Interplay of deformability and adhesion on localization of elastic micro-particles in blood flow

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The margination and adhesion of micro-particles (MPs) have been extensively investigated separately, due to their important applications in the biomedical field. However, the cascade process from margination to adhesion should play an important role in the transport of MPs in blood flow. To the best of our knowledge, this has not been explored in the past. Here we numerically study the margination behaviour of elastic MPs to blood vessel walls under the interplay of their deformability and adhesion to the vessel wall. We use the lattice Boltzmann method and molecular dynamics to solve the fluid dynamics and particle dynamics (including red blood cells (RBCs) and elastic MPs) in blood flow, respectively. Additionally, a stochastic ligand-receptor binding model is employed to capture the adhesion behaviours of elastic MPs on the vessel wall. Margination probability is used to quantify the localization of elastic MPs at the wall. Two dimensionless numbers are considered to govern the whole process: the capillary number Ca, denoting the ratio of viscous force of fluid flow to elastic interfacial force of MP, and the adhesion number Ad, representing the ratio of adhesion strength to viscous force of fluid flow. We systematically vary them numerically and a margination probability contour is obtained. We find that there exist two optimal regimes favouring high margination probability on the plane Ca-Ad. The first regime, namely region I, is that with high adhesion strength and moderate particle stiffness; the other one, region II, has moderate adhesion strength and large particle stiffness. We conclude that the existence of optimal regimes is governed by the interplay of particle deformability and adhesion strength. The corresponding underlying mechanism is also discussed in detail. There are three major factors that contribute to the localization of MPs: (i) near-wall hydrodynamic collision between RBCs and MPs; (ii) deformation-induced migration due to the presence of the wall; and (iii) adhesive interaction between MPs and the wall. Mechanisms (i) and (iii) promote margination, while (ii) hampers margination. These three factors perform different roles and compete against each other when MPs are located in different regions of the flow channel, i.e. near-wall region. In optimal region I, adhesion outperforms deformation-induced migration; and in region II, the deformation-induced migration is small compared to the coupling of near-wall hydrodynamic collision and adhesion. The finding of optimal regimes can help the understanding of localization of elastic MPs at the wall under the adhesion effect in

blood flow. More importantly, our results suggest that softer MP or stronger adhesion is not always the best choice for the localization of MPs.

Key words: blood flow, capsule/cell dynamics, complex fluids

1. Introduction

Margination, defined as the migration of a particle in blood flow towards the periphery of the blood vessel, allows the particle to come close to the endothelium, and then adhere to the vessel wall (Du Trochet 1824; Koumoutsakos, Pivkin & Milde 2013). It is of significant importance to understand such physiological processes for curing relevant diseases. For example, in the inflammation process, margination of leukocytes towards the vessel wall is the precondition for an organism to perform defence functions, such as adhering to vascular endothelium and transmigrating into the tissues (Ley & Tedder 1995; Fedosov, Fornleitner & Gompper 2012). In atherosclerosis, the thrombosis, formed by the clot, is caused by the margination and accumulation of numerous platelets responding quickly to events on the vessel wall, e.g. injury (Wootton & Ku 1999; Fogelson & Neeves 2015). Additionally, margination has extensive applications in microfluidic devices for the removal of pathogens and the separation of cells (Bhagat *et al.* 2010; Gossett *et al.* 2010; Hou *et al.* 2010).

The root cause of margination has not been completely revealed so far. In blood flow, every component of blood such as plasma and red blood cells (RBCs) may contribute to margination (Farutin & Misbah 2013). Generally speaking, three major factors, i.e. hydrodynamic forces, wall effects and adhesive interactions between ligands and receptors, are considered to be responsible for the margination of micro-particles (MPs). Here, another most important effect, Brownian interaction in nanoparticles, can be ignored due to the large size of MPs (Ramakrishnan et al. 2017). Hence, when placing the MP in the blood flow through injection or other administration, the dynamics of MPs is governed by the complex interplay among these three factors. The performance of the MP will be affected by its physiological properties, such as size, shape, stiffness and surface functionality - also known as the '4S' parameters (Li et al. 2016; Ye et al. 2018c). These properties play different roles, depending on the specific physiological conditions. For example, Decuzzi et al. (2010) found that, in an in vivo experiment, discoidal particles demonstrated the strongest accumulation in most organs, such as spleen and kidney; whereas in the liver, cylindrical particles outperformed the other kinds of particles. Therefore, investigations of the '4S' parameters become crucial in the optimal design of MPs acting as drug carriers in biomedical application.

Among the '4S' parameters, stiffness attracts relatively less attention compared to the other parameters. It should play an important role in the margination process of MPs. Owing to deformability, the symmetry of the Stokes flow is broken. According to the mirror symmetry time reversal theorem proposed by Bretherton (1962), the elastic MP will experience a lateral force in the near-wall region. For example, usually the leukocyte is assumed to marginate towards the vessel wall in blood flow (Freund 2007; Fedosov *et al.* 2012; Marth, Aland & Voigt 2016). Recently it has been discovered that the reversal of margination (migration from the near-wall region to the centre of a vessel) happens when the stiffness is reduced by reorganization of cellular cortical actins (Fav *et al.* 2016).

The dynamics of an elastic particle is more complex than that of a rigid one. The shape of an elastic MP is not given a priori and continuously deforms in flow. The evolution of shape is determined by the dynamic balance between the interfacial force and fluid stress, depending on the local flow environment, Additionally, a large number of RBCs occupy the blood flow. Thus, the deformation and motion of RBCs influence the flow field around MPs. Hydrodynamic interaction can also happen between RBCs and elastic MPs. Poiseuille (1836) recognized that blood corpuscles in the capillaries tended to migrate away from the wall due to deformation-induced migration stemming from viscous effects. Nevertheless, this stiffness-dependent migration of particles has attracted extensive attention very recently. Owing to the similar behaviour of RBCs under flow, a series of elastic particles, such as capsules and vesicles, have been investigated in regard to their migration motion by experimental (Abkarian, Lartigue & Viallat 2002; Callens et al. 2008; Coupier et al. 2008; Kantsler, Segre & Steinberg 2008), analytical (Olla 1997a,b; Seifert 1999; Vlahovska & Gracia 2007; Danker, Vlahovska & Misbah 2009; Farutin & Misbah 2011, 2013; Qi & Shaqfeh 2017) and numerical studies (Cantat & Misbah 1999; Sukumaran & Seifert 2001; Secomb, Styp-Rekowska & Pries 2007; Doddi & Bagchi 2008; Kaoui et al. 2008; Zhao, Spann & Shaqfeh 2011; Nix et al. 2014; Singh, Li & Sarkar 2014). Quantitative determination of the deformation-induced migration is instrumental in revealing the underlying mechanism of the migration behaviours of erythrocytes and leukocytes in blood flow. Abkarian et al. (2002) used light microscopy to study the tank-treading motion and deformation of vesicles in linear shear flow. Upon increasing the shear rate of flow, the vesicle tilted with respect to the substrate, and further incrementation of shear rate $\dot{\gamma}$ made vesicle migrate away from the substrate. These observations revealed the existence of deformation-induced migration. They found that the magnitude of the deformation-induced migration depended on the viscosity η of the fluid, the radius R of the vesicle, the distance h from the substrate and a monotonically decreasing function f(1-v) of the reduced volume v. On the basis of these direct observations, Farutin & Misbah (2013) derived the migration velocity of a vesicle near the wall. From the method using the stresslet of a droplet in a Couette device (Smart & Leighton Jr 1991), they employed an asymptotic method to derive the expression for the migration velocity by determining the stresslet in a power series of the shape parameter Γ of the vesicles. This parameter Γ quantifies the deflation of a vesicle from a sphere with the same volume. In the leading order of Γ , the migration velocity $\sim \dot{\gamma} R^3/h^2$. The theoretical analysis was implemented on the basis of the assumption that the deflation Γ is small. This means that if the shear modulus of the particles, such as that of the capsule, is not high, the expression should not be valid. More recently, Singh et al. (2014) corrected the analytical migration velocity by fitting the results obtained from a series of numerical simulations for capsules with different elastic capillary numbers Ca. They found that there existed a critical Ca_{cr} splitting the migration velocity into two distinct regimes. When $Ca < Ca_{cr}$, migration velocity $\sim Ca$ and $\sim \dot{\gamma} R^3/h^2$, which is similar to the analytical relation for vesicles. However, when $Ca > Ca_{cr}$, migration velocity $\sim Ca^{0.6}$ and $\sim \dot{\gamma} R^{2.35}/h^{1.35}$. Hence, if the capsule is soft (large Ca), the analytic relation is not valid for the capsule any more. Also, a detailed study for lift velocity of RBCs through simulations has been proposed by Qi & Shaqfeh (2017). Here, the elastic MPs pertain to capsules, and will be discussed in detail later.

