FISCHER DECOMPOSITION AND CAUCHY–KOVALEVSKAYA EXTENSION IN FRACTIONAL CLIFFORD ANALYSIS: THE RIEMANN–LIOUVILLE CASE

N. VIEIRA

CIDMA – Center for Research and Development in Mathematics and Applications, Department of Mathematics, University of Aveiro, Campus Universitário de Santiago, 3810-193 Aveiro, Portugal (nloureirovieira@gmail.com)

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Abstract In this paper we present the basic tools of a fractional function theory in higher dimensions by means of a fractional correspondence to the Weyl relations via fractional Riemann–Liouville derivatives. A Fischer decomposition, Almansi decomposition, fractional Euler and Gamma operators, monogenic projection, and basic fractional homogeneous powers are constructed. Moreover, we establish the fractional Cauchy–Kovalevskaya extension (FCK extension) theorem for fractional monogenic functions defined on \mathbb{R}^d . Based on this extension principle, fractional Fueter polynomials, forming a basis of the space of fractional spherical monogenics, i.e. fractional homogeneous polynomials, are introduced. We study the connection between the FCK extension of functions of the form $\mathbf{x}P_l$ and the classical Gegenbauer polynomials. Finally, we present an example of an FCK extension.

Keywords: fractional monogenic polynomials; Fischer decomposition; Almansi decomposition; Cauchy–Kovalevskaya extension theorem; fractional Clifford analysis; fractional Dirac operator

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1. Introduction

In recent decades, interest in fractional calculus has increased substantially. This is due, on the one hand, to the fact that different problems can be considered in the framework of fractional derivatives like, for example, those in optics and quantum mechanics, and, on the other hand, to the fact that fractional calculus provides us with a new degree of freedom that can be used for more complete characterization of an object or as an additional encoding parameter.

The study of the fractional Dirac operator is motivated by its physical and geometrical interpretations. Physically, this fractional differential operator is related to some aspects of fractional quantum mechanics such as the derivation of the fractal Schrödinger-type wave equation, the resolution of the gauge hierarchy problem, and the study of supersymmetries. Geometrically, the classical part of this operator may be identified with the scalar curvature in Riemannian geometry.

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There are some disadvantages in the implementation of a fractional approach. For example, complicated problems arise during the mathematical manipulations due to the inexistence of a simple Leibnitz rule for the product. Restricting ourselves to the purposes of this work, the main drawback is that in spite of similarities in the formulation of some fractional results with the corresponding classical ones, the proofs are very different in nature because we cannot apply polar or spherical coordinates when we are dealing with fractional derivatives. An explicit and complete derivation of fractional operators in polar or spherical coordinates is still an open task, despite several attempts in the past (see [18, 24, 29, 31]). A possible route to overcoming this problem is to adapt the approach presented for the discrete case [10].

Clifford analysis is a generalization of classical complex analysis in the plane to the case of an arbitrary dimension $d \in \mathbb{Z}$ (in the case of negative dimensions, one is dealing with the so-called super Clifford analysis). At the heart of the theory lies the Dirac operator D on \mathbb{R}^d , a conformally invariant first-order differential operator that plays the same role in classical Clifford analysis as the Cauchy–Riemann operator ∂_z does in complex analysis. Over the last decades Sommen and his collaborators developed a method for establishing a higher dimension function theory based on the so-called Weyl relations [7,11,14]. In more restrictive settings it is nowadays called the Howe dual pair technique (see [27]). There are two focal points: the construction of an operator algebra (classically $\mathfrak{osp}(1|2)$), and the establishment of a Fischer decomposition.

The traditional Fischer decomposition in harmonic analysis yields an orthogonal decomposition of the space of homogeneous polynomials of given homogeneity in terms of spaces of harmonic homogeneous polynomials. In classical continuous Clifford analysis one obtains a refinement yielding an orthogonal decomposition with respect to the so-called Fischer inner product of homogeneous polynomials in terms of spaces of monogenic polynomials, i.e. null solutions of the Dirac operator (see [14]). Generalizations of the Fischer decomposition in other frameworks can be found, for example, in [2,7,11,15,21,25,27].

Another well-known result in Clifford analysis is the Cauchy–Kovalevskaya extension theorem, which we will denote simply as the CK extension (see [6,23]). It corresponds to a direct generalization to higher dimension of the complex plane case, and can be found in [14]. Other generalizations of the CK extension can be found, for instance, in [5,9,10,12,13,26,32].

The aim of this paper is to present an analogue of the results in [21,32] for a fractional Dirac operator defined via fractional Riemann–Liouville derivatives. The author would like to reinforce that this is not a direct generalization because, contrarily to what happens in the classical and Caputo cases, the constant functions are not null solutions of the Euclidian/fractional Dirac operator.

The structure of the paper is as follows. In the preliminaries we recall some basic facts about Clifford analysis and fractional calculus. In $\S 3$ we introduce the corresponding Weyl relations for this fractional setting and we introduce the notion of a fractional homogeneous polynomial. Here, we also present the fractional correspondence to the Fischer decomposition and its extension to a fractional Almansi decomposition. At the end

of this section we construct the projection of a given fractional homogeneous polynomial into the space of fractional homogeneous monogenic polynomials. We also calculate the dimension of the space of fractional homogeneous monogenic polynomials. In \S 4 we establish a fractional Cauchy–Kovalevskaya extension (FCK extension) theorem for fractional monogenic functions. Based on this extension principle, we introduce fractional Fueter polynomials, which form a basis of the space of fractional spherical monogenics, i.e. of fractional homogeneous monogenic polynomials. Moreover, we go into detail about the connection between the FCK extension of functions of the form xP_l and the classical Gegenbauer polynomials. We end this paper with an example of an FCK extension.

2. Preliminaries

It is well known that the treatment of the two-dimensional vector space \mathbb{R}^2 in terms of complex numbers has the advantage of providing an additional multiplication operator on \mathbb{R}^2 . Appropriate higher-dimensional associative analogues of the complex numbers are real Clifford algebras. For details about Clifford algebras and basic concepts of its associated function theory, we refer the interested reader to, for example, [3,14,19].

Let $\{e_1, \ldots, e_d\}$ be the standard basis of the Euclidian vector space in \mathbb{R}^d . The associated Clifford algebra $\mathbb{R}_{0,d}$ is the free algebra generated by \mathbb{R}^d modulo $x^2 = -\|x\|^2 e_0$, where $x \in \mathbb{R}^d$ and e_0 is the neutral element with respect to the multiplication operation in the Clifford algebra $\mathbb{R}_{0,d}$. The defining relation induces the multiplication rule $e_i e_j + e_j e_i = -2\delta_{i,j}$, where $\delta_{i,j}$ is the Kronecker delta. In particular, $e_i^2 = -1$ for all $i = 1, \ldots, d$. The standard basis vectors thus operate as imaginary units.

A vector space basis for $\mathbb{R}_{0,d}$ is given by the set $\{e_A : A \subseteq \{1,\ldots,d\}\}$ with $e_A = e_{l_1}e_{l_2}\cdots e_{l_r}$, where $1\leqslant l_1<\cdots< l_r\leqslant d$, $e_\emptyset:=e_0:=1$. Each $a\in\mathbb{R}_{0,d}$ can be written in the form $a=\sum_A a_A e_A$, with $a_A\in\mathbb{R}$. The conjugation in the Clifford algebra $\mathbb{R}_{0,d}$ is defined by $\bar{a}=\sum_A a_A \bar{e}_A$, where $\bar{e}_A=\bar{e}_{l_r}\bar{e}_{l_{r-1}}\cdots\bar{e}_{l_1}$, and $\bar{e}_j=-e_j$ for $j=1,\ldots,d$, $\bar{e}_0=e_0=1$. An important property of the Clifford algebra $\mathbb{R}_{0,d}$ is that each non-zero vector $a\in\mathbb{R}_1^d$ has a multiplicative inverse given by $\bar{a}/\|a\|^2$. An important subspace of the real Clifford algebra $\mathbb{R}_{0,d}$ is the so-called space of paravectors $\mathbb{R}_1^d=\mathbb{R}\oplus\mathbb{R}^d$, that being the sum of scalars and vectors. An element $\underline{a}=(a_0,a_1,\ldots,a_d)$ of \mathbb{R}^d will be identified by $\underline{a}=a_0+a$, with $a=\sum_{i=1}^d e_i a_i$.

We now introduce the complexified Clifford algebra \mathbb{C}_d as the tensor product

$$\mathbb{C} \otimes \mathbb{R}_{0,d} = \left\{ w = \sum_{A} w_{A} e_{A}, \ w_{A} \in \mathbb{C}, \ A \subset M \right\},\,$$

where the imaginary unit i of $\mathbb C$ commutes with the basis elements, i.e. $\mathbf ie_j=e_j$ if or all $j=1,\ldots,d$. To avoid ambiguities with the Clifford conjugation, we denote the complex conjugation mapping a complex scalar $w_A=a_A+\mathbf ib_A$, with real components a_A and b_A , onto $\bar w_A=a_A-\mathbf ib_A$ by \sharp . The complex conjugation leaves the elements e_j invariant, i.e. $e_j^{\sharp}=e_j$ for all $j=1,\ldots,d$. We also have a pseudo-norm on $\mathbb C$, namely, $|w|:=\sum_A|w_A|$, where $w=\sum_Aw_Ae_A$, as usual. Notice also that for $a,b\in\mathbb C_d$ we only have $|ab|\leqslant 2^d|a|\,|b|$. The other norm criteria are fulfilled.

