

Projections of fractal percolations

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Abstract. In this paper we study the radial and orthogonal projections and the distance sets of the random Cantor sets $E \subset \mathbb{R}^2$, which are called Mandelbrot percolation or percolation fractals. We prove that the following assertion holds almost surely: if the Hausdorff dimension of E is greater than 1 then the orthogonal projection to *every* line, the radial projection with *every* centre, and the distance set from *every* point contain intervals.

1. Introduction

Figure 1 shows what we prove: although the fractal percolation is a Cantor dust, it throws a thick shadow *at any time*. Here, thick means containing at least one non-trivial open interval (we will write simply ‘containing intervals’). One does not need to rotate it to use it as an umbrella.

In order to construct a model for turbulence, Mandelbrot introduced [11] a random set which is now called Mandelbrot percolation or fractal percolation or canonical curdling. In the simplest case (we consider a more general case in this paper), we are given a natural number $M \geq 2$ and a probability $p \in (0, 1)$. First we partition the unit square $[0, 1]^2$ into M^2 congruent squares and then we retain each of them with probability p and discard them with probability $1 - p$ independently. In the squares which were retained we repeat this process independently ad infinitum. The random set $E \subset [0, 1]^2$ that results is the fractal percolation or canonical curdling. In fact, in this paper we sometimes consider the more general setup where the M^2 congruent squares, mentioned above, are chosen with not necessarily the same probabilities.

These random Cantor sets have attracted considerable attention. In 1978, Peyrière computed the almost sure Hausdorff dimension, conditioned on non-extinction (this result was re-proved many times). In 1988, Chayes *et al* [2] proved that there is a critical probability p_c such that for every $0 < p < p_c$ the random Cantor set E is totally

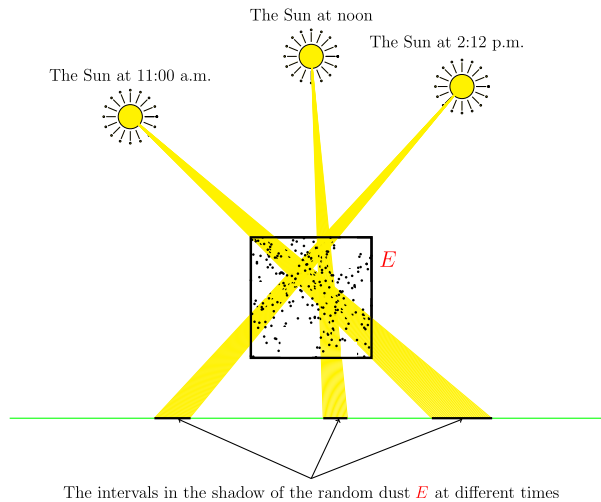


FIGURE 1. Projections of fractal percolation.

disconnected, but for every $p > p_c$ with positive probability E percolates. This means that there is a connected component in E which connects the left hand side wall to the right hand side wall of the unit square $[0, 1]^2$ with positive probability. Dekking and Meester [3] gave a simplified proof for the previously mentioned result and defined several phases such that as we increase p the process passes through all of these phases. If the fractal is totally disconnected ($p < p_c$) it can still happen that some of its projections contain intervals.

The orthogonal projections of fractals on the plane were already studied by Marstrand [12] in 1954. Marstrand's theorem says that for any set $A \subset \mathbb{R}^2$ with $\dim_{\text{H}} A > 1$, the orthogonal projection of A to almost all lines has positive Lebesgue measure; here, \dim_{H} denotes the Hausdorff dimension.

Existence of an interval in the orthogonal projections of some Cantor sets in the plane was first studied in relation to the famous Palis conjecture about the algebraic difference of Cantor sets. The algebraic difference of the Cantor sets C_1, C_2 is the 45° projection of $C_1 \times C_2$. Palis conjectured that 'typically' $C_1 - C_2$ is either small in the sense that it has Lebesgue measure zero or big in the sense that it contains some intervals. See, for example, [4, 14–16].

For percolation fractals, Falconer and Grimmett [6, 7] studied the existence of intervals in the vertical and horizontal projections. Our work is a generalization of their result.

The most important conclusion of our result is that whenever the probability $p > 1/M$ then, although the set E may be totally disconnected, almost surely conditioned on non-extinction, all projections in various families (orthogonal, radial, co-radial projections) contain some intervals. On the other hand, if $p \leq 1/M$ this cannot happen. Namely, Falconer [5] proved that in this case the one-dimensional Hausdorff measure of E is almost surely zero.