According to Farutin & Misbah (2013), in addition to deformation-induced migration, hydrodynamic interaction is an additional governing mechanism of particle migration in simple shear flow. Hydrodynamic interaction results in hydrodynamic

diffusion, which is induced by collisions between particles. Collisions between two identical particles, namely homogeneous collisions, such as between capsules (Singh & Sarkar 2015) and between vesicles (Farutin & Misbah 2013), have been investigated numerically and theoretically, respectively. These homogeneous collisions are not essential in particle migration and segregation, because the migrations of the two collision partners are the same. Kumar & Graham (2011, 2012b) and Sinha & Graham (2016) extended this to heterogeneous collisions between capsules with the same volume but different membrane rigidities and shapes, respectively. In a binary suspension of soft and stiff capsules, the stiff particles were observed to accumulate in the near-wall region in a suspension of primarily soft particles, whereas soft particles were found to concentrate on the centreline in a suspension of primarily stiff particles. This segregation behaviour was attributed to larger cross-stream displacement in heterogeneous collisions of stiff particles than that of soft particles. Furthermore, Vahidkhah & Bagchi (2015) proposed that a binary collision between an RBC and a rigid MP should be one of the reasons for the shape-dependent margination behaviour of MPs. The result presented that spherical and oblate MPs marginated more than prolate MPs after several collisions. In terms of the elastic MPs, the collisions between MPs and RBCs will be more complex, and should play an important role in the margination behaviour of elastic MPs. However, it remains largely unexplored

After the particle marginates, it has a chance to interact with the vessel wall and adhere to it, depending on the ligand-receptor binding properties. Adhesion behaviour has been studied extensively using the Bell model (Bell 1978), developed by adhesive dynamics which was first employed to understand the dynamics of leukocyte adhesion under flow (Hammer & Lauffenburger 1987; King & Hammer 2001; Hammer 2014). A number of studies in drug delivery systems focus on the adhesion process (Decuzzi & Ferrari 2006; Charoenphol, Huang & Eniola-Adefeso 2010; Fedosov 2010; Charoenphol et al. 2012; Luo & Bai 2016; Coclite et al. 2017). In human blood, MPs with diameters of 3 µm were found to be the ideal choice for spherical, rigid particles to adhere to vessel walls rather than nanoparticles (Charoenphol et al. 2010, 2012). In addition to spherical particles, Decuzzi & Ferrari (2006) investigated the effects of particle size and shape on the adhesion behaviour from the viewpoint of specific adhesive interaction strength. They predicted that, for a fixed shape (e.g. spherical or ellipsoidal), there existed an optimal volume (size) making the adhesive strength reach a maximum. Additionally, they found that non-spherical particles can carry a larger amount of drugs than spherical particles with the same adhesive strength. More recently, Coclite et al. (2017) constructed a two-dimensional lattice Boltzmann-immersed boundary model to systematically predict the near-wall dynamics of circulating particles with different shapes and adhesive strengths. As for the adhesion behaviour of deformable particles, a variety of dynamic phenomena, including detachment, rolling, firm adhesion and stop-and-go motion (Fedosov 2010; Luo & Bai 2016), were found. Luo & Bai (2016) combined the front-tracking finite element method and adhesion kinetics model to investigate capsule dynamics in flow and adhesive dynamics, respectively. It was found that, for a particle with low Ca, deformation promoted the transition from rolling to firm adhesion; while deformation would inhibit both the rolling to firm adhesion and the detachment to rolling transitions when the Ca of the particle was relatively high. Because the particle with high Ca would collapse on the substrate, and in the middle of the particle, a ligand-receptor free region formed. Further increment of Ca made the rolling motion vanish and the particle shape largely deviate from spherical.

In general, margination is thought to be the necessary precondition for adhesion (Müller, Fedosov & Gompper 2016). Before a particle can interact with a vessel wall, it should marginate into the near-wall region, e.g. the cell-free layer (CFL) in the blood flow. The CFL is a thin layer near the vessel wall with no RBCs inside, which forms due to the deformability of RBCs. However, adhesion can also, in turn, affect the margination process. In engineering applications, micrometre-sized particles are often used as drug carriers due to their better performance over nanometre-sized particles in the margination process (Tasciotti et al. 2008). The thickness of the CFL is also measured in micrometres (approximately 1.5-5.0 μm) in the human vasculature (Fedosov et al. 2010b). Hence, when a particle moves close to or enters the CFL, the particle can interact with the vessel wall through ligand-receptor binding. Additionally, in terms of deformation of the particle, the elastic MP may move away from the wall to the centre of blood flow due to deformation-induced migration. But adhesion may play a role in preventing it escaping from the CFL. Thus, adhesion will affect the choice of elastic MP located near the CFL: entering or departing from the CFL? Such a phenomenon was also reported in previous work (Müller et al. 2016), but without discussion. Researchers pay more attention to the effects of particle '4S' properties on either margination or adhesion (Decuzzi & Ferrari 2006; Müller, Fedosov & Gompper 2014; Vahidkhah & Bagchi 2015).

Considering the above aspects, we focus on the performance of elastic MPs in the whole process from margination to adhesion. We combine the lattice Boltzmann method (LBM) and molecular dynamics to solve the fluid dynamics and particle dynamics (RBCs and elastic MPs), respectively. These two parts are coupled by the immersed boundary method (IBM). In our simulation, the most expensive part is solving the fluid dynamics. The LBM is adopted due to its high natural parallelism. In the past two decades, it has been confirmed as an efficient and accurate numerical solver to handle fluid dynamics problems (Higuera, Succi & Benzi 1989; Benzi, Succi & Vergassola 1992; Chen & Doolen 1998). Its application in simulating blood flow has achieved significant progress (Zhang, Johnson & Popel 2007, 2008; Lorenz, Hoekstra & Caiazzo 2009; MacMeccan et al. 2009; Aidun & Clausen 2010; Clausen, Reasor & Aidun 2010; Melchionna et al. 2010; Czaja et al. 2018; de Haan et al. 2018). In the absence of large numbers of RBCs, Melchionna et al. (2010) took a hydrokinetic approach (Bernaschi et al. 2009) to model large-scale cardiovascular blood flow to recognize the key relevance to the localization and progression of major cardiovascular diseases, such as atherosclerosis. Borgdorff et al. (2014) provided a multiscale coupling library and environment to make possible the simulation of an extra-large-scale vasculature network. Furthermore, considering the existence of RBCs, Zhang et al. (2007, 2008) conducted simulations from the aggregation of multiple RBCs to the rheology of an RBC suspension in two-dimensional blood flow. MacMeccan et al. (2009) and Clausen et al. (2010) extended it to three-dimensional blood flow by coupling the LBM with the finite element method. Additionally, the adhesive dynamics of elastic MPs to a vessel wall is governed by the probabilistic model proposed by Hammer & Lauffenburger (1987). The diameter of MPs is set as 2 μm, and the haematocrit of blood flow is 30 %, in which the thickness of the CFL is comparable to the particle size. To clarify the influence of near-wall adhesion on the localization of MPs, the particle size and blood flow conditions are fixed. The Ca is tuned by changing the shear modulus of elastic MPs, and we vary the adhesion strength to adjust Ad. The interplay of adhesion strength and particle deformability leads to two optimal margination regimes. One is with moderate Ca and high Ad, and the other is with small Ca and moderate Ad. This may shed light on the optimal design of MPs favouring high localization at the wall in blood flow.

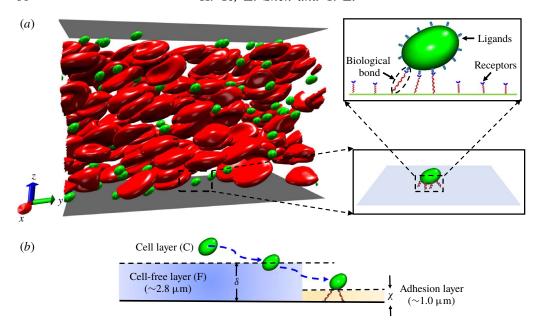


FIGURE 1. (Colour online) Transport of elastic MPs in blood flow. (a) Computational model of margination and adhesion of elastic MPs in blood flow. The zoomed panels give the detailed adhesion behaviour of an elastic MP under a stochastic ligand–receptor binding effect. (b) Schematic of transport process of an elastic MP from the centre of the bloodstream (denoted (C)) to the cell-free layer (F), and then reaching the adhesion layer.

The paper is organized as follows. In § 2 we describe the physical problem involving the transport of elastic MPs in blood flow and the numerical methods that we employ to solve the fluid flow, particle dynamics and adhesive dynamics. We validate our computational method in § 3. Furthermore, § 4 presents the margination and adhesion results. A detailed discussion of the underlying physical mechanisms is also provided. In § 5, conclusions are given.

2. Physical problem and computational method

2.1. Physical problem

In blood flow, most parts of the vessel are occupied by a large number of RBCs. In a normal human blood vessel, the volume fraction of RBCs (haematocrit *Ht*) is approximately 20%–45%. Under the interplay effect of the flow and the vessel wall, RBCs move from the near-wall region to the centre of the vessel due to deformation-induced migration. This results in the formation of a cell-free layer (CFL). The CFL plays the role of a lubricant layer and reduces the blood flow resistance, which is also called the Fåhraeus–Lindqvist effect (Fåhraeus & Lindqvist 1931). When elastic MPs, acting as drug carriers, are injected into a vein, they move with the bulk flow as shown in figure 1(a). The elastic MPs deform under the shear stress and collide with RBCs. The deformation depends on the local flow environment. Additionally, the MPs may move in the cross-stream direction, migrating either towards the wall or to the centre of the channel. Once MPs migrate to the near-wall region, i.e. CFL, the ligands decorated on their surfaces have the chance to interact with the receptors on endothelial cells distributed on the vessel wall (figure 1a). This ligand–receptor binding is required for the further release of

Parameters	Simulation	Physical value
Equilibrium length of bond (l_0)	1	250 nm
Bond strength (k_s)	$2.6 \times 10^{-5} - 1.2 \times 10^{-2}$	$1.64 \times 10^{-9} - 7.56 \times 10^{-6} \text{ N m}^{-1}$
Reactive and rupture distance		
$(d_{on} \text{ and } d_{off})$	4	1 μm
On strength (σ_{on})	0.7305	$1.9 \times 10^{-7} \text{ N m}^{-1}$
Off strength (σ_{off})	0.7305	$1.9 \times 10^{-7} \ N \ m^{-1}$
Unstressed on rate (k_{on}^0)	3.75	$1.3 \times 10^6 \text{ s}^{-1}$
Unstressed off rate (k_{off}^0)	0.05	$1.8 \times 10^4 \text{ s}^{-1}$
Ligand density (n_l)	4.11	$66 \text{ mol } \mu\text{m}^{-2}$
Receptor density (n_r)	1.0	$16 \text{ mol } \mu\text{m}^{-2}$

TABLE 1. Parameters used in adhesive model for ligand-receptor binding.

drug molecules into tumour sites through a vascular targeting strategy (Schnitzer 1998; Neri & Bicknell 2005). However, reaching the CFL cannot guarantee that such interactions will occur. Only when an MP reaches a closer distance to the vessel wall, in which ligands can interact with receptors, does the interaction occur. This distance is determined by the reaction distance between ligands and receptors. We name the layer within this distance as the adhesion layer (χ). Usually the thickness of the adhesion layer is in the range of tens to hundreds of nanometres (Decuzzi & Ferrari 2006; Müller *et al.* 2014, 2016). Here, it is set as 1.0 μ m according to the reaction distance that we used in the computational model. This is reasonable compared to that used in the previous work of Müller *et al.* (2014).