Clifford analysis can be regarded as a higher-dimensional generalization of complex function theory in the sense of the Riemann approach. A \mathbb{C}_d -valued function f over $\Omega \subset \mathbb{R}^d_1$ has representation $f = \sum_A e_A f_A$, with components $f_A \colon \Omega \to \mathbb{C}$. Properties such as continuity will be understood component-wise. Next, we recall the Euclidean Dirac operator $D = \sum_{j=1}^d e_j \partial_{x_j}$, which factorizes the d-dimensional Euclidean Laplacian, i.e.

$$D^2 = -\Delta = -\sum_{i=1}^d \partial x_j^2.$$

A \mathbb{C}_d -valued function f is called *left monogenic* if it satisfies $\mathrm{D}u = 0$ on Ω (respectively, right monogenic if it satisfies $u\mathrm{D} = 0$ on Ω).

The most widely known definition of the fractional derivative is the so-called Riemann–Liouville definition. This definition appears as a result of the unification of the notions of integer-order integration and differentiation, and is expressed as follows:

$${}_{a}D_{t}^{p}f(t) = \frac{1}{\Gamma(m+1-p)} \left(\frac{\mathrm{d}}{\mathrm{d}t}\right)^{m+1} \int_{a}^{t} (t-\tau)^{m-p} f(\tau) \,\mathrm{d}\tau, \quad m \leqslant p < m+1.$$
 (2.1)

The previous definition requires that the function f(t) must be m+1 times continuously differentiable, which corresponds, in some sense, to a narrow class of functions; however, this class of functions is very important for applications because the character of the majority of dynamical processes is smooth enough and does not allow discontinuities. Understanding this fact is important for proper use of the methods of fractional calculus in applications, especially because of the fact that the Riemann–Liouville definition provides an excellent opportunity to weaken the conditions of the function f(t); then integral (2.1) exists for t > a and can be differentiated m+1 times. The weak condition on the function f(t) in (2.1) is necessary, for example, for obtaining the solution of the Abel equation. For more details about fractional calculus and applications we refer the reader to [22,28,30].

In [16] the fractional derivative (2.1) was successfully applied in the definition of the fractional equivalent of the Dirac operator in the context of Clifford analysis. In fact, the fractional Dirac operator corresponds to

$$D^{\alpha} = \sum_{j=1}^{d} e_{j} D_{j}^{\alpha} = \sum_{j=1}^{d} e_{j} (D_{j} + Y_{j}),$$

where D_j is the classical derivative with respect to x_j , and $Y_j = (1 - \alpha)/(\xi_j - x_j)$, with $0 < \alpha < 1$, and $\xi = (\xi_1, \dots, \xi_d)$ is the observer time vector. A \mathbb{C}_n -valued function f is called fractional left monogenic if it satisfies $D^{\alpha}u = 0$ on Ω (respectively, fractional right monogenic if it satisfies $uD^{\alpha} = 0$ on Ω). We observe that due to the definition of the fractional Dirac operator we have that

$$D^{\alpha}\left(\prod_{i=1}^{d} (\xi_i - x_i)^{1-\alpha}\right) = 0, \tag{2.2}$$

i.e. $\prod_{i=1}^{d} (\xi_i - x_i)^{1-\alpha}$ is a fractional monogenic function.

Remark 2.1. In (2.2) the fractional power $(\xi_i - x_i)^{1-\alpha}$ should be understood in the following way:

$$(\xi_j - x_j)^{1-\alpha} = \begin{cases} \exp((1-\alpha)\ln|\xi_j - x_j|), & \xi_j > x_j, \\ 0, & \xi_j = x_j, \\ \exp((1-\alpha)\ln|\xi_j - x_j| + i\alpha\pi), & \xi_j < x_j, \end{cases}$$

with $0 < \alpha < 1$ and j = 0, 1, ..., d.

Hereafter we will consider paravectors of the form $\underline{x}^{\alpha} = x_0 + x$, where $x_j = \alpha(\xi_j - x_j)$.

Remark 2.2. During the paper we will restrict ourselves to the case in which the fractional parameter α belongs to the interval]0,1[. Cases in which α is outside this range can be reduced to the considered one. In fact, for $\alpha \in \mathbb{R}$ we have that $\alpha = [\alpha] + \tilde{\alpha}$, with $[\alpha]$ the integer part of α and $\tilde{\alpha} \in]0,1[$.

3. Weyl relations and Fractional Fischer decomposition

The aim of this section is to provide the basic tools for a function theory for the fractional Dirac operator defined via fractional Riemann–Liouville derivatives.

3.1. Fractional Weyl relations

Now we introduce the fractional correspondence of the classical Euler and Gamma operators. Moreover, we will show that the two natural operators D^{α} and \boldsymbol{x} , considered as odd elements, generate a finite-dimensional Lie superalgebra in the algebra of endomorphisms generated by the partial fractional Riemann-Liouville derivatives, the basic vector variables \boldsymbol{x}_j (seen as multiplication operators), and the basis of the Clifford algebra \boldsymbol{e}_j . Before we proceed, we recall the definition of a Lie superalgebra (for more details about Lie superalgebras and their connections with Clifford analysis, see [4, 20]).

Definition 3.1. A Lie superalgebra \mathfrak{g} (over \mathbb{R} or \mathbb{C}) is a \mathbb{Z}_2 -graded vector space, i.e., a direct sum of two vector spaces $\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$ equipped with a graded bracket $[[\cdot, \cdot]]$, satisfying

- the \mathbb{Z}_2 -grading: $[[a_i, a_j]] \in \mathfrak{g}_{i+j \mod 2}$, with $a_i \in \mathfrak{g}_i$ and $a_j \in \mathfrak{g}_j$;
- the graded antisymmetry: $[[a_i, a_j]] = (-1)^{ij}[[a_j, a_i]]$, with $a_i \in \mathfrak{g}_i$ and $a_j \in \mathfrak{g}_j$;
- the generalized Jacobi identity:

$$(-1)^{ik}[[a_i,[[a_j,a_k]]]] + (-1)^{ji}[[a_j,[[a_k,a_i]]]] + (-1)^{kj}[[a_k,[[a_i,a_j]]]] = 0,$$

with $a_i \in \mathfrak{g}_i$, $a_i \in \mathfrak{g}_i$, $a_k \in \mathfrak{g}_k$.

In order to obtain our results, we will use a standard technique in higher dimensions, namely, we study the commutator and the anti-commutator between x and D^{α} . We start by proposing the following fractional Weyl relations:

$$[D_i^{\alpha}, \boldsymbol{x}_i] = D_i^{\alpha} \boldsymbol{x}_i - \boldsymbol{x}_i D_i^{\alpha} = -\alpha, \tag{3.1}$$

with $i = 1, ..., d, 0 < \alpha < 1$. This leads to the following relations for \boldsymbol{x} and D^{α} :

$$\{D^{\alpha}, \boldsymbol{x}\} = D^{\alpha}\boldsymbol{x} + \boldsymbol{x}D^{\alpha} = -2\mathbb{E}^{\alpha} + \alpha d, \tag{3.2}$$

$$[\mathbf{x}, D^{\alpha}] = \mathbf{x}D^{\alpha} - D^{\alpha}\mathbf{x} = -2\Gamma^{\alpha} - \alpha d, \tag{3.3}$$

where \mathbb{E}^{α} , Γ^{α} are, respectively, the fractional Euler and Gamma operators and are expressed as

$$\mathbb{E}^{\alpha} = \sum_{i=1}^{d} \boldsymbol{x}_{i} \mathcal{D}_{j}^{\alpha}, \qquad \Gamma^{\alpha} = \sum_{i < j} \boldsymbol{e}_{i} \boldsymbol{e}_{j} (\boldsymbol{x}_{i} \mathcal{D}_{j}^{\alpha} - \mathcal{D}_{j}^{\alpha} \boldsymbol{x}_{i}). \tag{3.4}$$

