log layer. Then DI is expressed as

$$DI = \left(1 - \Delta U^+ / U_{b,0}^+\right)^{-2} - 1. \quad (3.6)$$

Figure 4(b) compares the drag increase ratio DI calculated from (3.6) with the present results and those obtained in the previous studies (Chan *et al.* 2015; MacDonald *et al.* 2016; Busse, Thakkar & Sandham 2017; Ma, Alamé & Mahesh 2019; Ganju *et al.* 2019). Good agreement with (3.6) is evident in all cases, which indicates that the relationship for wall resistance prediction is also valid for other roughness forms. In fact, we can also obtain an approximate relationship of the drag increase DI with k^+S by substituting the predicted roughness function equation (3.5) into (3.6), but the fitted curve in figure 4(a) is more intuitive. Accordingly, for a given rough surface, relative increases in wall resistance due to roughness elements can be estimated directly from k^+S or ΔU^+ , which is of great significance to practical applications.

3.4. Scaling of velocity fluctuations

The presence of roughness elements has a significant effect on the velocity fluctuations. According to the phase average and triple decomposition, the second-order velocity correlation can be decomposed into three parts, i.e.

$$\overline{u_i u_j} = \overline{(\bar{u}_i + \tilde{u}_i + u'_i) (\bar{u}_j + \tilde{u}_j + u'_j)} = \bar{u}_i \bar{u}_j + \overline{\tilde{u}_i \tilde{u}_j} + \overline{u'_i u'_j}, \quad (3.7)$$

where the second and third terms on the right-hand side are the dispersive and Reynolds stresses, which correspond to the wave-induced and turbulent components, respectively. Figure 5 shows the streamwise Reynolds stresses obtained by using the triple decomposition. In figure 5(a), it can be seen that the streamwise Reynolds normal stress for the smooth wall reaches its maximum at $y^+ \approx 15$ (Jimenez 2004). For rough walls, as the roughness size increases, the intensity of the peaks tends to decrease and they move outward away from the wall. This result indicates that as the roughness size increases, the typical coherent structures near the wall are disrupted, and the turbulent fluctuations are weakened. Correspondingly, the wave-induced fluctuations due to roughness are enhanced

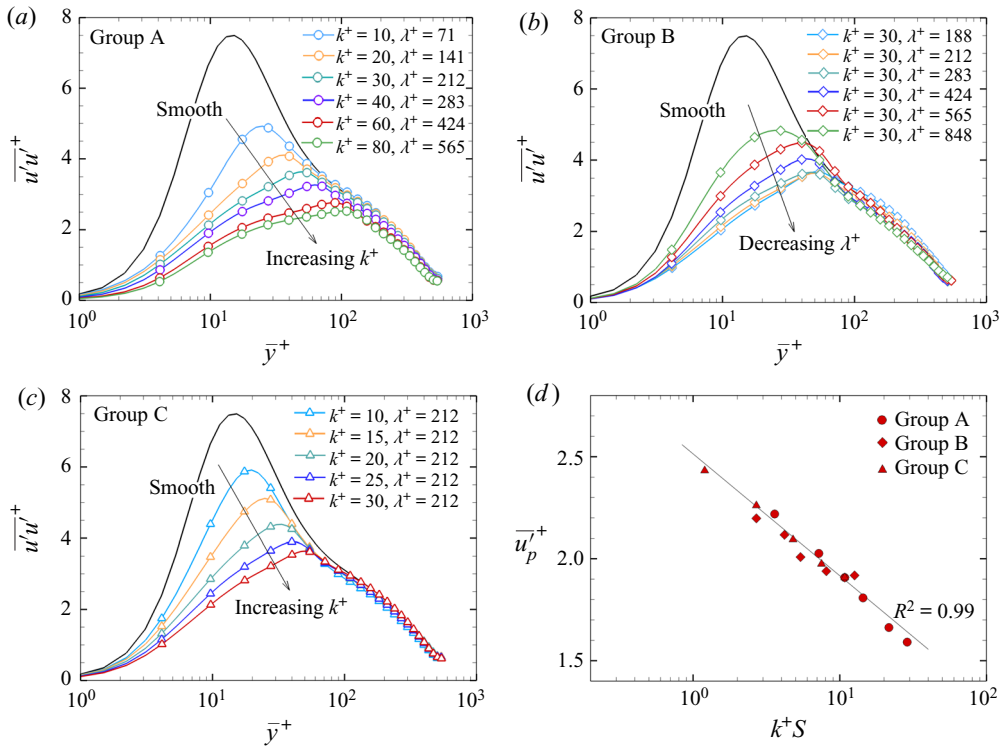


FIGURE 5. Profiles of the streamwise Reynolds stresses for (a) group A, (b) group B, and (c) group C. (d) The peak intensity of the streamwise turbulent velocity fluctuations versus k^+S .