The numerical study is employed to study the transport of elastic MPs due to its flexibility in tuning the properties of MPs and adhesive interactions. Blood flow is considered as a suspension of RBCs. Owing to limited computational resources, a small part of the vessel is taken into account and modelled as a rectangular channel. The size of the channel is of height 36 μ m, width 27 μ m and length 54 μ m. Periodic boundary conditions are applied in the width (x) and length (y) directions. The height (z) direction is bounded by two flat plates. The bottom plate (vessel wall, also named substrate) is fixed and the flow is driven by the moving of the upper one with a constant velocity U. In all of the simulations, shear rates stay at 200 s⁻¹. A total of 162 RBCs and 80 identical elastic MPs are placed inside the channel. The haematocrit is approximately 30%. MPs are initially set to a spherical shape with radius 1 μ m, and their total volume fraction is approximately 0.64% in the channel. Additionally, the ligands and receptors are uniformly distributed on the surfaces of MPs and substrate, respectively. The densities of ligands and receptors are listed in table 1.

2.2. Computational method

2.2.1. Lattice Boltzmann method for fluid flow

The RBCs are immersed within blood plasma in the blood flow. The other components, such as the white blood cells and platelets, are negligible due to their low volume fractions compared to that of RBCs. The plasma is usually considered as a Newtonian fluid. Its dynamics is described by the continuity equation and incompressible Navier–Stokes (NS) equation:

$$\nabla \cdot \boldsymbol{u} = 0, \tag{2.1}$$

$$\rho \frac{\partial \mathbf{u}}{\partial t} + \rho \mathbf{u} \cdot \nabla \mathbf{u} = -\nabla p + \mu \nabla^2 \mathbf{u} + F, \tag{2.2}$$

where ρ is the plasma density, and \boldsymbol{u} and \boldsymbol{p} represent the velocity and pressure of the flow, respectively. The term F on the right-hand side of (2.2) is the external force; μ is the dynamic viscosity of the plasma and is set as 1.2 cP. The LBM is employed to solve the NS equation due to its high efficiency and accuracy in handling incompressible Newtonian flow (Higuera *et al.* 1989; Benzi *et al.* 1992; Chen & Doolen 1998). By discretizing the velocity of the linearized Boltzmann equation, a finite difference scheme is obtained:

$$f_i(\mathbf{x} + \mathbf{e}_i \Delta t, \ t + \Delta t) = f_i(\mathbf{x}, t) - \frac{\Delta t}{\tau} (f_i - f_i^{eq}) + F_i, \tag{2.3}$$

where $f_i(x, t)$ is the distribution function and e_i is the discretized velocity. In the current simulation, the D3Q19 velocity model is used (Mackay, Ollila & Denniston 2013), and the fluid particles have the possible discrete velocities stated in Mackay *et al.* (2013). In (2.3) τ denotes the non-dimensional relaxation time, which is related to the dynamic viscosity in the NS equation as follows:

$$\mu = \rho c_s^2 (\tau - \frac{1}{2}) \Delta t. \tag{2.4}$$

Also in (2.3) $f_i^{eq}(\mathbf{x}, t)$ is the equilibrium distribution function and F_i is the discretized scheme of the external force. In the current simulation, the equilibrium distribution function adopts the form

$$f_i^{eq}(\mathbf{x}, t) = \omega_i \rho \left[1 + \frac{\mathbf{e}_i \cdot \mathbf{u}}{c_s^2} + \frac{(\mathbf{e}_i \cdot \mathbf{u})^2}{2c_s^4} - \frac{(\mathbf{u})^2}{2c_s^2} \right], \tag{2.5}$$

where the weighting coefficients are $\omega_0 = 1/3$, $\omega_i = 1/18$ (i = 1-6) and $\omega_i = 1/36$ (i = 7-18). The term c_s represents the sound speed, which equals $\Delta x/(\sqrt{3}\Delta t)$. The external forcing term can be discretized by the form (Guo, Zheng & Shi 2002):

$$F_{i} = \left(1 - \frac{1}{2\tau}\right)\omega_{i} \left[\frac{\boldsymbol{e}_{i} - \boldsymbol{u}}{c_{s}^{2}} + \frac{(\boldsymbol{e}_{i} \cdot \boldsymbol{u})}{c_{s}^{4}} \boldsymbol{e}_{i}\right] \cdot \boldsymbol{F}. \tag{2.6}$$

Equation (2.3) is advanced through the algorithm proposed by Ollila *et al.* (2011). Here, the solver of the LBM is embedded in a large-scale atomic/molecular massively parallel simulator (LAMMPS) (Plimpton 1995), which is implemented by Mackay *et al.* (2013). After the particle density distributions are known in the whole fluid domain, the properties of the fluid, such as fluid density and velocity, can be calculated as

$$\rho = \sum_{i} f_{i}, \quad \mathbf{u} = \frac{1}{\rho} \sum_{i} f_{i} \mathbf{e}_{i} + \frac{1}{2\rho} \mathbf{F} \Delta t.$$
 (2.7*a*,*b*)

2.2.2. Coarse-grained models for RBC and MP

To capture the dynamics and deformation of RBCs and elastic MPs, we develop a coarse-grained model and implement it into LAMMPS (Ye, Shen & Li 2018b). The RBC is modelled as a liquid-filled coarse-grained membrane, and its equilibrium shape is biconcave. The diameter of an RBC is 7.8 μ m, and the thickness is approximately 2.1 μ m. The surface area and volume of an RBC are 134.1 μ m² and 94.1 μ m³, respectively (Evans & Skalak 1980). In the simulation, the membrane is discretized into 3286 vertices and 6568 triangular elements.

To capture the in-plane shear property of an RBC, a stretching potential $U_{stretching}$ is used. It includes two parts, namely an attractive nonlinear spring potential (wormlike chain model, WLC) and a repulsive power potential (power function, POW) (Fedosov, Caswell & Karniadakis 2010a; Fedosov *et al.* 2011b). They can be expressed as

$$U_{WLC} = \frac{k_B T l_m}{4p} \frac{3x^2 - 2x^3}{1 - x}, \quad U_{POW} = \frac{k_p}{l}, \tag{2.8a,b}$$

where k_BT is the basic energy unit, $x = l/l_m \in (0, 1)$, l is the length of the spring, l_m is the maximum spring extension, p is the persistence length, and k_p is the POW force coefficient. Applying the bending potential

$$U_{bending} = \sum_{k \in 1, \dots, N_s} k_b [1 - \cos(\theta_k - \theta_0)], \tag{2.9}$$

the out-of-plane bending property of an RBC is reflected. Here k_b is the bending stiffness, θ_k is the dihedral angle between two adjacent triangular elements, and θ_0 is the initial value of the dihedral angle. In the following, subscript 0 represents the corresponding initial value; and N_s denotes the total number of dihedral angles.

Besides the above, the bulk properties, such as surface area and volume conservation, are ensured by introducing the penalty forms:

$$U_{area} = \sum_{k=1,\dots,N_t} \frac{k_d (A_k - A_{k0})^2}{2A_{k0}} + \frac{k_a (A_t - A_{t0})^2}{2A_t}$$
(2.10)

and

$$U_{volume} = \frac{k_v(V - V_0)}{2V_0},\tag{2.11}$$

where the first term in (2.10) represents the local area constraint, A_k and A_{k0} denote the area of the kth element and its initial area, respectively, and k_d is the corresponding spring constant. The second term in (2.10) is the global area constraint, A_t is the total area, and k_a is the spring constant. In (2.11), k_v is the spring constant and V is the total volume.

Then the total energy U is

$$U = U_{WLC} + U_{POW} + U_{bending} + U_{area} + U_{volume}.$$
 (2.12)

The nodal forces exerted on each vertex of the RBC membrane are derived from

$$f_i = -\partial U(X_i)/\partial X_i, \tag{2.13}$$

where X_i denotes the vertex of the RBC membrane. Thus, if we know the positions of the membrane vertices, we can calculate the nodal force according to (2.13). The detailed derivation of the force formulae, such as two-point stretching force and three-point bending force, are presented in Ye *et al.* (2018b).

The elastic MPs adopt the same model as RBCs, but with 828 vertices and changeable in-plane shear strength. Before we choose the parameters for the coarse-grained model of RBCs and elastic MPs, we should know the corresponding macroscopic properties through experiments *a priori*. According to the relationships

Parameters	Simulation	Physical value
RBC diameter (D_r)	32	8×10^{-6} m
MP diameter $(2R)$	8	$2 \times 10^{-6} \text{ m}$
RBC shear modulus (μ_r)	0.01	$6.3 \times 10^{-6} \text{ N m}^{-1}$
MP shear modulus (μ_0)	$10^{-4} - 1.0$	$6.3 \times 10^{-8} - 6.3 \times 10^{-4} \text{ N m}^{-1}$
Energy scale (k_BT)	1.1×10^{-4}	$4.14 \times 10^{-21} \text{ N m}$
Viscosity of fluid (η)	0.167	0.0012 Pa s
Area constant (k_a)	0.0075	$4.72 \times 10^{-6} \text{ N m}^{-1}$
Local area constant (k_d)	0.367	$2.31 \times 10^{-4} \text{ N m}^{-1}$
Volume constant (k_v)	0.096	$249 \ N \ m^{-2}$
RBC bending constant (k_b)	0.013	$5 \times 10^{-19} \text{ N m}$

TABLE 2. Coarse-grained potential parameters for RBCs and elastic MPs, and their corresponding physical values.

between coarse-grained model parameters and macroscopic properties (Allen & Tildesley 1989; Dao, Li & Suresh 2006; Fedosov *et al.* 2010a) we have

$$\mu_{0} = \frac{\sqrt{3}k_{B}T}{4pl_{m}x_{0}} \left(\frac{x_{0}}{2(1-x_{0})^{3}} - \frac{1}{4(1-x_{0})^{2}} + \frac{1}{4} \right) + \frac{3\sqrt{3}k_{p}}{4l_{0}^{3}},$$

$$K = 2\mu_{0} + k_{a} + k_{d},$$

$$Y = \frac{4K\mu_{0}}{K+\mu_{0}},$$

$$(2.14)$$

where μ_0 is the shear modulus, K represents the area compression modulus and Y denotes the Young's modulus. Therefore, the potential parameters can be chosen on the basis of the physical quantities. The parameters used in the simulation are listed in table 2.