From (3.4) we derive, via straightforward calculations, the following relations:

$$\mathbb{E}^{\alpha} + \Gamma^{\alpha} = -\boldsymbol{x}D^{\alpha}, \qquad [\mathbb{E}^{\alpha}, \Gamma^{\alpha}] = 0, \qquad [\boldsymbol{x}, \mathbb{E}^{\alpha}] = \alpha \boldsymbol{x},
[D^{\alpha}, \mathbb{E}^{\alpha}] = -\alpha D^{\alpha}, \qquad \{\boldsymbol{x}, \boldsymbol{x}\} = -2|\boldsymbol{x}|^{2}, \qquad \{D^{\alpha}, D^{\alpha}\} = 2\Delta^{2\alpha},
[\boldsymbol{x}, |\boldsymbol{x}|^{2}] = 0, \qquad [\boldsymbol{x}, \Delta^{2\alpha}] = 2\alpha D^{\alpha}, \qquad [D^{\alpha}, |\boldsymbol{x}|^{2}] = -2\alpha \boldsymbol{x},
[D^{\alpha}, \Delta^{2\alpha}] = 0, \qquad [\mathbb{E}^{\alpha}, \Delta^{2\alpha}] = 2\alpha\Delta^{2\alpha}, \qquad [\mathbb{E}^{\alpha}, |\boldsymbol{x}|^{2}] = -2\alpha|\boldsymbol{x}|^{2},
[|\boldsymbol{x}|^{2}, \Delta^{2\alpha}] = 4\alpha \left(\mathbb{E}^{\alpha} - \frac{\alpha d}{2}\right), \qquad (3.5)$$

where $\Delta^{2\alpha} = -D^{\alpha}D^{\alpha}$. Relations (3.5) show that we have a finite-dimensional Lie superalgebra, in the sense of Definition 3.1, generated by \boldsymbol{x} and D^{α} , isomorphic to $\mathfrak{osp}(1|2)$. At the end of this section we give a brief description (with references) of the $\mathfrak{osp}(1|2)$ algebra and its realizations. The normalization

$$H^{\alpha} = \frac{1}{2} \left(\mathbb{E}^{\alpha} - \frac{\alpha d}{2} \right),$$

$$(E^{\alpha})^{-} = \frac{-\alpha}{2} |\boldsymbol{x}|^{2}, \qquad (E^{\alpha})^{+} = \frac{\alpha}{2} \Delta^{2\alpha}, \qquad (F^{\alpha})^{-} = \frac{-\mathrm{i}\alpha}{2\sqrt{2}} \boldsymbol{x}, \qquad (F^{\alpha})^{+} = \frac{-\mathrm{i}\alpha}{2\sqrt{2}} \mathrm{D}^{\alpha},$$

leads to the standard commutation relations for $\mathfrak{osp}(1|2)$ (see [17]):

$$\begin{split} [H^\alpha,(E^\alpha)^\pm] &= \pm \alpha (E^\alpha)^\pm, \qquad [(E^\alpha)^+,(E^\alpha)^-] = -2\alpha^3 H^\alpha, \\ [H^\alpha,(F^\alpha)^\pm] &= \pm \frac{\alpha}{2} (F^\alpha)^\pm, \qquad \{(F^\alpha)^+,(F^\alpha)^-\} = \frac{\alpha^2}{2} H^\alpha, \\ [(E^\alpha)^\pm,(F^\alpha)^\mp] &= -\alpha^2 (F^\alpha)^\pm, \qquad \{(F^\alpha)^\pm,(F^\alpha)^\pm\} = \pm \frac{\alpha}{2} (E^\alpha)^\pm. \end{split}$$

We now introduce the definition of fractional homogeneity of a polynomial by means of the fractional Euler operator.

Definition 3.2. A polynomial P_l is called fractional homogeneous of degree $l \in \mathbb{N}_0$ if and only if $\mathbb{E}^{\alpha} P_l = -\alpha l P_l$.

We observe that from the previous definition the basic fractional homogeneous powers are given by $\prod_{j=1}^{d} \boldsymbol{x}_{j}^{\beta_{j}}$, with $l = |\beta| = \beta_{1} + \cdots + \beta_{d}$. In combination with the third relation in (3.5),

$$[\boldsymbol{x}, \mathbb{E}^{\alpha}] = \alpha \boldsymbol{x},$$

this definition also implies that:

- the multiplication of a fractional homogeneous polynomial of degree l by x will result in a fractional homogeneous polynomial of degree l+1, and thus may be seen as a raising operator;
- for a fractional homogeneous polynomial P_l of degree l, $D^{\alpha}P_l$ is a fractional homogeneous polynomial of degree l-1;
- the fractional Weyl relations (3.1) will now enable us to construct fractional homogeneous polynomials recursively.

The variables x_j , x_j^k are the basic fractional homogeneous polynomials of degree k. In the following result their fundamental properties are listed.

Theorem 3.3. For all $k \in \mathbb{N}$ and i, j = 1, ..., d we have

$$D_{j}^{\alpha} \boldsymbol{x}_{j}^{k} = -k \boldsymbol{x}_{j}^{k-1},
D_{i}^{\alpha} \boldsymbol{x}_{j}^{k} = 0, \qquad i \neq j,
D_{j}^{\alpha} \boldsymbol{x}_{j}^{k_{1}} \boldsymbol{x}_{i}^{k_{2}} = -k_{1} \boldsymbol{x}_{j}^{k_{1}-1} \boldsymbol{x}_{i}^{k_{2}}, \quad i \neq j.$$
(3.6)

Moreover, for any two multi-index $\gamma = (\gamma_1, \dots, \gamma_d)$ and $\beta = (\beta_1, \dots, \beta_d)$ with $|\gamma| = |\beta|$, it holds that

$$\mathrm{D}_{1}^{\gamma_{1}}\cdots\mathrm{D}_{1}^{\gamma_{d}}(\boldsymbol{x}_{1}^{\beta_{1}}\cdots\boldsymbol{x}_{d}^{\beta_{d}})\prod_{j=1}^{d}\boldsymbol{x}_{j}^{1-\alpha}=\begin{cases} (-1)^{\gamma!}\gamma! & \text{if } \gamma=\beta,\\ 0 & \text{if } \gamma\neq\beta, \end{cases}$$

where we have put $\gamma! = \gamma_1! \cdots \gamma_d!$.

The proof of this result is immediate and we therefore omit it from the text. Furthermore, from the previous theorem we conclude that a closed form for the fractional homogeneous polynomials is given by

$$(e_j x_j)^{2n+1} = (-1)^n e_j(x_j)^{2n+1}, \qquad (e_j x_j)^{2n} = (-1)^n (x_j)^{2n}$$
 (3.7)

for $n = 1, 2, \ldots$ and $j = 1, \ldots, d$. Moreover, from Theorem 3.3 we have the equalities

$$\mathbf{D}^{\alpha}\bigg(\prod_{j=1}^{d}\boldsymbol{x}_{j}^{1-\alpha}\bigg)=0, \qquad \mathbb{E}^{\alpha}\bigg(\prod_{j=1}^{d}\boldsymbol{x}_{j}^{1-\alpha}\bigg)=0, \qquad \mathbb{E}^{\alpha}\bigg(\boldsymbol{x}^{\beta}\prod_{j=1}^{d}\boldsymbol{x}_{j}^{1-\alpha}\bigg)=-|\beta|\boldsymbol{x}^{\beta}\prod_{j=1}^{d}\boldsymbol{x}_{j}^{1-\alpha},$$

and therefore in the fractional Fischer decomposition that we will present in the next section we will have that

$$P_0 = \operatorname{span} \left\{ \prod_{j=1}^d oldsymbol{x}_j^{1-lpha}
ight\} \quad ext{and} \quad P_l = \operatorname{span} \left\{ oldsymbol{x}_j^{eta} \prod_{j=1}^d oldsymbol{x}_j^{1-lpha}, \,\, |eta| = l
ight\},$$

where $\beta = (\beta_1, \dots, \beta_d)$ with $|\beta| = \beta_1 + \dots + \beta_d$. Furthermore, we have the following remark.

Remark 3.4. We would like to point out the main difference between this approach and the correspondent one presented in previous work (even when considering a fractional Dirac operator defined via fractional Caputo derivatives): due to the fact that $D^{\alpha}c \neq 0$, with c a constant and D^{α} the fractional Dirac operator defined via Riemann–Liouville derivatives, we cannot assume that $P_0 = \text{span}\{1\}$.

3.2. Fractional Fischer decomposition

A fractional Fischer inner product of two fractional homogeneous polynomials P and Q has the form

$$\langle P(\boldsymbol{x}), Q(\boldsymbol{x}) \rangle = \operatorname{Sc}[\overline{P(\partial_{\boldsymbol{x}})}Q(\boldsymbol{x})],$$
 (3.8)

where $\partial_{\boldsymbol{x}}$ represents D_j^{α} , and $P(\partial_{\boldsymbol{x}})$ is a differential operator obtained by replacing in the polynomial P each variable \boldsymbol{x}_j by the corresponding fractional derivative, i.e. $D_j + Y_j$. From (3.8) we have that for any polynomial P_{l-1} of homogeneity l-1 and any polynomial Q_l of homogeneity l,

$$\langle \boldsymbol{x} P_{l-1}, Q_l \rangle = \langle P_{l-1}, D^{\alpha} Q_l \rangle.$$
 (3.9)

This fact allows us to prove the following result.

Theorem 3.5. For each $l \in \mathbb{N}_0$ we have $\Pi_l = \mathcal{M}_l + \boldsymbol{x}\Pi_{l-1}$, where Π_l denotes the space of fractional homogeneous polynomials of degree l, and \mathcal{M}_l denotes the space of fractional monogenic homogeneous polynomials of degree l. Moreover, the subspaces \mathcal{M}_k and $\boldsymbol{x}\Pi_{l-1}$ are orthogonal with respect to the Fischer inner product (3.8).