The paper is organized as follows. In §2 we give precise definitions of the objects we study; we also formulate our main results. In §3 we explain the importance of statistical

self-similarity. Section 4 contains the proof of Theorem 2. In §5 we add one more idea that lets us upgrade this argument, yielding the proof of Theorem 3. Finally, in §6 we formulate the most general form of our results, Theorem 14, and Theorem 4 follows as a special case.

2. Notation and results

2.1. Mandelbrot percolation. First we provide a definition of the random Cantor set E (we will call it the fractal percolation) which is the object of interest of this paper. Given

$$M \geq 2 \quad \text{and} \quad p_{i,j} \in [0, 1] \quad \text{for every } i, j \in \{0, \dots, M - 1\},$$

we partition the unit square $K = [0, 1]^2$ into M^2 congruent squares of side length $1/M$,

$$K = \bigcup_{i,j=0}^{M-1} K_{i,j} \quad \text{where } K_{i,j} := \left[\frac{i}{M}, \frac{i+1}{M} \right] \times \left[\frac{j}{M}, \frac{j+1}{M} \right].$$

In the first step, we retain the square $K_{i,j}$ with probability $p_{i,j}$ and we discard $K_{i,j}$ with probability $1 - p_{i,j}$ for every $(i, j) \in \{0, \dots, M - 1\}^2$ independently. The union of squares retained is denoted E_1 . Within each square $K_{i,j} \subset E_1$ we repeat the process described above independently. The retained squares of side length $1/M^2$ are called level two squares and their union is called E_2 . Similarly, for every n we construct the set E_n . The object of interest in this paper is the random set $E := \bigcap_{n=1}^{\infty} E_n$.

More formally, let \mathcal{T}_n be the partition of K into M -adic squares of level n . For each square $L \in \mathcal{T}_n$ we can find two sequences $\{i_1, \dots, i_n\}, \{j_1, \dots, j_n\} \in \{0, \dots, M - 1\}^n$ such that

$$L = \left[\sum_{l=1}^n i_l \cdot M^{-l}, \sum_{l=1}^n i_l \cdot M^{-l} + M^{-n} \right] \times \left[\sum_{l=1}^n j_l \cdot M^{-l}, \sum_{l=1}^n j_l \cdot M^{-l} + M^{-n} \right].$$

We will denote such a square by $K_{\underline{i}_n, \underline{j}_n}$, where

$$\underline{i}_n := (i_1, \dots, i_n), \quad \underline{j}_n := (j_1, \dots, j_n) \in \{0, \dots, M - 1\}^n.$$

Clearly, $K_{\underline{i}_{n+1}, \underline{j}_{n+1}} \subset K'_{\underline{i}'_n, \underline{j}'_n}$ if and only if

$$i_k = i'_k, \quad j_k = j'_k \quad \text{for all } k = 1, \dots, n.$$

We define $\mathcal{E}_0 = \mathcal{T}_0 = (\emptyset, \emptyset)$ and then we inductively construct a random family $\{\mathcal{E}_n\}$, $\mathcal{E}_n \subset \mathcal{T}_n$. That is, if $(\underline{i}_n; \underline{j}_n) \notin \mathcal{E}_n$ then $(i_1, \dots, i_n, i; j_1, \dots, j_n, j) \notin \mathcal{E}_{n+1}$ for all $i, j \in \{0, \dots, M - 1\}$ and if $(\underline{i}_n; \underline{j}_n) \in \mathcal{E}_n$ then $(i_1, \dots, i_n, i; j_1, \dots, j_n, j) \in \mathcal{E}_{n+1}$ with probability $p_{i,j}$. Those events are jointly independent.

We denote

$$E_n = \bigcup_{(\underline{i}_n; \underline{j}_n) \in \mathcal{E}_n} K_{\underline{i}_n, \underline{j}_n}$$

and

$$E = \bigcap_{n=1}^{\infty} E_n.$$

The sequence $\{E_n\}$ is a decreasing sequence of compact sets, hence E is non-empty if and only if all E_n are non-empty. It follows easily from the general theory of branching processes (see, for example, [1, Theorem 1]) that

$$E \neq \emptyset \text{ with positive probability if and only if } \sum_{0 \leq i, j \leq M-1} p_{i,j} > 1.$$

We will always assume

$$\sum_{i,j=0}^{M-1} p_{i,j} > M$$

and our results will be conditioned on E being non-empty. It was proved by several authors (Peyrière [17], Hawkes [9], Falconer [5], Mauldin and Williams [13] and Graf [8]) that

$$\text{if } E \neq \emptyset \text{ then } \dim_{\text{H}}(E) = \frac{\log(\sum_{i,j=0}^{M-1} p_{i,j})}{\log M} \text{ almost surely.}$$

In particular, under our assumptions $\dim_{\text{H}} E > 1$ (provided E is non-empty).