The accuracy of this model for RBCs and elastic MPs has been validated in our previous works (Ye et al. 2017a; Ye, Shen & Li 2018a; Ye et al. 2018b). In § 3, we will show two more validations to confirm the convergence of both the fluid and membrane meshes and modelling of the rheology of blood flow. Details about the computational efficiency and cost are discussed in § 5 and Ye et al. (2018b). In addition to the above potentials, it is necessary to employ intermolecular interactions between RBCs to characterize their interactions. Here we use the Morse potential as intermolecular interaction (Liu & Liu 2006; Fedosov et al. 2011b; Tan, Thomas & Liu 2012), in the form

$$U_{morse} = D_0[e^{-2\beta(r - r_0)} - 2e^{-\beta(r - r_0)}], \quad r < r_c,$$
(2.15)

where D_0 represents the depth of the potential energy well and β controls its width, r is the distance between the two particles, r_0 is the equilibrium distance, and r_c is the cutoff distance. Additionally, a short-range and purely repulsive Lennard-Jones potential is applied to prevent overlap between RBCs and MPs (Ye *et al.* 2018*b*).

2.2.3. Immersed boundary method for fluid-structure interaction

The IBM is used to couple the LBM with LAMMPS to account for fluid–structure interaction (Peskin 2002; Krüger, Varnik & Raabe 2011; Krüger, Kaoui & Harting 2014; Ye *et al.* 2017*b*). We use the Lagrangian (*X*) and Eulerian (*x*) mesh points in

the computational domain to represent RBCs (or MPs) and fluid particles, respectively. The Eulerian fluid mesh is uniform and the resolution is $\Delta x = 250$ nm in all directions. The Lagrangian mesh for RBCs or MPs is generated by MATLAB code (Persson & Strang 2004; Persson 2005). The mesh is approximately uniform and the mesh size is set at approximately $\Delta X = (0.6-0.8)\Delta x$. Then there are approximately 32 Eulerian points across one RBC in diametral direction. That is sufficient to resolve the deformation and motion of an RBC (MacMeccan *et al.* 2009; Vahidkhah & Bagchi 2015). The coupling is fulfilled by the interpolation of velocity and force distributions between Lagrangian and Eulerian mesh points (Mittal & Iaccarino 2005).

To ensure a no-slip boundary condition, the membrane vertex X with Lagrangian coordinate s should move at the same velocity as the fluid around it, that is

$$\frac{\partial X(s,t)}{\partial t} = u(X(s,t)). \tag{2.16}$$

The velocity can be interpolated by the fluid velocity through a smoothed Dirac delta function δ :

$$u(X,t) = \int_{\Omega} u(x,t)\delta(x - x(X,t)) d\Omega.$$
 (2.17)

This condition will cause the membrane to move and deform. The membrane force density F(s, t) is obtained by derivation of potential functions such as (2.13), and is distributed to the surrounding fluid mesh points by

$$f^{fsi}(x,t) = \int_{\Omega} F^{fsi}(X,t)\delta(x - x(X,t)) \,\mathrm{d}\Omega. \tag{2.18}$$

2.2.4. Adhesive model for ligand-receptor binding

The ligand–receptor binding is described by the association and dissociation of biological bonds, and it is governed by the probabilistic adhesion model (Hammer & Lauffenburger 1987). Figure 1(a) gives a schematic of the adhesive model. When the ligands on the MP approach the receptors on the vessel wall, they have the chance to bind together, which is determined by the probability P_{on} . In the reverse situation, the existing bond has a probability P_{off} to break. They can be expressed as

$$P_{on} = \begin{cases} 1 - e^{-k_{on}\Delta t}, & l < d_{on}, \\ 0, & l \geqslant d_{on}, \end{cases} \text{ and } P_{off} = \begin{cases} 1 - e^{-k_{off}\Delta t}, & l < d_{off}, \\ 0, & l \geqslant d_{off}. \end{cases}$$
 (2.19*a,b*)

Here Δt is the time step in the simulation, d_{on} and d_{off} are the cutoffs for bond creation and breakup, respectively, and k_{on} and k_{off} are the association and dissociation rates with the forms

$$k_{on} = k_{on}^{0} \exp\left(-\frac{\sigma_{on}(l - l_{0})^{2}}{2k_{B}T}\right)$$
 and $k_{off} = k_{off}^{0} \exp\left(\frac{\sigma_{off}(l - l_{0})^{2}}{2k_{B}T}\right)$, (2.20*a*,*b*)

where σ_{on} and σ_{off} are the effective on and off strengths, representing a decrease and increase of the corresponding rates within d_{on} and d_{off} , respectively, and k_{on}^0 and k_{off}^0 are the reaction rates at the equilibrium length $l=l_0$ between ligand and receptor. The mechanical properties of the biological bond are described by a harmonic spring. The equilibrium length is l_0 , and the force exerted on the receptor and ligand is $F_b = k_s(l-l_0)$. Here, k_s represents the adhesive strength. This model and the relevant

parameters (cf. table 1) are chosen according to the previous works of Fedosov (2010) and Fedosov, Caswell & Karniadakis (2011a).

There are three dimensionless parameters:

Reynolds number
$$Re = \rho \dot{\gamma} R^2 / \mu$$
, (2.21)

capillary number
$$Ca = \mu \dot{\gamma} R/\mu_0$$
, (2.22)

adhesion number
$$Ad = k_s/\mu \dot{\gamma} R$$
. (2.23)

Considering the physiological environment surrounding the cell, the fluid flow is considered as a Stokes flow. Thus, Re is very small, and we fix its value as Re = 0.0134 to approximately represent the Stokes regime. The capillary number represents the ratio of the shear stress exerted on the surface of an elastic MP to the elastic force induced by the deformation of the elastic MP; and μ_0 is the shear modulus of the MP. The higher the Ca, the softer the particle. The adhesion number denotes the ratio of adhesive strength to shear stress of the flow. Thus, the higher the Ad, the stronger the adhesion strength. In our simulations, Ca is tuned by varying the shear modulus μ_0 , and Ad is varied by changing the adhesive strength k_s .

3. Validation of numerical method

Grid independence studies of the fluid and RBC membrane are conducted. We perform a case study in which a single RBC with diameter D_r moves in simple shear flow $v(z) = \dot{\gamma}z$, as shown in figure 2(a). Here the RBC is discretized with different numbers of vertices as presented in figure 2(b). To exclude the size effect of the channel, we adopt the same channel and same shear rate as the margination studies of MPs. First, we vary the mesh size Δx of the fluid, and track the trajectories of the centre of the RBC in the height direction (z direction). Figure 2(c) shows that, when the mesh is coarse ($\Delta x = 1/8D_r$), the trajectory is obviously different from those with fine meshes, and it is not smooth compared to those with fine meshes. Further increase of mesh resolution ($\Delta x = 1/16D_r$) leads to a more consistent trajectory, and only a small difference of trajectory exists between it and with the finer mesh. When the mesh resolution increases to $\Delta x = 1/32D_r$, the difference between it and with the finer mesh can be negligible. Thus, the current study adopts the mesh size $\Delta x = 1/32D_r$. Furthermore, we change the number of discretized vertices of the RBC membrane. Four cases V = 766, 1418, 3286 and 9864 are investigated here; V and T represent the numbers of vertices and triangular elements of the RBC membrane, respectively. Again, we track the trajectories of the centre of the RBC in the height direction. We find that the discretization of the membrane has a weak influence on the motion of an RBC under the current scheme (766 < V < 9864). There is only a small difference for the case of V = 766, compared to other cases. To ensure enough convergence of the membrane mesh, we adopt a relatively fine mesh V=3286. In the following simulations, the fluid mesh size is $\Delta x = 1/32D_r$ and the discretization of the RBC membrane is V = 3286.

Here, we study the Fåhraeus effect and the Fåhraeus–Lindqvist effect of blood flow with different haematocrits (15 % and 30 %) in a tube with different diameters (10, 20 and 40 $\mu m)$ to validate our numerical method in terms of rheology of blood flow. The length of the tube is fixed as three times the diameter.

The Fåhraeus effect presented an increased value of discharge haematocrit (H_d) measured at the tube exit in comparison with that before the tube entrance. It was first discovered in *in vitro* experiments of blood flow in a tube (Fåhraeus 1929).

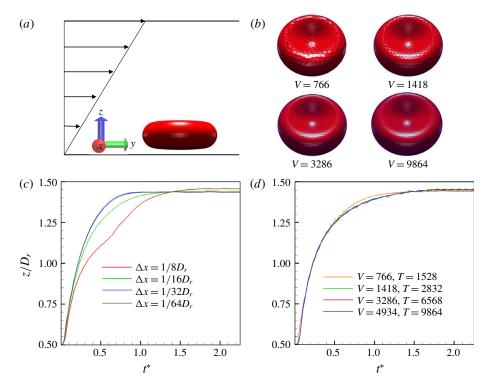


FIGURE 2. (Colour online) Grid independence studies. (a) Model of motion of a single RBC in simple shear flow. (b) Discretization of an RBC membrane with different numbers of vertices. (c) Grid independence of fluid mesh. (d) Grid independence of RBC discretization.

In our simulation, we take the same definition as that in Fedosov *et al.* (2010b) to calculate the discharge haematocrit:

$$H_d = \frac{\bar{v}_c}{\bar{v}} H_t, \tag{3.1}$$

where $\bar{v} = Q/A$ is the mean velocity of the blood flow, and \bar{v}_c is the average cell velocity averaged in time in the steady-state regime.