Proof. Since $\Pi_l = \boldsymbol{x}\Pi_{l-1} + (\boldsymbol{x}\Pi_{l-1})^{\perp}$, it suffices to prove that $(\boldsymbol{x}\Pi_{l-1})^{\perp} = \mathcal{M}_{l-1}$. To this end, assume that for some $P_l \in \Pi_l$ we have $\langle \boldsymbol{x}P_{l-1}, P_l \rangle = 0$ for all $P_{l-1} \in \Pi_{l-1}$. From (3.9) we then have that $\langle P_{l-1}, D^{\alpha}P_l \rangle = 0$ for all $P_{l-1} \in \Pi_{l-1}$. As $D^{\alpha}P_l \in \Pi_{l-1}$, we obtain that $D^{\alpha}P_l = 0$, or that $P_l \in \mathcal{M}_l$. This means that $(\boldsymbol{x}\Pi_{l-1})^{\perp} \subset \mathcal{M}_{l-1}$. Conversely, take $P_l \in \mathcal{M}_l$. Then we have, for any $P_{l-1} \in \Pi_{l-1}$, that

$$\langle \boldsymbol{x} P_{l-1}, P_l \rangle = \langle P_{l-1}, D^{\alpha} P_l \rangle = \langle P_{l-1}, 0 \rangle = 0,$$
 (3.10)

from which it follows that $\mathcal{M}_{l-1} \subset (\boldsymbol{x}\Pi_{l-1})^{\perp}$, and therefore $\mathcal{M}_{l-1} = (\boldsymbol{x}\Pi_{l-1})^{\perp}$.

As a result we obtain the fractional Fischer decomposition with respect to the fractional Dirac operator D^{α} .

Theorem 3.6. Let P_l be a fractional homogeneous polynomial of degree l. Then

$$P_l = M_l + x M_{l-1} + x^2 M_{l-2} + \dots + x^l M_0, \tag{3.11}$$

where each M_j denotes the fractional homogeneous monogenic polynomial of degree j. More specifically,

$$M_0 = P_0$$
 and $M_l = \{u \in P_l : D^{\alpha}u = 0\}.$

The spaces represented in (3.11) are orthogonal to each other with respect to the Fischer inner product (3.8). This a consequence of the construction of the fractional Euler operator \mathbb{E}^{α} , and in particular of (3.2) and (3.3). Moreover, the space $\mathcal{P}(S)$ of all Clifford-valued polynomials decomposes in a multiplicity free by means of our fractional Weyl relations, and the decomposition has the form of an infinite triangle

While in the classic case all the summands in the same row are isomorphic to $\operatorname{Pin}(d)$ modules, and each row is an irreducible module for the Howe dual pair $\operatorname{Pin}(d) \times \mathfrak{osp}(1|2)$ (see [8] for more details), the same cannot be said in the fractional case yet. The reason is
that while the classical Laplacian and the Fischer dual are invariant under O(d) ($\operatorname{Pin}(d)$ is the double cover of O(d)), we can easily show that this is not true in the fractional
case.

Nevertheless, we have that all the summands in the same row are modules. The author's conjecture is that they can be invariant under a certain 'fractional' Pin group that does not coincide with the classical one; this subject will be studied in forthcoming work.

The Dirac operator shifts all spaces in the same row to the left, the multiplication by \boldsymbol{x} shifts them to the right, and both of these actions are isomorphisms of modules. Moreover, any spinor-valued polynomial can be written (in a unique way) as a sum of monogenic polynomials and a product of powers of \boldsymbol{x} with other monogenic polynomials.

From Theorem 3.6 we have the following direct extension to the fractional case of the Almansi decomposition.

Theorem 3.7. For any fractional polyharmonic polynomial P_l of degree $l \in \mathbb{N}_0$ in a star-like domain D in \mathbb{R}^d with respect to 0, i.e. $\Delta^{2\alpha}P_l = 0$, there exist uniquely fractional harmonic functions $P_0, P_1, \ldots, P_{l-1}$ such that

$$P_l = P_0 + |\mathbf{x}|^2 P_1 + \dots + |\mathbf{x}|^{2(l-1)} P_{l-1} \quad \forall \mathbf{x} \in D.$$

3.3. Explicit formulae

Here we obtain an explicit formula for the projection $\pi_{\mathcal{M}}(P_l)$ of a given fractional homogeneous polynomial P_l into the space of fractional homogeneous monogenic polynomials. We start with the following auxiliary result.

Theorem 3.8. For any fractional homogeneous polynomial P_l and any positive integer s, we have

$$D^{\alpha} \mathbf{x}^s P_l = g_{s,l} \mathbf{x}^{s-1} P_l + (-1)^s \mathbf{x}^s D^{\alpha} P_l,$$

where $g_{2k,l} = 2k\alpha$ and $g_{2k+1,l} = 2(\alpha k + \alpha l) + \alpha d$.

Proof. The proof follows, by induction and straightforward calculations, from the commutation between D^{α} and x^{s} using the relations

$$D^{\alpha} x = -2\mathbb{E}^{\alpha} + \alpha d - xD^{\alpha}$$
, $\mathbb{E}^{\alpha} x = x\mathbb{E}^{\alpha} - \alpha x$.

Let us now compute an explicit form of the projection $\pi_{\mathcal{M}}(P_l)$.

Theorem 3.9. Consider the constants $c_{j,l}$ defined by

$$c_{0,l} = 1,$$
 $c_{j,l} = \frac{(-1)^j}{(2[j/2])!! \prod_{i=0}^{[j/2]} g_{2i+1,l-(2i+1)}},$

where j = 1, ..., l and $[\cdot]$ represents the integer part. Then the map $\pi_{\mathcal{M}}$ given by

$$\pi_{\mathcal{M}}(P_l) := P_l + c_{1,l} \mathbf{x} D^{\alpha} P_l + c_{2,l} \mathbf{x}^2 (D^{\alpha})^2 P_l + \dots + c_{l,l} \mathbf{x}^l (D^{\alpha})^l P_l$$

is the projection of the fractional homogeneous polynomial P_l into the space of fractional homogeneous monogenic polynomials.

Proof. Let us consider the linear combination

$$r = a_0 P_l + a_1 \mathbf{x} D^{\alpha} P_l + a_2 \mathbf{x}^2 (D^{\alpha})^2 P_l + \dots + a_k \mathbf{x}^l (D^{\alpha})^l P_l$$

with $a_0 = 1$. If there are constants a_j , j = 1, ..., l, such that $r \in \mathcal{M}_l$, then r is equal to $\pi_{\mathcal{M}}(P_l)$. Indeed, we know that $P_l = \mathcal{M}_l \oplus \boldsymbol{x} P_{l-1}$ and

$$r = P_l + Q_{l-1}$$
 with $Q_{l-1} = \sum_{i=1}^{l} a_i \mathbf{x}^i (D^{\alpha})^i P_l$.

Applying Theorem 3.8, we get

$$0 = D^{\alpha}(\pi_{\mathcal{M}}(P_{l}))$$

$$= D^{\alpha}P_{l} + a_{1}D^{\alpha}\mathbf{x}D^{\alpha}P_{l} + a_{2}D^{\alpha}\mathbf{x}^{2}(D^{\alpha})^{2}P_{l} + \dots + a_{l}D^{\alpha}\mathbf{x}^{l}(D^{\alpha})^{l}P_{l}$$

$$= (1 + a_{1}g_{1,l-1})D^{\alpha}P_{l} + (-a_{1} + a_{2}g_{2,l-2})\mathbf{x}(D^{\alpha})^{2}P_{l} + (a_{2} + a_{3}g_{3,l-3})\mathbf{x}^{2}(D^{\alpha})^{3}P_{l}$$

$$+ \dots + ((-1)^{l-1}a_{l-1} + a_{l}g_{1,0})\mathbf{x}^{l-1}(D^{\alpha})^{l}P_{l}.$$

Hence, if the relation $(-1)^{j-1}a_{j-1} + a_i g_{j,l-j} = 0$ holds for each j = 1, ..., l, then the function r is fractional monogenic. By induction we get

$$a_j = \frac{(-1)^j}{(2[j/2])!! \prod_{i=0}^{[j/2]} g_{2i+1,l-(2i+1)}}.$$

Theorem 3.10. Each polynomial P_l can be written in a unique way as

$$P_l = \sum_{j=0}^{l} \boldsymbol{x}^j M_{l-j}(P_l),$$

where

$$M_{l-j}(P_l) = c'_j \sum_{n=0}^{j} c_{j,l-n} \boldsymbol{x}^n (D^{\alpha})^n (D^{\alpha})^{l-j} P_l, \quad j = 0, \dots, l,$$

and the coefficients c'_{i} are defined by

$$c'_{j} = \frac{(-1)^{j}}{(2[j/2])!! \prod_{i=0}^{[j/2]} g_{2i+1,l-(2i+1)}}.$$

Proof. We know that for any P_l there is a unique decomposition

$$P_l = x^l M_0 + x^{l-1} M_1 + \dots + x M_{l-1} + M_l,$$

where $M_{l-j} \in \mathcal{M}_{l-j}$ with j = 0, ..., l. To compute a component M_{l-j} explicitly, we apply $(D^{\alpha})^j$ to both sides of the previous equality:

$$(D^{\alpha})^{j} P_{l} = (D^{\alpha})^{j} \boldsymbol{x}^{l} M_{0} + (D^{\alpha})^{j} \boldsymbol{x}^{l-1} M_{1} + \dots + (D^{\alpha})^{j} \boldsymbol{x}^{j+1} M_{l-j-1} + (D^{\alpha})^{j} \boldsymbol{x}^{j} M_{l-j}.$$

The summands on the right-hand side belong, in turn, to the spaces

$$\boldsymbol{x}^{l-j}\mathcal{M}_0, \quad \boldsymbol{x}^{l-j-1}\mathcal{M}_1, \quad \dots, \quad \boldsymbol{x}\mathcal{M}_{l-j-1}, \quad \mathcal{M}_{l-j}.$$

Hence, $(D^{\alpha})^{j} \mathbf{x}^{j} M_{l-j}$ is equal to $\pi_{\mathcal{M}}((D^{\alpha})^{j} P_{l})$. We can now use the expression for the harmonic projection proved above. So, to get our result it is sufficient to show that

$$(\mathrm{D}^{\alpha})^{j} \boldsymbol{x}^{j} M_{l-j} = \frac{1}{c_{j}} M_{j}.$$

By Theorem 3.8, we get by induction that $c'_j = a_j$, and therefore the proof is finished. \square

Under these conditions it is possible to calculate the dimension of the space of fractional homogeneous monogenic polynomials of degree l. From the Fischer decomposition (3.11) we get $\dim(\mathcal{M}_l) = \dim(\Pi_l) - \dim(\Pi_{l-1})$, with the dimension of the space of fractional homogeneous polynomials of degree l given by $\dim(\Pi_l) = (k+d-1)!/k!(d-1)!$. This leads to the following theorem.