The proof of this statement involves proving the following fact.

FACT 1. *The following assertion holds almost surely: if $E(\omega) \neq \emptyset$ then*

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log \#\mathcal{E}_n(\omega) \rightarrow \log \sum_{i,j=0}^{M-1} p_{ij}.$$

2.2. Projections. The object of our study is the existence of intervals in different kinds of projections of E . The nature of projections of angles 0 or $\pi/2$ is conspicuously different and these cases were already treated by Falconer and Grimmett in [6, 7]. So, we mostly restrict our attention to the domain of angles

$$\mathfrak{D} := (0, \pi/2) \cup (\pi/2, \pi).$$

It will be convenient for us to use a special form of projections. Instead of the ‘usual’ orthogonal projection proj_α onto some line we will use the projection Π_α , the codomain of which is one of the diagonals of K . If $\alpha \in (0, \pi/2)$ (i.e. if the projection is in the upper left–lower right direction) we will use the non-orthogonal projection in direction α onto the interval $([0, 0], [1, 1])$. Otherwise, if $\alpha \in (\pi/2, \pi)$ and the projection is in the upper right–lower left direction, we will project onto the interval $([0, 1], [1, 0])$. Naturally, $\text{proj}_\alpha(E)$ contains an interval if and only if $\Pi_\alpha(E)$ does (see Figure 2).

We are going to consider nonlinear projections of E as well. Given $t \in \mathbb{R}^2$, the radial projection with centre t of the set E is denoted by $\text{Proj}_t(E)$ and is defined as the set of angles under which points of $E \setminus \{t\}$ are visible from t . Given $t \in \mathbb{R}^2$, the co-radial projection with centre t of a set E is denoted by $\text{CProj}_t(E)$ and is defined as the set of distances between t and points from E . Figure 2 explains why we consider this object a projection.

As in the case of orthogonal projections, we will consider auxiliary formulations. If the point t is in ‘diagonal’ direction from K (i.e. if both X and Y coordinates of t are outside $[0, 1]$) then instead of Proj_t with codomain S^1 and CProj_t with codomain \mathbb{R}_+ we

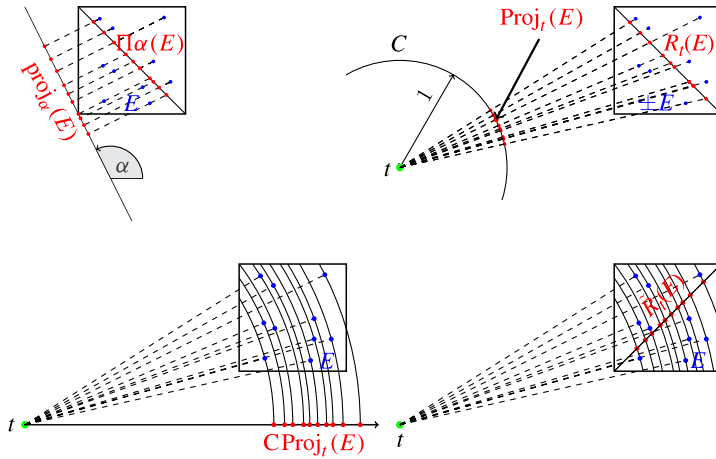


FIGURE 2. The orthogonal proj_α , radial Proj_t , co-radial CProj_t projections and the auxiliary projections Π_α , R_t , and \tilde{R}_t .

can consider R_t and \tilde{R}_t , whose codomains are diagonals of K . For example, as shown in Figure 2, if t is in lower left direction from K (both coordinates of t are negative) then the codomain of R_t is $([0, 1], [1, 0])$ and the codomain of \tilde{R}_t is $([0, 0], [1, 1])$. Once again, $R_t(E)$ contains an interval if and only if $\text{Proj}_t(E)$ does, and similarly for $\tilde{R}_t(E)$ and $\text{CProj}_t(E)$.