The Fåhraeus–Lindqvist effect stated that apparent blood viscosity decreased with decrease of tube diameter found in experiments (Fåhraeus & Lindqvist 1931; Pries, Neuhaus & Gaehtgens 1992; Pries *et al.* 1994). It is usually convenient to calculate the relative apparent viscosity to investigate this effect, which is defined as

$$\eta_{rel} = \frac{\eta_{apparent}}{\eta_{plasma}},\tag{3.2}$$

where the apparent viscosity $\eta_{apparent} = \Delta P D_{tube}^2/32\bar{\nu}L$, with ΔP and L the pressure difference between inlet and outlet of the tube and the length of the tube, respectively. In figure 3(a), we show snapshots of blood flow in a tube with different diameters

In figure 3(a), we show snapshots of blood flow in a tube with different diameters under haematocrit 15%. We calculate the discharge haematocrit and relative viscosity of the blood flow, and compare our results with those in experiment (Pries et al. 1992) and numerical (Fedosov et al. 2010b; Czaja et al. 2018) studies in figure 3(b,c).

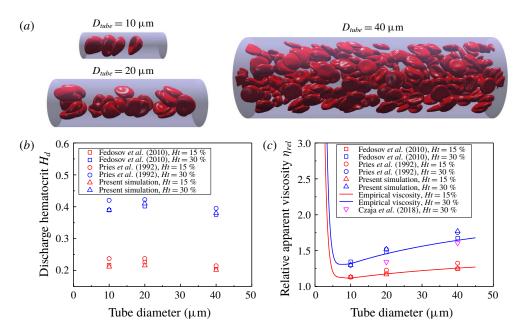


FIGURE 3. (Colour online) Fåhraeus and Fåhraeus-Lindqvist effects. (a) Snapshots to show the tube flow with different diameters under haematocrit 15%. (b) Fåhraeus effect: discharge haematocrit comparison. (c) Fåhraeus-Lindqvist effect: relative viscosity validation.

As for the relative viscosity of the blood flow, we also provide the empirical viscosity from experiment (Pries *et al.* 1994). We find that our results are more consistent with an empirical value under low haematocrit 15% compared with that under haematocrit 30%. What is more, the results are more consistent with the numerical results than with the empirical results. The discrepancies between numerical simulations and experiments may be induced by the interaction between an RBC and the tube wall, and the estimation method in experiments (Fedosov *et al.* 2010*b*). However, the current study has adequate accuracy to model the blood flow from the above comparison.

4. Results and discussion

We study the margination behaviours of elastic MPs (i) without (Ad = 0) and (ii) with (Ad = 0.07-32.8) adhesion. The stiffness of the elastic MPs is varied by changing the shear modulus μ_0 , which makes Ca range from 0.00037 to 3.7. This corresponds to the shear modulus of an MP from 6.3×10^{-4} to 6.3×10^{-8} N m⁻¹ (note that the shear modulus of an RBC is 6.3×10^{-6} N m⁻¹). The elastic MPs are randomly placed among RBCs in the whole channel at the beginning of all simulations. For MPs with different shear moduli, they have the same initial configurations. This eliminates the influence of the initial condition on the margination results.

4.1. Margination of elastic MPs without adhesion

The margination of MPs without adhesion is first investigated. The margination process of a typical case of MPs with Ca = 0.0037 is shown in figure 4. In these

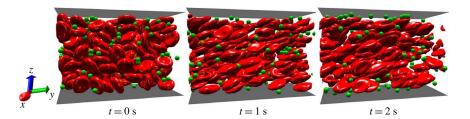


FIGURE 4. (Colour online) Snapshots to show the margination behaviour of an elastic MP (Ca = 0.0037) without effect of adhesion.

snapshots, at t=0 s, we can see that MPs are randomly distributed as well as RBCs. The RBCs and MPs are considered at their equilibrium states. The shapes of RBCs and MPs are biconcave and spherical, respectively. At time t=1.0 s, the fluid flow is developed. A large deformation has been observed for RBCs. Under the shear flow, we find that RBCs align their major axes along the flow direction. Though the deformation of MPs is small due to their high stiffness (small Ca=0.0037), they should deform under the shear stress; and the deformation will be significant for the case with high Ca. In addition to the deformation, RBCs and MPs both demonstrate cross-stream migration, but towards the opposite directions. RBCs migrate from the near-wall region to the centre of the channel, while MPs move towards the wall. We also find that the CFL becomes clear and that some MPs reach the CFL quickly. As simulation time further advances, at t=2.0 s, the CFL is fully developed and MPs start to accumulate at the CFL.

Localization of MPs at the wall is characterized by margination probability $\Phi(t)$, which is defined as

$$\Phi(t) = \frac{n_f(t)}{N},\tag{4.1}$$

where $n_f(t)$ represents the number of MPs with centres locating in the CFL at time t, and \hat{N} denotes the total number of MPs in the channel. Before quantifying the margination probability, the thickness of the CFL is estimated in the absence of MPs. We use the same method as proposed by Fedosov et al. (2010b); the thickness of the CFL is approximately 2.8 μ m for current blood flow with Ht = 30 %. This is consistent with previous numerical studies (Lee et al. 2013; Müller et al. 2014). Figure 5(a) gives the evolution of margination probabilities Φ for three different stiffnesses (Ca = 0.00037, 0.037 and 3.7). We find that the margination process can be split into two stages. In the first stage, the margination probability increases very fast, which signifies that there are more and more particles moving from the centre to the CFL. We note that, in this stage, the margination probabilities of softer particles increase faster (Ca = 0.037 and 3.7) than that of stiff particles (Ca = 0.00037). However, the duration of this stage for stiff particles is longer than those of soft particles. Therefore, when the first stage ends, the margination probability of stiff particles is higher than those of soft ones. In the second stage, the margination probabilities of both stiff and soft particles increase slower than those in the first stage. Also, the growth rates for these particles are almost the same.

To investigate this stiffness dependence of margination behaviour, the mean-square displacements (MSDs) for MPs with different stiffnesses are calculated. The deformation of RBCs in the blood flow induces the fluctuation of flow around them. This is considered as the root cause of migration of rigid particles such as platelets

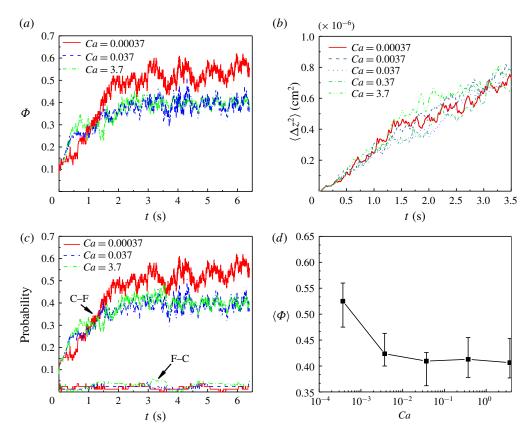


FIGURE 5. (Colour online) Margination behaviour of elastic MPs with different stiffnesses. (a) Evolution of margination probabilities for elastic MPs. (b) Mean-square displacement of elastic MPs during margination. (c) Probabilities of two types of motion: centre to cell-free layer (C–F) and cell-free layer to centre (F–C). (d) Time-averaged margination probability in the steady-state regime.

in blood flow (Zhao, Shaqfeh & Narsimhan 2012). From figure 5(b), we find that there are no obvious differences among MSDs for all of the MPs. At the initial stage (t < 1.0 s), the MSDs are almost the same. After that, the MSDs for MPs become different, but with only small variations. We calculated the diffusivities, defined as $D = \langle \Delta z^2 \rangle / 2t$, and they range from approximately 0.9 to $1.2 \times 10^{-7} \text{ cm}^{-2} \text{ s}^{-1}$ for these MPs. This is in good agreement with previous studies (Zhao & Shaqfeh 2011; Vahidkhah & Bagchi 2015). The diffusivity is approximately two orders of magnitude higher than the Brownian diffusivity, which means that the existence of RBCs augments the diffusion of MPs. However, from these results, RBC augmentation of diffusion is stiffness-independent. Thus, diffusion alone cannot explain the observed stiffness dependence of margination behaviour.

To gain a better insight into the margination behaviour, the types of motion of MPs in blood flow are studied. Compared to rigid particles in blood flow, elastic MPs may experience deformation-induced migration, which can drive them to move away from the vessel wall (Coupier *et al.* 2008; Kumar & Graham 2012b). This is the essential mechanism for CFL formation in a blood vessel. Here the motion of elastic MPs can be classified into four types: (i) staying in the centre; (ii) staying in the CFL;

(iii) moving from the centre to the CFL (C-F); and (iv) moving from the CFL to the centre (F-C). Obviously, the first two types cannot contribute to the localization of MPs at the wall. The margination probability is attributed to the difference between the last two types as shown in figure 5(c). We find that the probabilities of F-C motion for all of the elastic MPs are the same and the values are almost 0. This indicates that there are only a few particles migrating from the CFL to the centre region. We also observe that the C-F motion has the same tendency as the margination probability Φ . All these results lead to the conclusion that localization of MPs at the wall in the current study is determined by the C-F motion. This is different from our previous study in Ye et al. (2017a), in which F-C motion at some time can dominate the margination behaviour of particles. The reason for this difference mainly lies in the size of the particle and the haematocrit of blood flow. If the size of the particle is large (2 µm in diameter), and the haematocrit is high (30%), there is no available space for the particle to stay in the centre of the channel, because, under shear flow, most parts of the centre region are occupied by RBCs. Hence, F-C motion is not significant in the present study.

To quantify the stiffness effect on margination probability, the mean margination probabilities $\langle \Phi \rangle$ are calculated and are given in figure 5(d). The mean value takes the time-averaged value of margination probability, which is estimated in a time interval within the steady-state regime. We can see that the margination process of MPs reaches a steady state after approximately t=2.5 s. The localization of MPs at the wall decreases dramatically when the particles are very stiff (small Ca). With further decrease of stiffness (increase of Ca), there is no obvious change of the margination probability.