Theorem 3.11. The space of fractional homogeneous monogenic polynomials of degree l has dimension

$$\dim(\mathcal{M}_k) = \frac{(l+d-1)! - l(l+d-2)!}{l!(d-1)!} = \frac{(l+d-2)!}{l!(d-2)!}.$$

4. Fractional Cauchy-Kovalevskaya extension

Taking into account the formal similarities with the classical setting, we propose the following form for the FCK extension:

$$F(x_1, x_2, \dots, x_d) = \sum_{k=0}^{\infty} \frac{(e_1 x_1)^k x_1^{1-\alpha}}{k!} f_k(x_2, \dots, x_d),$$

with $f_0 = f$. From (3.7) we conclude that the function F takes the correct values and satisfies $F|_{x_1=0} = f$. For F to be fractional monogenic it must vanish under the action of the fractional Dirac operator D^{α} , which can be rewritten as

$$\mathrm{D}^{lpha} = \mathrm{D}_1^{lpha} + \sum_{j=2}^d oldsymbol{e}_j \mathrm{D}_j^{lpha} = \mathrm{D}_1^{lpha} + \mathrm{D}_*^{lpha}.$$

In order to determine the coefficient functions f_k , k = 1, 2, ..., d, such that $D^{\alpha}F = 0$, we proceed by direct calculation. From the action of D_j^{α} over \boldsymbol{x}_1 (see Theorem 3.3), and taking into account that D_1^{α} only acts on \boldsymbol{x}_1^k and D_*^{α} anticommutes with \boldsymbol{x}_1 , we obtain

$$0 = D^{\alpha} F = (D_1^{\alpha} + D_*^{\alpha}) \left(\sum_{k=0}^{\infty} \frac{(e_1 x_1)^k x_1^{1-\alpha}}{k!} f_k \right)$$
$$= \sum_{k=0}^{\infty} \frac{(e_1 x_1)^k x_1^{1-\alpha}}{k!} f_{k+1} + \sum_{k=0}^{\infty} (-1)^k \frac{(e_1 x_1)^k x_1^{1-\alpha}}{k!} D_*^{\alpha} f_k,$$

which results in the recurrence relation

$$f_{k+1} = (-1)^{k+1} \mathcal{D}_*^{\alpha} f_k.$$

Hence, we obtain the following definition for the FCK extension.

Definition 4.1. The FCK extension of a function $f = f(x_2, ..., x_d)$ is the fractional monogenic function

$$FCK[f](x_1, x_2, ..., x_d) = \sum_{k=0}^{\infty} \frac{(e_1 x_1)^k x_1^{1-\alpha}}{k!} f_k(x_2, ..., x_d),$$
(4.1)

where $f_0 = f$ and $f_{k+1} = (-1)^{k+1} D_*^{\alpha} f_k$.

Let us observe that the previous definition does not impose any conditions on the original function f. From (3.7) follow

$$(e_1 x_1)^{2n+1} x_1^{1-\alpha} = 0$$
 for $n \le |x_1|$,
 $(e_1 x_1)^{2n} x_1^{1-\alpha} = 0$ for $n \le |x_1| + 1$,

which imply that for every point $(\boldsymbol{x}_1,\ldots,\boldsymbol{x}_d)\in\mathbb{R}^d$ there exists $N\in\mathbb{N}$ such that all but the first N terms in the series (4.1) vanish, and therefore the series reduces to a finite sum at every point of \mathbb{R}^d . This fact implies that the FCK extension of the function $f(\boldsymbol{x}_2,\ldots,\boldsymbol{x}_d)$ is well defined on \mathbb{R}^d . The uniqueness of the extension is a corollary of the following result.

Theorem 4.2. Let F be a fractional monogenic function defined on \mathbb{R}^d with $F|_{x_1=0} \equiv 0$. Then F is the null function.

Proof. The fractional monogenicity of F explicitly reads as $(D_1^{\alpha} + D_*^{\alpha})F = 0$. Now take $(\boldsymbol{x}_1, \boldsymbol{x}_2, \dots, \boldsymbol{x}_d) \in \mathbb{R}^d$ with $\boldsymbol{x}_1 = 0$. Since $F|_{\boldsymbol{x}_1=0} \equiv 0$, the above expression reduces to $D_i^{\alpha}F = 0$. Furthermore, $-\Delta^{2\alpha}F = D^{\alpha}D^{\alpha}F = 0$, from which we obtain, for $(0, \boldsymbol{x}_2, \dots, \boldsymbol{x}_d) \in \mathbb{R}^d$ with $\boldsymbol{x}_1 = 0$, that $F \equiv 0$. Repeating this procedure, we find that $F \equiv 0$ on \mathbb{R}^d .

Corollary 4.3 (uniqueness of the FCK extension). Let F_1 and F_2 be two fractional monogenic functions such that $F_1|_{x_1=0} = f$ and $F_2|_{x_1=0} = f$. Then F_1 and F_2 coincide.

4.1. Fractional Fueter polynomials

The fractional FCK extension procedure establishes a homomorphism between the space $\Pi_l^{(d-1)}$ of fractional homogeneous polynomials of degree l in d-1 variables and the space $\mathcal{M}_l^{(d)}$ of spherical fractional monogenics of degree l in d variables. Theorem 4.2 and Corollary 4.3 imply that this homomorphism is injective. Moreover, a basis for the space $\Pi_l^{(d-1)}$ is given by the fractional homogeneous polynomials $\boldsymbol{x}_2^{\beta_2} \cdots \boldsymbol{x}_d^{\beta_d}$, with $\beta_2 + \cdots + \beta_d = l$, and its dimension is

$$\dim(\Pi_l^{(d-1)}) = \frac{(l-d)!}{l!(d-2)!},$$

which corresponds to the dimension of $\mathcal{M}_l^{(d)}$ (see Theorem 3.11 with d=d-1), whence the homomorphism is also surjective. The FCK extension procedure thus establishes an isomorphism between $\Pi_l^{(d-1)}$ and $\mathcal{M}_l^{(d)}$, allowing us to determine a basis for the space $\mathcal{M}_l^{(d)}$.

Definition 4.4. Let $\beta = (\beta_2, \dots, \beta_d) \in \mathbb{N}^{d-1}$ with $\beta_2 + \dots + \beta_d = l$. Then the fractional spherical monogenics

$$V_{\beta} = \mathrm{FCK} \left[oldsymbol{x}_2^{eta_2} \cdots oldsymbol{x}_d^{eta_d} \prod_{j=2}^d oldsymbol{x}_j^{1-lpha}
ight]$$

are called the fractional Fueter polynomials of degree l.

Theorem 4.5. The set $\{V_{\beta} \mid \beta_2 + \cdots + \beta_d = l\}$ is a basis for $\mathcal{M}_l^{(d)}$.

Proof. The FCK extension procedure is an isomorphism between both spaces. \Box

Example 4.6. The space $\mathcal{M}_2^{(3)}$ has dimension d=3. A basis for it is given by the elements

$$\begin{split} V_{2,0} &= \mathrm{FCK}[\boldsymbol{x}_2^2 \boldsymbol{x}_2^{1-\alpha}] \\ &= \boldsymbol{x}_2^2 \boldsymbol{x}_2^{1-\alpha} - 2\boldsymbol{x}_1 \boldsymbol{x}_2 \boldsymbol{x}_1^{1-\alpha} \boldsymbol{x}_2^{1-\alpha} - \boldsymbol{x}_1^2 \boldsymbol{x}_1^{1-\alpha}, \\ V_{1,1} &= \mathrm{FCK}[\boldsymbol{x}_2 \boldsymbol{x}_3 \boldsymbol{x}_2^{1-\alpha} \boldsymbol{x}_3^{1-\alpha}] \\ &= \boldsymbol{x}_2 \boldsymbol{x}_3 \boldsymbol{x}_2^{1-\alpha} \boldsymbol{x}_3^{1-\alpha} - \boldsymbol{x}_1 \boldsymbol{x}_3 \boldsymbol{x}_1^{1-\alpha} \boldsymbol{x}_3^{1-\alpha} + \boldsymbol{x}_1 \boldsymbol{x}_2 \boldsymbol{x}_1^{1-\alpha} \boldsymbol{x}_2^{1-\alpha} + \boldsymbol{x}_1^2 \boldsymbol{x}_1^{1-\alpha}, \\ V_{0,2} &= \mathrm{FCK}[\boldsymbol{x}_3^2 \boldsymbol{x}_3^{1-\alpha}] \\ &= \boldsymbol{x}_3^2 \boldsymbol{x}_3^{1-\alpha} - 2\boldsymbol{x}_1 \boldsymbol{x}_3 \boldsymbol{x}_1^{1-\alpha} \boldsymbol{x}_3^{1-\alpha} - \boldsymbol{x}_1^2 \boldsymbol{x}_1^{1-\alpha}, \end{split}$$

from which it can be checked directly that they are fractional monogenic, of homogeneity degree 2 in (x_1, x_2, x_3) , and are linearly independent.