There is a more general notion of a family of almost linear projections we are going to use, but it is more complicated. The definition will be given in the last section.

2.3. *Results.* Let us start from a direct generalization of [6, 7]. Let $\alpha \in \mathcal{D}$. In the fourth section we will define condition $A(\alpha)$ on the set of probabilities $\{p_{i,j}\}$; at the moment it is enough to know that if all $p_{i,j} > M^{-1}$ then $A(\alpha)$ is satisfied for all $\alpha \in \mathcal{D}$.

THEOREM 2. *Let $\alpha \in \mathcal{D}$. If $A(\alpha)$ holds and E is non-empty then almost surely $\text{proj}_\alpha(E)$ contains an interval.*

Our next, stronger, result lets us consider projections in all directions at once.

THEOREM 3. *Assume that $A(\alpha)$ holds for all $\alpha \in \mathcal{D}$ and that $E \neq \emptyset$. To handle the horizontal and vertical projections, we also assume that*

$$\text{for all } i, j \in \{0, \dots, M - 1\}, \quad \sum_{l=0}^{M-1} p_{i,l} > 1 \quad \text{and} \quad \sum_{k=0}^{M-1} p_{k,j} > 1.$$

Then, almost surely $\text{proj}_\alpha(E)$ contains an interval for all $\alpha \in S^1$.

Finally, let us consider nonlinear projections.

THEOREM 4. *Assume that $A(\alpha)$ holds for all $\alpha \in \mathcal{D}$ and that $E \neq \emptyset$. Then, almost surely both $\text{Proj}_t(E)$ and $\text{CProj}_t(E)$ contain an interval for all $t \in \mathbb{R}^2$.*

3. Statistical self-similarity

The goal of this section is to explain two simple ideas, explaining why the statistical self-similarity of the construction of E simplifies our task.

Let φ_{i_n, j_n} be the natural contraction sending K onto K_{i_n, j_n} . That is,

$$\varphi_{i_n, j_n}(x, y) = \frac{1}{M^n} \cdot (x, y) + t_{i_n, j_n},$$

where t_{i_n, j_n} is the lower left corner of K_{i_n, j_n} . Then, by the *statistical self-similarity* of E we obtain the following fact: for any $K_{i_n, j_n} \in \mathcal{T}_n$ the conditional distribution of $E \cap K_{i_n, j_n}$ conditioned on $(i_n; j_n) \in \mathcal{E}_n$ is the same as the distribution of $\varphi_{i_n, j_n}(E)$.

The first idea, already used in [6, 7], is as follows. Let E be a non-empty realization of the fractal percolation. Almost surely, E has infinitely many points, hence we can find an infinite sequence of numbers n_k and squares $K_{i_{n_k}, j_{n_k}} \subset E_{n_k}$ such that any two squares $K_{i_{n_k}, j_{n_k}}$ are not contained in each other. Fix α . The probability that $\text{proj}_\alpha(E \cap K_{i_{n_k}, j_{n_k}})$ contains an interval is the same for each k (and the same as the probability that $\text{proj}_\alpha(E)$ contains an interval) and those are independent events. Hence, it is enough to prove that $\text{proj}_\alpha(E)$ contains an interval with positive probability to know that it contains an interval with probability 1 (conditioned on E being non-empty).

The second idea is quite similar. Let $t \in \mathbb{R}^2$ and consider the radial projection with centre t (for co-radial projections it works much the same). Once again, if E is non-empty then we can almost surely find a square K_{i_l, j_l} with non-empty intersection with E and which t does not belong to and is in diagonal direction from E (almost surely is not contained in a horizontal or vertical line). We can then construct the family $K_{i_{n_k}, j_{n_k}}$ of subsets of K_{i_l, j_l} such that the size of each $K_{i_{n_k}, j_{n_k}}$ is very small compared to its distance from t (we just need to take them sufficiently small). Note that not only is t in diagonal direction from each $K_{i_{n_k}, j_{n_k}}$, but the direction is actually bounded away from the horizontal and vertical.

The probability that $\text{Proj}_t(E \cap K_{i_{n_k}, j_{n_k}})$ contains an interval is the same as the probability that $\text{Proj}_{\varphi_{i_{n_k}, j_{n_k}}^{-1}(t)}(E)$ contains an interval. Hence, to prove that $\text{Proj}_t(E)$ almost surely contains an interval, it is enough to prove that the probability that $\text{Proj}_{t'}(E)$ contains an interval is uniformly bounded away from zero for t' far away from K and in direction bounded away from the horizontal and vertical.