The underlying mechanism of this stiffness dependence of margination behaviour relies on the interplay of collision with RBCs and deformation-induced lateral migration of elastic MPs (Qi & Shaqfeh 2017). At the beginning of the simulation, the RBCs near the wall of the channel sense the shear flow, and then deform under the shear stress. The existence of the wall makes RBCs move away from the wall, and then the CFL forms. According to the previous study (Katanov, Gompper & Fedosov 2015), the time needed to fully form the CFL is approximately 0.8 s under the conditions (channel size and haematocrit) in the current study (Ye et al. 2017a). This signals that the first stage of margination probability corresponds to the development of the CFL (cf. figure 5a). In this stage, a large number of RBCs move from the near-wall region to the centre of the channel. The migration of RBCs should induce a reverse flow moving from the centre to the CFL in the regions around RBCs, due to the mass conservation of the fluid. Hence, if the MPs are located in these reverse flow regions, they will move along with the flow from the centre to the CFL. This phenomenon looks like the exclusion effect that particles are excluded by RBCs from the near-wall region to the centre of the channel (Crowl & Fogelson 2011). Specifically, the exclusion effect appears more significant for soft particles than for stiff particles. Here soft MPs have stronger alignment with the flow due to deformation. This is the reason why, in the first stage, the soft MPs marginate faster than stiff ones. In the second stage, the CFL is fully formed and the flow is fully developed. The soft MPs in the near-wall region may experience deformation-induced migration due to the existence of the wall. This results in low accumulation of soft MPs in the CFL. However, when the stiffness of the MPs decreases to a critical value (approximately Ca = 0.037), the deformation-induced migration dominates the motion of MPs. Therefore, under this circumstance, changing stiffness of MPs will not result in an obvious difference of the margination probability.

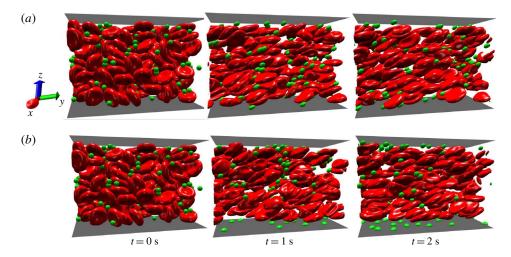


FIGURE 6. (Colour online) Snapshots for the margination behaviour of elastic MPs (Ca = 0.37) under the influence of adhesion: (a) Ad = 0.07 and (b) Ad = 32.8.

4.2. Adhesion effect on localization of elastic MPs at wall

In figure 5(a), it is obvious that the evolution of margination probability oscillates. In some time intervals, the oscillation amplitude can reach approximately 20% of the margination probability. This indicates that many MPs are travelling between the centre of the channel and the CFL. Under this circumstance, MPs near the CFL have a chance to interact with the vessel wall through ligand–receptor binding. Since the diameter of an MP is $2.0~\mu m$, when it moves near the CFL, part of its surface will be located inside the adhesion layer according to the thicknesses of the CFL $(2.8~\mu m)$ and adhesion layer $(1.0~\mu m)$.

To have a direct comparison, figure 6 presents the adhesion effect on the localization of elastic MPs. In figure 6(a,b), the stiffnesses of MPs are the same Ca=0.37, while the adhesion strengths are different: (a) Ad=0.07 and (b) Ad=32.8. We find that there are more MPs entering and staying inside the CFL when increasing the adhesion strength Ad. With small Ad=0.07, when MPs move into the CFL, only a small contact area forms between the MP and the substrate. The ligand–receptor binding is not strong, and these MPs move freely near the substrate. However, with strong adhesion Ad=32.8, the MPs collapse on the substrate like a droplet on the ground. It should be emphasized that this collapse phenomenon only happens for soft MPs. If the MP is stiff or rigid, it cannot deform any more. They can only roll on the substrate (King & Hammer 2001; Decuzzi & Ferrari 2006; Coclite et al. 2017). However, elastic MPs can either roll or firmly adhere on the substrate, depending on the adhesion strength Ad.

To differentiate the margination probability of MPs with and without adhesion, we use Π rather than Φ to represent the margination probability with the adhesion effect. The interplay of stiffness and adhesion strength effects is isolated in figure 7. Figure 7(a) gives the relationship between the margination probability and the adhesion strength for MPs with different stiffnesses. We use $\langle \cdot \rangle$ to denote the mean value over a time interval, and subscript m represents margination. We find that the margination probabilities have the same tendencies with increment of adhesion strength for MPs with different stiffness. Under relatively low adhesion

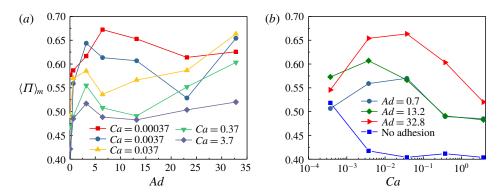


FIGURE 7. (Colour online) Margination probabilities of elastic MPs with adhesion effect. (a) Margination probability against adhesion strength with different MP stiffnesses. (b) Margination probability against MP stiffness with different adhesion strengths.

strength (Ad < 5), the margination probability dramatically increases with increasing adhesion strength; while further increment of adhesion strength makes the margination probability slowly decrease (5 < Ad < 23). But when the adhesion strength exceeds a critical value, the margination probability will increase with the increment of adhesion strength again. The critical value differs among MPs with different stiffnesses. The margination probability against stiffness is given in figure 7(b) for MPs with different adhesion strengths. The margination probability result of MPs without adhesion (Ad = 0) is also presented to allow a comparison. We find that, with the same adhesion strength, the margination probabilities increase with the increment of Ca when MPs are stiff (relatively small Ca); while a further increase of Ca results in the decrease of margination probability. Though the margination probability has a decrement when the MP is soft (high Ca), it is still higher than that of an MP without adhesion. The difference of margination probability between the cases with and without adhesion is determined by the adhesion strength. These relationships remain to be discussed in detail later.

Furthermore, we summarize the results of margination probabilities in the contours on the Ca-Ad plane as shown in figure 8. We find that two peaks exist in the contours for the margination probability. One is in the region with high adhesion strength Ad and moderate stiffness (moderate Ca), namely I; the other one is located in the region with moderate adhesion strength Ad and large stiffness (small Ca), denoted as II. These two regions, which favour margination behaviour, are determined by the interplay of the adhesion effect and deformability. To investigate the underlying mechanisms, the adhesion behaviour of elastic MPs is first examined.

4.3. Adhesion behaviour of elastic MPs

The adhesion behaviour should be influenced by the deformability according to previous studies (Ndri, Shyy & Tran-Son-Tay 2003; Khismatullin & Truskey 2005; Balsara, Banton & Eggleton 2016; Luo & Bai 2016; Ye *et al.* 2018*a*). The deformability of MPs can affect the hydrodynamics, which balances the spring force exerted by the biological bonds. It is revealed that deformation of an MP can promote the adhesion of the MP to the substrate. Previous studies (Ndri *et al.* 2003; Khismatullin & Truskey 2005) demonstrated that when an elastic MP moved near

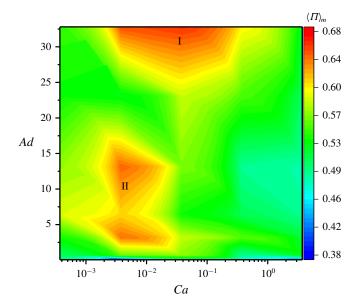


FIGURE 8. (Colour online) Contours of margination probability on the Ca-Ad plane.

the substrate, the bottom of the MP was flattened. This resulted in a large contact area between the MP and the substrate. Then the adhesion became strong. Before we present the adhesion behaviour of elastic MPs in blood flow, the classification of the types of motion of elastic MPs is shown first. On the basis of our adhesive model, the probabilistic model (Hammer & Lauffenburger 1987), there are a total of four motion types of elastic MPs, which are presented in figure 9(a). They are characterized by the snapshots at t = 0.01, 0.02, 0.03 and 0.04 s along the flow (y) direction. In the case of firm adhesion (FA), the MP collapses on the substrate like a droplet and cannot move any more. The MP can slowly move at some time intervals despite collapsing on to the substrate in stop-and-go motion (SG). However, in stable rolling (SR), the MP moves on the substrate. Additionally, the MP deforms like an ellipsoid under shear stress with a flattened contact area between MP and substrate. In the free motion (FM), the MP totally becomes an ellipsoid, and it moves freely near the substrate. Under FM, there is no obvious contact between the MP and the substrate. These motions are distinguished by calculating the velocity of the MP's centre (cf. figure 9b) along the flow direction (y direction). In FA, the velocity is nearly zero through the simulation time. When the velocity is non-zero at some time intervals and zero at other time intervals, it is referred to as SG. As for the SR and FM, there is no difference in terms of trajectories of the MP's centre, while their velocities are not identical. If the velocity of the MP's centre is the same as the fluid velocity at the same location, it is defined as FM. Otherwise, it is SR motion. The detailed classification of these adhesion types is discussed in the supporting information (supplementary material is available at https://doi.org/10.1017/jfm.2018.890).

The adhesion probability is used to quantify the behaviours of MPs near the substrate; it is defined as

$$\Pi_a(t) = \frac{n_a(t)}{N},\tag{4.2}$$

where $n_a(t)$ represents the number of elastic MPs that have interactions with the substrate at time t, N is the total number of elastic MPs, and subscript a is adopted

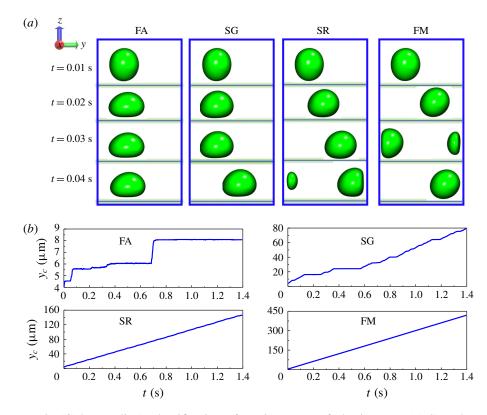


FIGURE 9. (Colour online) Identification of motion types of elastic MPs. (a) Snapshots for firm adhesion (FA), stop-and-go motion (SG), stable rolling (SR) and free motion (FM). (b) Corresponding trajectories of the four different types of motion for elastic MPs along the flow direction.