4.2. Fractional Cauchy–Kovalevskaya extension of $x^s M_l$

In the Euclidian setting functions of the form $x^s P_l(x)$ are building blocks of homogeneous polynomials in \mathbb{R}^d and whence, in order to characterize spaces of inner spherical monogenics in \mathbb{R}^{d+1} , it suffices to determine the CK extension of polynomials of the form $x^s P_l(x)$ (see [14] for more details), which was formulated in the following theorem.

Theorem 4.7 (cf. Delanghe et al. [14]). Let $s \in \mathbb{N}$ and let $P_l \in M^+(l;d;C)$. Then the CK extension of $x^s P_l(x)$ has the form $X_l^s(x_0, x) P_l(x)$, where

$$X_l^s(x_0,x) = \lambda_l^s r^s \left[C_s^{(d-1)/2+l} \left(\frac{x_0}{r} \right) + \frac{2l+d-1}{s+2l+d-1} C_{s-1}^{(d+1)/2+l} \left(\frac{x_0}{r} \right) \frac{x_0}{r} \right].$$

In this equation, $r^2 = x_0^2 - x^2$ and the polynomials $C_n^{\lambda}(x)$ are the standard Gegenbauer polynomials [1] given by

$$C_n^{\lambda}(x) = \sum_{j=0}^{[n/2]} \frac{(-1)^j (\lambda)_{n-j}}{j!(n-2j)!} (2x)^{n-2j}, \tag{4.2}$$

where the Pochhammer symbol $(a)_n$ denotes $a(a+1)\cdots(a+n-1)$. Furthermore, the coefficients λ_k^s are

$$\lambda_l^{2k} = (-1)^k (C_{2k}^{(d-1)/2+l}(0))^{-1}, \qquad \lambda_l^{2k+1} = (-1)^k \frac{2k+2l+d}{2l+d-1} (C_{2k}^{(d+1)/2+l}(0))^{-1},$$

and explicitly

$$\lambda_l^{2k} = \frac{k!\Gamma(l + \frac{1}{2}(d-1))}{\Gamma(k+l+\frac{1}{2}(d-1))}, \qquad \lambda_l^{2k+1} = \frac{2k+2l+d}{2l+d-1} \frac{k!\Gamma(l+\frac{1}{2}(d+1))}{\Gamma(k+l+\frac{1}{2}(d+1))}. \tag{4.3}$$

We now consider the fractional version of the previous theorem. We will consider P_l to be a fractional homogeneous monogenic function in d variables x_1, \ldots, x_d and will

determine the FCK extension of $x^s P_l$. The result is a fractional monogenic in d+1 variables x_0, x_1, \ldots, x_d such that

$$FCK[f] = \sum_{k=0}^{\infty} \frac{1}{k!} x_1 f_k, \qquad f_0 = f, \qquad f_{k+1} = (-1)^{k+1} D^{\alpha} f_k,$$

where D^{α} is the fractional Dirac operator in d variables. The operators D^{α} and \boldsymbol{x} satisfy Theorem 3.8. Denote by R the fractional vector variable in d+1 dimensions, i.e.

$$R = x_0 - \sum_{j=1}^d e_j x_j = x_0 - x,$$

with $R^2 = x_0^2 + x^2$.

Remark 4.8. As was done in the Euclidian case (see our Theorem 4.7 from [14]), in this section we will use the formal notation x_0/R and x/R as arguments in the Gegenbauer polynomials, by which we mean that we first of all expand the Gegenbauer polynomials using $(x_0/R)^k = x_0^k/R^k$, and then cancel out all appearances of R in the denominators, after which no ambiguity is left.

4.2.1. Auxiliary results

In this section we present some necessary results for the proof, in the next section, of the main theorem. Taking into account Theorem 3.3, we present the following auxiliary lemmas.

Lemma 4.9. Let $k \in \mathbb{N}$ and let P_l be a fractional spherical monogenic of degree l in the variables x_1, \ldots, x_d . Then

$$D_0^{\alpha} R^{2k} P_l = -2\alpha k x_0 R^{2k-2} P_l, \tag{4.4}$$

$$D^{\alpha}R^{2k}P_l = 2\alpha k \boldsymbol{x} R^{2k-2} P_l, \tag{4.5}$$

$$\mathbb{E}^{\alpha} R^{2k} P_l = (-lR^2 - \alpha k \mathbf{x}^2) R^{2k-2} P_l. \tag{4.6}$$

Proof. We start by expanding R^{2k} in the following way:

$$R^{2k} = \sum_{s=0}^{k} \binom{k}{s} x_0^{2k-2s} x^{2s}.$$

Taking into account that x and P_l do not depend on x_0 , we get

$$D_0^{\alpha} R^{2k} P_l = -2\alpha k \sum_{s=0}^{k-1} \frac{(k-1)!}{s!(k-s-1)!} \boldsymbol{x}_0^{2k-2s-1} \boldsymbol{x}^{2s} P_l = -2\alpha k \boldsymbol{x}_0 R^{2k-2} P_l.$$

The proof of the second statement uses the relations presented in Theorem 3.8 and the fact that P_l is a fractional spherical monogenic in the variables $\mathbf{x}_1, \dots, \mathbf{x}_d$ (thus, $D^{\alpha}P_l = 0$):

$$D^{\alpha}R^{2k}P_{l} = 2s\alpha \sum_{s=0}^{k} \frac{k!}{(s-1)!(k-s)!} \boldsymbol{x}_{0}^{2k-2s} \boldsymbol{x}^{2s-1}P_{l}$$

$$= 2s\alpha k \sum_{s=1}^{k} \frac{k!}{(s-1)!(k-s)!} \boldsymbol{x}_{0}^{2k-2s} \boldsymbol{x}^{2s-1}P_{l}$$

$$= 2\alpha k \boldsymbol{x} R^{2k-2}P_{l}.$$

For the final relation we use the commutation relation

$$x\mathbb{E}^{\alpha} - \mathbb{E}^{\alpha}x = \alpha x \iff \mathbb{E}^{\alpha}x = x\mathbb{E}^{\alpha} - \alpha x$$

which implies that

$$\mathbb{E}^{\alpha} \boldsymbol{x}^{2s} = \boldsymbol{x}^{2s} \mathbb{E}^{\alpha} - 2s\alpha \boldsymbol{x}^{2s},$$

to show that

$$\mathbb{E}^{\alpha} R^{2k} P_l = -l R^{2k} P_l - 2\alpha k \sum_{p=0}^{k-1} {k-1 \choose p} x_0^{2(k-1)-2p} x^{2p+2} P_l$$
$$= (-l R^2 - 2\alpha k x^2) R^{2k-2} P_l.$$

Lemma 4.10. For a parameter λ and $k \geqslant 1$ we have

$$\left(D_0^{\alpha} + D^{\alpha}\right) \left[C_{2k}^{\lambda} \left(\frac{\boldsymbol{x}_0}{R}\right) R^{2k} P_l \right] = -2\alpha \lambda \left[C_{2k-1}^{\lambda+1} \left(\frac{\boldsymbol{x}_0}{R}\right) - C_{2k-2}^{\lambda+1} \left(\frac{\boldsymbol{x}_0}{R}\right) \right] R^{2k-1} P_l.$$

Proof. Taking into account the series expansion (4.2) for the Gegenbauer polynomials and the relations presented in Lemma 4.9, after straightforward calculations we have

$$\begin{split} \left(\mathcal{D}_{0}^{\alpha} + \mathcal{D}^{\alpha}\right) & \left[C_{2k}^{\lambda} \left(\frac{\boldsymbol{x}_{0}}{R}\right) R^{2k} P_{l}\right] \\ & = \sum_{j=0}^{k} \frac{(-1)^{j} (\lambda)_{2k-j}}{j! (2k-2j)!} 2^{2k-2j} \left[-\alpha (2k-2j) \boldsymbol{x}_{0}^{2k-2j-1} R^{2j} + \boldsymbol{x}_{0}^{2k-2j} \mathcal{D}_{0}^{\alpha} R^{2j} \right. \\ & \qquad \qquad + (-1)^{2k-2j} \boldsymbol{x}_{0}^{2k-2j} \mathcal{D}^{\alpha} R^{2j} \left] P_{l} \\ & = -2\alpha \lambda \left[C_{2k-1}^{\lambda+1} \left(\frac{\boldsymbol{x}_{0}}{R}\right) - C_{2k-2}^{\lambda+1} \left(\frac{\boldsymbol{x}_{0}}{R}\right)\right] R^{2k-1} P_{l}. \end{split}$$

We remark that in Lemma 4.10, on the right-hand side, there is no ambiguity about whether the Rs should be left or right since the first thing one has to do is eliminate the powers of R in the denominator, which leaves only even powers of R (in the denominator), which commute with x_0 and x. We now continue presenting auxiliary lemmas.