It is a natural observation that the radial/co-radial projections with centre sufficiently far away do not differ much from linear projections. Indeed, this is how this idea will be used in the proof of Theorem 4 in the last section.

4. Proof of Theorem 2

4.1. *Ideas.* As our main idea comes from a paper of Falconer and Grimmett [6, 7], let us start by recalling their proof. We will assume the simplest case: all the probabilities are equal to $p > M^{-1}$. We want to prove that the probability that the vertical projection of the percolation fractal is the whole interval $[0, 1]$ is positive. For any $n > 0$ let us divide $[0, 1]$ into intervals of length M^{-n} and let us code them by the usual M -adic codes. Over each interval $C(i_1, \dots, i_n)$ there is a whole column of M^n M -adic squares of level n ,

and $C(i_1, \dots, i_n)$ is contained in the vertical projection of E_n if and only if at least one of those squares belongs to \mathcal{E}_n . Denoting by $A_n(i_1, \dots, i_n)$ the number of squares above $C(i_1, \dots, i_n)$ contained in \mathcal{E}_n , we need to prove that with positive probability all $A_n(i_1, \dots, i_n)$ (for all possible sequences \underline{i}_n) are positive.

Note that

$$\mathbb{E}(A_{n+1}(i_1, \dots, i_n, j) | A_n(i_1, \dots, i_n) = a) = Mpa. \tag{4.1}$$

Choose any $\gamma \in (1, Mp)$ and let $G_n(i_1, \dots, i_n)$ be the event that

$$A_{n+1}(i_1, \dots, i_n, j) > \gamma A_n(i_1, \dots, i_n)$$

for all $j = 0, 1, \dots, M - 1$. By large deviation estimations,

$$1 - P(G_n(i_1, \dots, i_n)) \approx \tau^{A_n(i_1, \dots, i_n)}$$

for some $\tau < 1$. Hence, if all the events $G_1(i_1), \dots, G_{n-1}(i_1, \dots, i_{n-1})$ hold then $A_n(i_1, \dots, i_n) \geq \gamma^n$ and so

$$P(G_n(i_1, \dots, i_n) | G_1(i_1) \wedge \dots \wedge G_{n-1}(i_1, \dots, i_{n-1})) > 1 - c\tau^{\gamma^n}.$$

Hence, at level n we have to check an exponentially big number of events (precisely, M^n of them) but each of those events is superexponentially certain to happen. It follows that with positive probability all those events will happen.

Our goal in this section is a more complicated statement: for the same kind of percolation fractal we fix a direction α (neither horizontal nor vertical) and we want to check that the projection of the fractal in this direction contains an interval with positive probability. Equation (4.1) does not hold: even if a point belongs to a projection of some n th level square, it does not imply that the expected number of $n + 1$ -st level squares in the approximation of the percolation fractal such that their projections contain the point is greater than 1. More precisely, if the point belongs to the projection of the ‘central’ part of the square then everything might work, but not for the points very close to the ends of the projection interval.

To get around this technical problem, we only count the number of ‘central’ parts of projections of n th level squares that a given point belongs to. This lets us replace (4.1) by Condition $A(\alpha)$ as our main working tool. Note that if we check that a sufficiently dense set of points belongs to ‘central’ parts of projections of some squares from the n th approximation of the fractal, the whole projections will cover everything. We only need to take care that the number of points needed at step n grows at most exponentially fast with n and then Falconer and Grimmett’s argument will go through.

4.2. *Condition A.* Time to give the details. We fix $\alpha \in \mathcal{D}$. We are going to consider Π_α instead of proj_α , i.e. we are projecting onto a diagonal Δ_α of K . For any $(\underline{i}_n, \underline{j}_n)$ the map $\Pi_\alpha \circ \varphi_{\underline{i}_n, \underline{j}_n} : \Delta_\alpha \rightarrow \Delta_\alpha$ is a linear contraction of ratio M^{-n} . We will use its inverse: a map $\psi_{\alpha, \underline{i}_n, \underline{j}_n} : \Pi_\alpha(K_{\underline{i}_n, \underline{j}_n}) \rightarrow \Delta_\alpha$. It is a linear expanding map (of ratio M^n) and it is onto.