(not shown here). At the same time, the turbulent active region is elevated. Figure 5(c) shows that the results for group C are similar to those for group A. Moreover, these curves coincide with that for the smooth wall for $y^+ > 100$. For group A with large k^+ , e.g. $k^+ = 60$ and 80 , there are slight downward shifts in the rough wall results from the smooth-wall case and the outer-layer similarity is no longer obvious. As the roughness size increases, a higher vertical position is required to achieve similarity in the outer region. This result probably arises because the channel flow is an internal flow for which δ is fixed, and larger roughness elements have a greater impact on the outer-layer similarity. In figure 5(b), the peaks increase as the roughness wavelength increases. However, this increase is not obvious for rough-pipe flows (Chan *et al.* 2018). All the data in group B have the same roughness height, so the peak locations are approximately at the same vertical positions, except for $\lambda^+ = 848$. In the outer region, the data coincide with those for the smooth wall for $y^+ > 100$, and the data for the smallest wavelength in group B, i.e. $\lambda^+ = 188$, are slightly higher than those for the smooth wall. The cases with different roughness wavelengths, for instance the sparsest case $\lambda^+ = 848$ and the densest case $\lambda^+ = 188$, differ mainly in roughness density.

We found that the Reynolds stresses are strongly correlated with both k^+ and S , as is ΔU^+ . Figure 5(d) shows the statistics for the peak values of streamwise turbulent velocity fluctuation $\overline{u'_p}^+$ with respect to the coupling scale k^+S . The data fall on a single line. In order to express this relationship more clearly, a linear–log fit was computed, i.e.

$$\overline{u'_p}^+ = -0.26 [\log(k^+S)] + 2.5, \quad (3.8)$$

which indicates that roughness elements with similar k^+S have similar effects on turbulence fluctuations. This fit is even better than that for ΔU^+ as depicted in (3.5) since R^2 is close to 0.99. Orlandi (2013) found a correlation between the roughness function and the r.m.s. wall-normal velocity fluctuation at the plane of the crests and proposed that the equivalent sand grain roughness can be replaced with the velocity fluctuations. Our results show that the roughness function also has a strong correlation with the peak values of the turbulence fluctuation intensity and thus the coupling scale k^+S provides an alternative to k_s^+ as a means of characterizing rough walls.

4. Conclusions

In the present study, DNSs with a body-conforming grid were performed for turbulent channel flows over three-dimensional sinusoidal rough walls. By systematically varying the roughness height k^+ or roughness steepness S , three groups of cases were chosen and compared with those arising for flat-wall turbulence. We demonstrated that the combination of k^+ and S , i.e. k^+S , produces a predictive scheme that performs significantly better and is more reliable than k^+ or S alone. Note that k^+S is a coupling scale between the inner and outer scales, i.e. $k^+S \sim (k/\delta_v)(k/\lambda)$, similar to that proposed for scaling in the overlap region of high-Reynolds-number wall turbulence (Smits, McKeon & Marusic 2011). Furthermore, a wall resistance increasing ratio can be defined to capture the predictive relationship between the total drag coefficient and the roughness function. As a result, the wall drag coefficient can be estimated directly from the known roughness parameters of the surface, i.e. $C_f \sim f(k^+S)$.

Note also the limitations of the current scaling behaviour. When S is very large or small, the predicted behaviour would become incorrect. Rough forms with a smaller roughness steepness are generally considered to have two-dimensional roughness properties and result in what is known as the waviness regime (Mejia-Alvarez & Christensen 2013). In the case presented above, when the roughness steepness decreases to 0.09 ($k^+ = 30$, $\lambda^+ = 848$), the roughness function begins to deviate from the fitting line. On the other hand, when S is large, an increase in the roughness height or a decrease in the roughness wavelength can cause the flow to enter the dense roughness regime. At this point, the roughness function begins to decline with S . On the other hand, the fitting line of the roughness function tends to rise monotonically, and so fails within this regime. All the cases of the present study lie outside the dense roughness regime. Nevertheless, some cases of Chan *et al.* (2015), Schultz & Flack (2009) and Yuan & Piomelli (2014) deviate from the fitting line, and are marked as blue symbols in figure 3(d). A perusal of the reference data revealed that the deviation is caused by either small or large S . Therefore, the current scaling is applicable to different roughness forms within a certain range of S . Moreover, for irregular rough surfaces, more roughness parameters besides k^+ and S should be taken into account to improve the prediction model, as in Thakkar *et al.* (2017).

It was not the focus of the present study to distinguish the waviness and dense roughness regimes because all the simulated data could be fitted satisfactorily. Here, we focused on the scaling of the turbulence statistics in the intermediate roughness regime, where the roughness height k^+ and roughness steepness S act in concert. The good scaling behaviour of k^+S when applied to the first- and second-order turbulence statistics indicates that it is an important roughness parameter that provides an alternative roughness parametrization to the equivalent sand grain roughness k_s . In addition, it should be pointed out that the roughness form studied here is three-dimensional regular roughness and that the

universality of the proposed coupling scale for other types of roughness forms needs further investigation.

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Declaration of interests

The authors report no conflict of interest.

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