Lemma 4.11. For a parameter λ and $k \ge 1$ we have

$$\begin{split} (\mathbf{D}_0^\alpha + \mathbf{D}^\alpha) \bigg[C_{2k-1}^\lambda \bigg(\frac{\boldsymbol{x}_0}{R} \bigg) \frac{\boldsymbol{x}}{R} R^{2k} P_l \bigg] \\ &= \bigg[-2\alpha \lambda C_{2k-2}^{\lambda+1} \bigg(\frac{\boldsymbol{x}_0}{R} \bigg) \boldsymbol{x} R^{2k-2} + \alpha (d+2l) C_{2k-1}^\lambda \bigg(\frac{\boldsymbol{x}_0}{R} \bigg) R^{2k-1} \\ &\qquad \qquad -2\alpha \lambda C_{2k-3}^{\lambda+1} \bigg(\frac{\boldsymbol{x}_0}{R} \bigg) \frac{\boldsymbol{x}}{R} R^{2k-1} \bigg] P_l. \end{split}$$

Proof. Taking into account the series expansion (4.2) for the Gegenbauer polynomials and the relations presented in Lemma 4.9, after straightforward calculations we have

$$\begin{split} &(\mathbf{D}_{0}^{\alpha} + \mathbf{D}^{\alpha}) \left[C_{2k-1}^{\lambda} \left(\frac{x_{0}}{R} \right) \frac{x}{R} R^{2k} P_{l} \right] \\ &= -\alpha \sum_{j=0}^{k-1} \frac{(-1)^{j} (\lambda)_{2k-j-1}}{j! (2k-2j-2)!} 2^{2k-2j-1} x_{0}^{2k-2j-2} x R^{2j} P_{l} \\ &\qquad - \sum_{j=0}^{k-1} \frac{(-1)^{j} (\lambda)_{2k-j-1}}{j! (2k-2j-1)!} (2x_{0})^{2k-2j-1} [x \mathbf{D}_{0}^{\alpha} R^{2j} - (2\mathbb{E}^{\alpha} - \alpha d + x \mathbf{D}^{\alpha}) R^{2j}] P_{l} \\ &= -2\alpha \lambda C_{2k-2}^{\lambda+1} \left(\frac{x_{0}}{R} \right) x R^{2k-2} P_{l} + \alpha (d+2l) C_{2k-1}^{\lambda} \left(\frac{x_{0}}{R} \right) R^{2k-1} P_{l} \\ &\qquad - 2\alpha \lambda \sum_{p=0}^{k-2} \frac{(-1)^{p} (\lambda)_{2k-p-3}}{p! (2k-2p-3)!} \left(\frac{2x_{0}}{R} \right)^{2k-2p-3} \frac{x}{R} R^{2k-1} P_{l} \\ &= \left[-2\alpha \lambda C_{2k-2}^{\lambda+1} \left(\frac{x_{0}}{R} \right) x R^{2k-2} + \alpha (d+2l) C_{2k-1}^{\lambda} \left(\frac{x_{0}}{R} \right) R^{2k-1} - 2\alpha \lambda C_{2k-3}^{\lambda+1} \left(\frac{x_{0}}{R} \right) \frac{x}{R} R^{2k-1} \right] P_{l}. \end{split}$$

We remark that in Lemma 4.11, after elimination of the powers of R in the denominator, there is no ambiguity in the first and last terms of the right-hand side. For the second term, however, we must clarify how the elimination should be made. For example, letting d=2 we have

$$C_1^{\lambda+1}\left(\frac{\boldsymbol{x}_0}{R}\right)\frac{\boldsymbol{x}}{R}R^3 = 2(\lambda+1)\frac{\boldsymbol{x}_0}{R}\frac{\boldsymbol{x}}{R}R^3 = 2(\lambda+1)\boldsymbol{x}_0\boldsymbol{x}R,$$

which is not the same as

$$C_1^{\lambda+1} \left(\frac{\boldsymbol{x}_0}{R}\right) R^3 \frac{\boldsymbol{x}}{R} = 2(\lambda+1) \boldsymbol{x}_0 R \boldsymbol{x}$$

or

$$R^3C_1^{\lambda+1}\left(\frac{\boldsymbol{x}_0}{R}\right)\frac{\boldsymbol{x}}{R} = 2(\lambda+1)R\boldsymbol{x}_0\boldsymbol{x}.$$

For the second term on the right-hand side we thus put as a convention that (after elimination of R in the denominator) the remaining (odd) powers of R are written on the far right of both x_0 and x.

In a very similar way to in Lemma 4.11, we can prove the following results.

Lemma 4.12. For a parameter λ and $k \ge 1$ we have

$$\begin{split} (\mathbf{D}_0^\alpha + \mathbf{D}^\alpha) \bigg[C_{2k+1}^\lambda \bigg(\frac{\boldsymbol{x}_0}{R} \bigg) \frac{\boldsymbol{x}}{R} R^{2k} P_l \bigg] \\ &= -2\alpha \lambda \bigg[C_{2k}^{\lambda+1} \bigg(\frac{\boldsymbol{x}_0}{R} \bigg) - C_{2k-1}^{\lambda+1} \bigg(\frac{\boldsymbol{x}_0}{R} \bigg) \bigg(\frac{\boldsymbol{x}_0}{R} - \frac{\boldsymbol{x}}{R} \bigg) \bigg] R^{2k} P_l. \end{split}$$

Lemma 4.13. For a parameter λ and $k \ge 1$ we have

$$\begin{split} (\mathbf{D}_0^\alpha + \mathbf{D}^\alpha) \bigg[C_{2k}^\lambda \bigg(\frac{\boldsymbol{x}_0}{R} \bigg) \frac{\boldsymbol{x}}{R} R^{2k+1} P_l \bigg] \\ &= \bigg[\alpha (d+2l) C_{2k}^\lambda \bigg(\frac{\boldsymbol{x}_0}{R} \bigg) R^{2k} - 2\alpha \lambda C_{2k-1}^{\lambda+1} \bigg(\frac{\boldsymbol{x}_0}{R} \bigg) \frac{\boldsymbol{x}}{R} R^{2k} \\ &- 2\alpha \lambda C_{2k-2}^{\lambda+1} \bigg(\frac{\boldsymbol{x}_0}{R} \bigg) \frac{\boldsymbol{x}}{R} \boldsymbol{x} R^{2k-1} \bigg] P_l. \end{split}$$

4.2.2. Main result

We now present the main result of this section.

Theorem 4.14. For a fractional spherical monogenic P_l of degree l in the fractional variables x_1, \ldots, x_d and for $s \in \mathbb{N}$, the fractional FCK extension of $x^s P_l$ is the fractional monogenic polynomial in d+1 variables x_0, x_1, \ldots, x_d given by

$$FCK[\mathbf{x}^{2k}P_{l}] = (-1)^{k} \lambda_{l}^{2k} R^{2k} \left[C_{2k}^{(d+1)/2+k} \left(\frac{\mathbf{x}_{0}}{R} \right) + \frac{2l+d-1}{2l+d-1+2k} C_{2k-1}^{(d-1)/2+k} \left(\frac{\mathbf{x}_{0}}{R} \right) \frac{\mathbf{x}}{R} \right] P_{l}, \quad (4.7)$$

$$FCK[\mathbf{x}^{2k+1}P_{l}] = (-1)^{k} \lambda_{l}^{2k+1} R^{2k+1} \left[-C_{2k+1}^{(d-1)/2+k} \left(\frac{\mathbf{x}_{0}}{R} \right) + \frac{2l+d-1}{2l+d-1+2k} C_{2k}^{(d+1)/2+k} \left(\frac{\mathbf{x}_{0}}{R} \right) \frac{\mathbf{x}}{R} \right] P_{l}. \quad (4.8)$$

In this formula $r^2 = x_0^2 - x^2$, $C_n^{\lambda}(x)$ are the standard Gegenbauer polynomials given by (4.2), and the coefficients λ_k^s are given by (4.3).

Before we present the proof we give the following remark concerning notation, which is similar to the one presented in [10].

Remark 4.15. Please note that in the main theorem terms like $C_k^{\lambda}(x_0/R)$ appear, while in fact x_0/R is not well defined. Since $Rx_0 \neq x_0R$ and $Rx \neq xR$, the notation has to be understood in the following way: because $C_k^{\lambda}(x)$ contains only powers of x of degree at most k, we first multiply it by R^k , after which there is no ambiguity.

Let us now consider the proof.