to distinguish it from margination probability. The formation of a biological bond between the ligand and the receptor is an indication of interaction between the MP and the substrate. Additionally, the adhesion probability of the four motion types of MPs on the substrate is defined as the number fraction of MPs with definite motion types. In the following, for simplicity, the type names of the MPs represent the corresponding adhesion probability. Figure 10 presents the adhesion probabilities for elastic MPs and the motion types. In figure 10(a), the adhesion strength is weak (Ad = 0.7). We find that when the MPs are stiff (low Ca), FM and SR dominate the motion of MPs compared to SG and FA; almost no MP has FA. But when the MPs become soft (increasing Ca), FM and SR decrease; and the FM can even vanish when Ca is large enough. When MPs are very soft (high Ca), SG and FA start to increase, and SG can exceed SR and FM. One thing that should be noted is that the sum of the adhesion probabilities of all four motion types should be equal to the total adhesion probability. The tendency is consistent with previous studies that deformability can promote the firm adhesion of particles on the substrate (Ndri et al. 2003; Khismatullin & Truskey 2005; Shen et al. 2018). However, when the adhesion strength increases (cf. figure 10b), the adhesion probabilities have the opposite trend compared to that under weak adhesion. FA and SG dominate the motion of MPs when MPs are stiff. When MPs become soft (increasing Ca), SG and FA start to decrease,

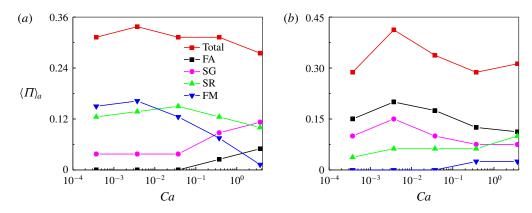


FIGURE 10. (Colour online) Adhesion probabilities for elastic MPs and corresponding adhesion probabilities of different motion types: (a) Ad = 0.7 and (b) Ad = 32.8.

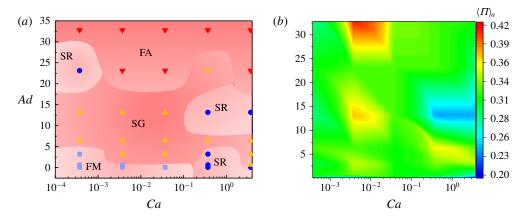


FIGURE 11. (Colour online) (a) Phase diagram for motion type of elastic MPs on Ca–Ad plane. (b) Adhesion probability contours of elastic MPs on Ca–Ad plane.

but SR and FM increase. When MPs are soft enough (high *Ca*), SR can outperform FA and SG. This results in the opposite conclusion that a stiff MP demonstrates superior adhesion compared to soft particles when adhesion strength is strong.

To have detailed motion type distributions with different adhesion strengths and stiffnesses, we give the phase diagram of motion types on the Ca-Ad plane in figure 11(a). The type is chosen as follows: for example, when Ca = 0.037 and Ad = 32.8, the adhesion probability of FA dominates compared to the other three motion types, and then we use FA to represent the motion type of MPs under the specific adhesion strength and stiffness. Comparing figure 11(a) with the margination probability contour under the adhesion effect (cf. figure 8), we find that the two regions favouring margination are just the FA and SG regions corresponding to the motion type phase diagram. This means that the adhesion-favouring region is also the margination-favouring region. Additionally, the adhesion probability contour is provided in figure 11(b). We find that in the regions where the margination probabilities are high, the adhesion probabilities are also high. Thus high margination

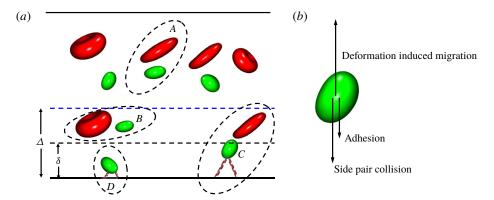


FIGURE 12. (Colour online) (a) Interaction modes of elastic MPs in blood flow. (b) Three mechanisms dominating the motion of elastic MPs near the wall of a channel.

should be a prerequisite for high adhesion, but the intrinsic relationship between margination and adhesion is not clear. We will discuss it in detail below.

4.4. Mechanism of localization of elastic MPs under adhesion

When the elastic MP is located in the blood flow, it can interact with other objects, such as RBCs, the wall of the channel and other MPs. Particularly, considering the adhesion effect, the elastic MPs can also interact with the wall through ligand-receptor binding. We give a simple schematic to show the interaction modes of an elastic MP with other objects in figure 12(a). Here, the interaction mode between MP and MP is negligible due to the low volume fraction (less than 1%). When the MP is located in the centre region of the channel, it can only interact with RBCs through hydrodynamic collision, which is denoted as interaction mode A in figure 12(a). We define a near-wall region Δ , in which the existence of the wall will influence the motion of objects within it. The thickness of Δ is approximately three times the radius of the object (Singh et al. 2014). If an MP enters the region Δ , it can experience deformation-induced migration besides a hydrodynamic collision with an RBC. We name this mode as B. Further moving towards the wall makes an elastic MP locate around the interface of the CFL (δ). An MP in this region has complicated interactions with its surroundings. It not only collides with an RBC and experiences deformation-induced migration, but also starts to interact with the wall through ligand-receptor binding. The interaction mode in this region is symbolized as C. After the MP moves into the CFL and adheres on the substrate, it experiences both adhesive interaction and deformation-induced migration. We call this interaction mode D. We focus on mode C and isolate it in figure 12(b). Here we believe that the motion of an elastic MP with mode C is complex but crucial to the margination and adhesion process. The region where this mode happens is located around the interface of the CFL and adhesion layer. If the MP moves away from the wall, it will not be counted as an MP having localization. While, when it moves towards the wall, it will be regarded as an MP owing to margination and adhesion. The moving direction is attributed to the competition among three mechanisms: (i) deformation-induced migration; (ii) adhesion effect; and (iii) near-wall hydrodynamic collision with an RBC. The deformation-induced migration makes an MP move away from the wall, and thus hampers localization. The adhesion effect plays a role through biological

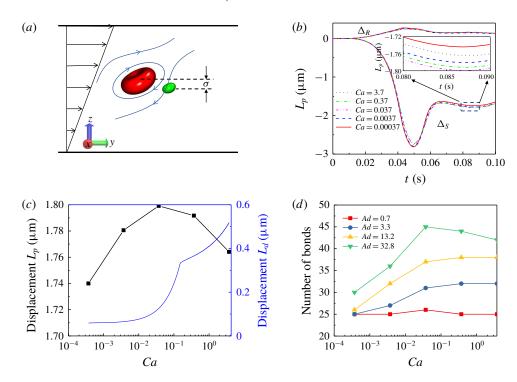


FIGURE 13. (Colour online) (a) Numerical experiment for pair collision between an RBC and an elastic MP. (b) Collision displacement of an RBC and an elastic MP with different stiffnesses. (c) Comparison of collision displacement and deformation-induced migration displacement of elastic MPs. (d) Number of biological bonds established when elastic MPs adhere on a substrate with different adhesion strengths against stiffness of elastic MP.

bond, and it facilitates localization. As for the near-wall hydrodynamic collision with an RBC, because there is no RBC within the CFL, then the collision should be a one-sided collision. The RBCs are always located on one side of the MP. Furthermore, it is confirmed that three-body and higher-order collision schemes can be negligible under the current circumstances (Ht = 30%) (Kumar & Graham 2012a; Rivera, Zhang & Graham 2016; Qi & Shaqfeh 2017). Therefore, only a side pair collision is considered here. According to the locations of the RBC and MP, the pair collision hinders the penetration of the MP into the centre of the channel, and thus promotes localization.

The side pair collision is first examined systematically for elastic MPs with different stiffnesses. Figure 13(a) gives the side pair collision illustration. In this numerical experiment, the channel and the flow condition are the same as in the above simulations for margination of elastic MPs. A single RBC and an elastic MP are placed in the centre of the channel to eliminate the wall effect. The centre distance between their initial positions in the height direction (z direction) is $\sigma = 2 \mu m$. During the simulation, the trajectories of the centres of the RBC and the MP are tracked. The displacement of the centres of the RBC and the MP in the z direction refers to the collision displacement. The evolution of collision displacements for the RBC (Δ_R) and the elastic MP (Δ_S) are presented in figure 13(b). As for the RBC, we find that the collision displacements are almost the same; and they are much smaller compared

to all of the elastic MPs. They have no dependence on the stiffness of MPs. This is attributed to the small size of an MP compared to the RBC. The trajectories of MPs with different stiffnesses have the same trend. The first approach between the RBC and the MP makes the MP abruptly migrate towards the wall. After collision ends, it can partially restore towards its initial position. It is located in a specific equilibrium position between the initial and maximum migration positions. We denote the distance between this equilibrium position and the initial position as the collision displacement, which is based on the definition in Loewenberg & Hinch (1997), Kumar & Graham (2011, 2012a,b) and Zhao & Shaqfeh (2013). From the zoom in figure 13(b), we can see that the difference of collision displacements among MPs with different stiffnesses is small. But this is an individual collision between an RBC and an MP. Repeated collisions between RBCs and MPs will distinguish the collision displacement with a large value for MPs with different stiffnesses. The result is shown in figure 13(c), L_p represents the collision displacement. We find that when Ca < 0.037, the collision displacement increases with the increment of Ca, while when Ca > 0.037, it decreases slightly with the increment of Ca. Hence, there is an optimal stiffness for the pair collision of an elastic MP and an RBC (results in the supporting information point out that this optimal Ca is a bit larger than 0.037).

As far as we know, this is the first time that a hydrodynamic collision between an RBC and an elastic MP has been presented. There are also a number of previous studies showing the pair collision between particles with either the same volume or the same shape (Kumar & Graham 2011, 2012b; Sinha & Graham 2016). The collision result can be explained as follows. Owing to the size difference between an RBC (diameter 8 µm) and an elastic MP (diameter 2 µm), the motion of the elastic MP is probably governed by the fluctuation of the flow field near the RBC induced by its deformation. The RBC should perform a tank-treading motion under shear flow, and the flow field around it is presented in figure 13(a). When Ca < 0.037, with the increment of Ca, it is easier for a soft MP to align itself with the flow field, thus the collision displacement increases. However, further increase of Ca makes the tank-treading motion of a soft MP become significant (Fedosov et al. 2010a). The tank-treading motion of a soft MP can also induce the fluctuation of flow around it, but with the opposite direction to the flow field induced by RBC motion. It acts as resistance to the alignment of the MP with the flow field. Therefore, further increase of Ca will lead to the decrease of the collision displacement of an MP.

When an elastic MP is placed in the flow, the shape cannot be analytically captured, especially for an MP with large deformation. Therefore, the deformation-induced migration, which is highly dependent on the shape of the MP, can hardly be determined. In the literature, numerical simulations are employed to study the deformation-induced migration of an elastic MP in a flow (Doddi & Bagchi 2008; Kaoui *et al.* 2008; Nix *et al.* 2014; Singh *et al.* 2014; Qi & Shaqfeh 2017). Here, an empirical relationship in Singh *et al.* (2014) is adopted, due to its systematics. In their study, the lateral migration velocity of the deformable capsule is a function of its stiffness (*Ca*) and distance away from the wall (*h*). A phenomenological formula for migration velocity is given as

$$\frac{V_d}{\dot{\gamma}a} = \begin{cases}
(0.65Ca + 0.021) \left(\frac{a}{h}\right)^2, & Ca \leqslant Ca_{cr}, \\
V_{cr}^* + 0.02(Ca - Ca_{cr})^{0.6} \left(\frac{a}{h}\right)^{1.35}, & Ca > Ca_{cr},
\end{cases}$$
(4.3)

where $V_{cr}^* = (V_d/\dot{\gamma}a)|_{Ca=Ca_{cr}}$. Their simulation results pointed out a power-law relation for the capsule velocity. There exists a critical stiffness, Ca_{cr} , of the capsule; here we choose it as $Ca_{cr} = 0.15$ according to the proposed regime in Singh *et al.* (2014). When $Ca \leq Ca_{cr}$, the migration velocity is linearly proportional to Ca and related to h^{-2} , while when $Ca > Ca_{cr}$, the velocity has 0.6 and -1.35 power scalings with Ca and h, respectively. On the basis of this relation, we set h=2 μ m, which corresponds to a position between the adhesion layer and the CFL, and then integrate (4.3) from t=0 to t=0.1. The deformation-induced migration displacement L_d against stiffness of the elastic MP is obtained and is shown in figure 13(c), denoted as a blue line.

To study the adhesion effect, we also conduct simulation experiments to investigate the adhesion behaviour of a single elastic MP on a substrate under shear flow. The flow and the channel size are the same as in the above margination study. The interaction between an elastic MP and the substrate is established by the biological bonds formed in the adhesion process, and the bond is modelled as a linear spring. The number of bonds can be used to quantify the adhesion effect. Figure 13(d) shows the relationship between the number of bonds and the stiffness of the elastic MP under different adhesion strengths. We find that the number of bonds increases with the increment of Ca when Ca is not large (Ca < 0.037). However, further increase of Ca does not significantly affect the number of bonds. When the adhesion strength is very strong (Ad = 32.8), the number of bonds may slightly decrease with increment of Ca.

The results given above demonstrate the strength of three mechanisms against the stiffness of MPs. They are combined to explain the margination results in figure 7(b). When the MP is relatively stiff (low Ca < 0.037), with the increment of Ca, the collision displacement increases, the adhesion effect increases, and the deformation-induced migration displacement remains almost unchanged. Two promoting factors of localization increase and one impeding factor remains unchanged. Thus, the margination probability increases with the increment of Ca. However, when Ca exceeds the critical value Ca = 0.037, the MP becomes relatively soft. With the increment of Ca, the collision displacement decreases, the adhesion effect stays almost unchanged, and the deformation-induced migration drastically increases. The impeding factor of localization dominates compared to the other two promoting factors. Hence, in this circumstance, the localization of the MP decreases with the increment of Ca.

Furthermore, the relationship between margination behaviour and adhesion strength is isolated for investigation. With the same Ca, the side pair collision displacements for MPs under different adhesion strengths should be the same, because the collision displacement is independent of the adhesion, while the deformation-induced migration displacement should be influenced by the adhesion strength. From (4.3), it seems that the deformation-induced migration velocity is only relevant to Ca. But this is not true. The root cause of deformation-induced migration is the deformation of the MP under shear flow. Here, considering the adhesion effect, the deformation of the MP is affected not only by Ca, but also by the adhesion strength Ad. Figure 14(a) presents the configurations of the MP with the same Ca = 0.037, but under different adhesion strengths. We find that, when the adhesion strength is weak (Ad = 0.07), the deformation of the MP is small. With the increment of adhesion strength (Ad = 0.7-13.2), the deformation becomes significant and increases, while further increase of Ad will not cause any further increment of MP deformation. This result reveals that the adhesion effect plays a role in the localization of MPs through influencing the deformation of the MP. Additionally, the relationship between

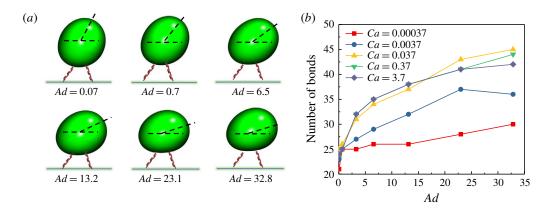


FIGURE 14. (Colour online) (a) Deformation of particles with Ca = 0.037 under different adhesion strengths. Dashed lines are used as a guide to show the deformation of particles. (b) Number of biological bonds established when elastic MPs adhere on a substrate against adhesion strengths for particles with different stiffnesses.

the number of bonds and the adhesion strength for MPs with different stiffnesses is displayed in figure 14(b). We find that, when the adhesion strength is small (Ad < 3.3), the number of bonds dramatically increases with the increment of Ad; while further increment of Ad also results in the increase of number of bonds, but with a slow growth rate.

Apart from the collision effect, the adhesion effect and deformation-induced migration are combined to reveal the underlying mechanism of margination probability against adhesion strength for MPs with different stiffnesses in figure 7(a). When Ad is small ($Ad \sim 0.7$), the deformation-induced migration displacements are almost the same, but the adhesion effect dramatically increases, and thus the margination probability grows rapidly with the increment of adhesion strength. When Ad becomes relatively large ($Ad \sim 0.7$ –13.2), the adhesion effect slowly increases, while the deformation of particles is significant, leading to large deformation-induced migration displacement. Therefore, in this regime, the margination probability decreases with the increment of adhesion strength. With the further increase of Ad, the deformation-induced migration displacements are almost constant, but adhesion effects still slowly increase. Hence, the margination probability should increase with the increment of adhesion strength in this regime.

5. Conclusion

We present numerical results on the localization of elastic MPs without and with effect of adhesion. Margination probability is adopted to quantify the localization of elastic MPs. Without adhesion effects, the margination probabilities of MPs decrease with the increment of Ca. This stiffness dependence of margination behaviour is found to rely on the interplay of collisions with RBCs and deformation-induced lateral migration of elastic MPs. We find that the evolution of margination can be split into two stages. The first stage corresponds to the development of the CFL. And in this stage, a soft MP marginates more readily than a stiff one. This is attributed to the exclusion of RBCs moving from the CFL to the centre of the channel. The volume exclusion effect is more significant for soft MPs than for stiff MPs, because

the deformation of soft MPs demonstrates stronger alignment with the flow direction. However, in the second stage, the CFL is fully formed and the flow is fully developed. The soft MPs in the near-wall region will experience deformation-induced migration due to the existence of the wall. This results in the low accumulation of soft MPs in the CFL. Thus, the margination probability decreases with the increment of Ca. After the MP becomes softer (high Ca), the deformation-induced lateral migration dominates the motion of MPs; therefore, the margination probabilities almost remain the same with the change of Ca.

Furthermore, localization of elastic MPs under the adhesion effect is studied. We obtain the margination probability contours by systematically varying the capillary number Ca and the adhesion number Ad. We find that there are two optimal regimes favouring high margination probability on the Ca-Ad plane. It is concluded that the existence of optimal regimes is induced by the interplay of MP deformability and adhesion. The underlying mechanism is explained as competition among three factors: (i) near-wall hydrodynamic collisions between RBCs and MPs; (ii) deformation-induced migration due to the existence of the wall; (iii) adhesive interaction between MPs and the substrate. For MPs with the same adhesion strengths Ad, when they are relatively stiff (low Ca = 0.00037-0.037), the collision displacements increase with the increment of Ca. At the same time, the adhesion effects increase. The deformation-induced migration displacements almost remain the same. Thus, the margination probability will increase with the increment of Ca. However, after Ca of MPs exceeds the critical value Ca = 0.037, the MPs become softer. With the increment of Ca, the collision displacements decrease and the adhesion effects have no obvious difference, while deformation-induced migration displacements dramatically increase. Hence, the margination probability decreases with the increment of Ca. Additionally, the dependence of the adhesion effect is investigated by fixing the stiffness of the MP. As the collision displacement only depends on the stiffness of the MP, we ignore its influence here. When Ad is small, the deformation-induced migration displacements are almost the same, while the adhesion effects increase quickly; then the margination probabilities dramatically increase with the increment of Ad. Furthermore, when Ad becomes relatively large, the adhesion effects slowly increase, while the deformation of the MPs is significant. Therefore, in this regime, the margination probabilities decrease with the increase of Ad. With the further increase of Ad, the deformation-induced migration displacements are almost the same. Although the growth rates are small, the adhesion effects continuously increase. Thus, the margination probabilities can slowly increase with the increment of Ad.

For computational studies of blood flow, there are still some limitations in the current numerical model. In normal human vasculature, the viscosity inside the RBC is 4–6 times larger than in the plasma outside the RBC. This viscosity contrast can affect the rheology of the RBC suspension. This is one of the reasons why our simulation results are not exactly the same as experimental results in the validation part. Besides, the blood vessel is usually tubular. Thus, the results obtained from the rectangular channel in our model may have some discrepancies with those in a tube. Tube flow deserves to be investigated in the future.

The findings in this work, especially the optimal regimes favouring localization, suggest that a softer MP or stronger adhesion is not always the best choice for the localization of MPs. This could offer further guidance to design efficient drug carriers in biomedical application, in which high localization is needed.

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Supplementary material

Supplementary material is available at https://doi.org/10.1017/jfm.2018.890.

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