Proof. We start with expression (4.7). The proof has two parts. In the first we show that the restriction of

$$F := (-1)^k \lambda_l^{2k} n R^{2k} \left[C_{2k}^{(d-1)/2+k} \left(\frac{\boldsymbol{x}_0}{R} \right) + \frac{2l+d-1}{2l+d-1+2k} C_{2k-1}^{(d+1)/2+k} \left(\frac{\boldsymbol{x}_0}{R} \right) \frac{\boldsymbol{x}_0}{R} \right] P_l$$

to the hyperplane $x_0 = 0$ is exactly $x^{2k}P_l$. In fact, $R^{2j}|_{x_0=0} = x^{2j}$ and

$$C_{2k}^{\lambda}\left(\frac{\boldsymbol{x}_0}{R}\right)\bigg|_{\boldsymbol{x}_0=0} = \sum_{j=0}^k \frac{(-1)^j(\lambda)_{2k-j}}{j!(2k-2j)!} \left(\frac{2\boldsymbol{x}_0}{R}\right)^{2k-2j}\bigg|_{\boldsymbol{x}_0=0} = \frac{(-1)^k(\lambda)_k}{k!},$$

$$C_{2k-1}^{\lambda}\left(\frac{x_0}{R}\right)\Big|_{x_0=0} = \sum_{j=0}^{k-1} \frac{(-1)^j (\lambda)_{2k-j-1}}{j!(2k-2j-1)!} \left(\frac{2x_0}{R}\right)^{2k-2j-1}\Big|_{x_0=0} = 0,$$

which implies that

$$F|_{\boldsymbol{x}_0=0} = \frac{k!\Gamma(l+(d-1)/2)}{\Gamma(l+(d-1)/2+k)} \frac{1}{k!} \frac{\Gamma(l+(d-1)/2+k)}{\Gamma(l+(d-1)/2)} \boldsymbol{x}^{2k} P_l = \boldsymbol{x}^{2k} P_l.$$

In the second part of the proof we show that F is fractional monogenic in the d+1 variables $\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_d$. By the uniqueness of the FCK extension, we know that F must be exactly FCK[$\mathbf{x}^{2k}P_l$]. Since F consists of two terms, we will first consider $D_0^{\alpha} + D^{\alpha}$ acting on each term separately via Lemmas 4.10 and 4.11 with $\lambda = l + (d-1)/2$. We will then continue by combining the obtained results. We have

$$\begin{split} &(\mathbf{D}_{0}^{\alpha} + \mathbf{D}^{\alpha})F \\ &= (-1)^{k+1} \lambda_{l}^{2k} 2\alpha \lambda \bigg[C_{2k-1}^{\lambda+1} \bigg(\frac{x_{0}}{R} \bigg) - C_{2k-2}^{\lambda+1} \bigg(\frac{x_{0}}{R} \bigg) \bigg] R^{2k-1} P_{l} \\ &\quad + (-1)^{k} \lambda_{l}^{2k} \frac{\lambda}{\lambda + k} \bigg[-2\alpha (\lambda + 1) C_{2k-2}^{\lambda+2} \bigg(\frac{x_{0}}{R} \bigg) x R^{2k-2} \\ &\quad + \alpha (2\lambda - 1) C_{2k-1}^{\lambda+1} \bigg(\frac{x_{0}}{R} \bigg) R^{2k-1} \\ &\quad - 2\alpha (\lambda + 1) C_{2k-3}^{\lambda+2} \bigg(\frac{x_{0}}{R} \bigg) \frac{x}{R} R^{2k-1} \bigg] P_{l} \\ &= (-1)^{k+1} \lambda_{l}^{2k} 2\alpha \lambda \bigg[\frac{2k+1}{2\lambda + 2k} C_{2k-1}^{\lambda+1} \bigg(\frac{x_{0}}{R} \bigg) R^{2k-1} - C_{2k-1}^{\lambda+1} \bigg(\frac{x_{0}}{R} \bigg) R^{2k-1} \\ &\quad + \frac{\lambda + 1}{\lambda + k} C_{2k-2}^{\lambda+2} \bigg(\frac{x_{0}}{R} \bigg) \frac{x}{R} R^{2k-1} + \frac{\lambda + 1}{\lambda + k} C_{2k-3}^{\lambda+2} \bigg(\frac{x_{0}}{R} \bigg) \frac{x}{R} R^{2k-1} \bigg] P_{l}. \end{split}$$

Taking into account the series expansion (4.2) for the Gegenbauer polynomials, the previous expression becomes

$$(D_{0}^{\alpha} + D^{\alpha})F$$

$$= (-1)^{k+1} \lambda_{l}^{2k} \alpha \left[\frac{\lambda(2k+1)}{\lambda + k} \sum_{j=0}^{k-1} \frac{(-1)^{j}(\lambda)_{2k-j}}{j!(2k-2j-1)!} 2^{2k-2j-1} \boldsymbol{x}_{0}^{2k-2j-1} R^{2j} \right]$$

$$- \sum_{j=0}^{k-1} \frac{(-1)^{j}(\lambda)_{2k-j-1}}{j!(2k-2j-2)!} 2^{2k-2j-1} \boldsymbol{x}_{0}^{2k-2j-2} R^{2j+1}$$

$$+ \frac{1}{\lambda + k} \sum_{j=0}^{k-1} \frac{(-1)^{j}(\lambda)_{2k-j}}{j!(2k-2j-2)!} 2^{2k-2j-1} \boldsymbol{x}_{0}^{2k-2j-2} \boldsymbol{x} R^{2j}$$

$$+ \frac{1}{\lambda + k} \sum_{j=0}^{k-2} \frac{(-1)^{j}(\lambda)_{2k-j-1}}{j!(2k-2j-3)!} 2^{2k-2j-2} \boldsymbol{x}_{0}^{2k-2j-3} \boldsymbol{x} R^{2j+1} \right] P_{l}. \quad (4.9)$$

From the series expansions of R^{2j} and R^{2j+1} ,

$$R^{2j} = \sum_{s=0}^{j} {j \choose s} \boldsymbol{x}_0^{2j-2s} \boldsymbol{x}^{2s}, \qquad R^{2j+1} = \sum_{s=0}^{j} {j \choose s} (\boldsymbol{x}_0^{2j-2s+1} \boldsymbol{x}^{2s} + \boldsymbol{x}_0^{2j-2s} \boldsymbol{x}^{2s+1}),$$

there are two possible combinations (with respect to the powers of x_0 and x): either an odd power of x_0 combined with an even power of x or vice-versa. We will look at both possibilities separately and show that both must be zero. We first consider the terms of (4.9) containing a combination of an even power of x_0 and an odd power of x, which we call the 'even part' and denote by EP:

$$\begin{split} \mathrm{EP} &= (-1)^{k+1} \lambda_l^{2k} \alpha \bigg[- \sum_{j=0}^{k-1} \frac{(-1)^j (\lambda)_{2k-j-1}}{j! (2k-2j-2)!} 2^{2k-2j-1} \boldsymbol{x}_0^{2k-2j-2} \boldsymbol{x} R^{2j} \\ &\quad + \sum_{j=0}^{k-1} \frac{(-1)^j (\lambda)_{2k-j}}{j! (2k-2j-2)!} \frac{2^{2k-2j-1}}{\lambda+k} \boldsymbol{x}_0^{2k-2j-2} \boldsymbol{x} R^{2j} \\ &\quad + \frac{1}{\lambda+k} \sum_{j=0}^{k-2} \frac{(-1)^j (\lambda)_{2k-j-1}}{j! (2k-2j-3)!} 2^{2k-2j-2} \boldsymbol{x}_0^{2k-2j-3} \boldsymbol{x}_0 \boldsymbol{x} R^{2j} \bigg] P_l \\ &= (-1)^{k+1} \lambda_l^{2k} \alpha \bigg[\frac{1}{\lambda+k} \sum_{j=0}^{k-1} \frac{(-1)^j (\lambda)_{2k-j-1}}{j! (2k-2j-2)!} (k-j-1) 2^{2k-2j-1} \boldsymbol{x}_0^{2k-2j-2} \boldsymbol{x} R^{2j} \\ &\quad + \frac{1}{\lambda+k} \sum_{j=0}^{k-2} \frac{(-1)^j (\lambda)_{2k-j-1}}{j! (2k-2j-3)!} 2^{2k-2j-2} \boldsymbol{x}_0^{2k-2j-2} \boldsymbol{x} R^{2j} \bigg] P_l \\ &= 0. \end{split}$$

For the 'odd part' we proceed in a very similar way.

One checks for different values of j for which the coefficients of R^{2j} will be zero, and hence the total sum will be zero. Regarding (4.8), we proceed in a similar way and consider Lemmas 4.12 and 4.13.

4.3. Example

To end the paper we present an example of an FCK extension.

Example 4.16. The FCK extension of x^2P_l is given by

$$FCK[\boldsymbol{x}^2 P_l] = \sum_{k=0}^{\infty} \frac{\boldsymbol{x}_0^k}{k!} f_k,$$

where the functions f_k are $f_0 = \mathbf{x}^2 P_l$, $f_1 = -2\alpha \mathbf{x} P_l$, $f_2 = 2\alpha (-2l - \alpha d) P_l$, whence explicitly

$$FCK[\mathbf{x}^2 P_l] = [\mathbf{x}^2 - 2\alpha \mathbf{x} + 2\alpha(-2l - \alpha d)]P_l.$$

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