Consider the class of non-negative real functions on Δ_α , vanishing on the endpoints. There is a natural random inverse Markov operator G_α defined as

$$G_\alpha f(x) = \sum_{(i,j) \in \mathcal{E}_1; x \in \Pi_\alpha(K_{i,j})} f \circ \psi_{\alpha, i, j}(x).$$

The corresponding operator on the n th level is

$$G_\alpha^{(n)} f(x) = \sum_{(\underline{i}_n, \underline{j}_n) \in \mathcal{E}_n; x \in \Pi_\alpha(K_{\underline{i}_n, \underline{j}_n})} f \circ \psi_{\alpha, \underline{i}_n, \underline{j}_n}(x).$$

In particular, for any $H \subset \Delta^\alpha$ we have

$$G_\alpha^{(n)} \mathbb{1}_H(x) = \#\{(\underline{i}_n, \underline{j}_n) \in \mathcal{E}_n : x \in \Pi_\alpha(\varphi_{\underline{i}_n, \underline{j}_n}(H))\}.$$

Although $G_\alpha^{(n)}$ should not be thought of as the n th iterate of G_α , the expected value of $G_\alpha^{(n)}$ is the n th iterate of the expected value of G_α . Namely, let

$$F_\alpha = \mathbb{E}[G_\alpha] \quad \text{and} \quad F_\alpha^n = \mathbb{E}[G_\alpha^n].$$

We then have the formulas

$$F_\alpha f(x) = \sum_{(i, j); x \in \Pi_\alpha(K_{i, j})} p_{i, j} \cdot f \circ \psi_{\alpha, i, j}(x)$$

and

$$F_\alpha^n f(x) = \sum_{(\underline{i}_n, \underline{j}_n); x \in \Pi_\alpha(K_{\underline{i}_n, \underline{j}_n})} p_{\underline{i}_n, \underline{j}_n} \cdot f \circ \psi_{\alpha, \underline{i}_n, \underline{j}_n}(x),$$

where

$$p_{\underline{i}_n, \underline{j}_n} = \prod_{k=1}^n p_{i_k, j_k}.$$

Hence, F_α^n is indeed the n th iteration of F_α (which explains why we are allowed to use this notation).

Definition 5. We say the percolation model satisfies *Condition A*(α) if there exist closed intervals $I_1^\alpha, I_2^\alpha \subset \Delta_\alpha$ and a positive integer r_α such that:

- (i) $I_1^\alpha \subset \text{int } I_2^\alpha, I_2^\alpha \subset \text{int } \Delta_\alpha$;
- (ii) $F_\alpha^{r_\alpha} \mathbb{1}_{I_1^\alpha} \geq 2 \mathbb{1}_{I_2^\alpha}$.

It will be convenient to use additional notation. For $x \in \Delta_\alpha, \alpha \in \mathcal{D}$, and $I \subset \Delta_\alpha$ we denote

$$D_n(x, I, \alpha) = \{(\underline{i}_n, \underline{j}_n); x \in \Pi_\alpha \circ \varphi_{\underline{i}_n, \underline{j}_n}(I)\}.$$

That is, if we write $\ell^\alpha(x)$ for the line segment through $x \in \Delta_\alpha$ in direction α , $D_n(x, I, \alpha)$ is the set $(\underline{i}_n, \underline{j}_n)$ for which $\ell^\alpha(x)$ intersects $\varphi_{\underline{i}_n, \underline{j}_n}(I)$.

Point (ii) of Definition 5 can then be written as

$$\text{for all } x \in I_2^\alpha \quad \sum_{(\underline{i}_{r_\alpha}, \underline{j}_{r_\alpha}) \in D_{r_\alpha}(x, I_1^\alpha, \alpha)} p_{\underline{i}_{r_\alpha}, \underline{j}_{r_\alpha}} \geq 2.$$

The heuristic explanation of condition $A(\alpha)$ is as follows: if $(\underline{i}_n, \underline{j}_n) \in \mathcal{E}_n \cap D_n(x, I_2^\alpha, \alpha)$ then the expected number of $(\tilde{\underline{i}}_{n+r}, \tilde{\underline{j}}_{n+r})$ such that $K_{\tilde{\underline{i}}_{n+r}, \tilde{\underline{j}}_{n+r}} \subset K_{\underline{i}_n, \underline{j}_n}$ and $(\tilde{\underline{i}}_{n+r}, \tilde{\underline{j}}_{n+r}) \in \mathcal{E}_{n+r} \cap D_{n+r}(x, I_1^\alpha, \alpha)$ is at least 2. See Figure 3.

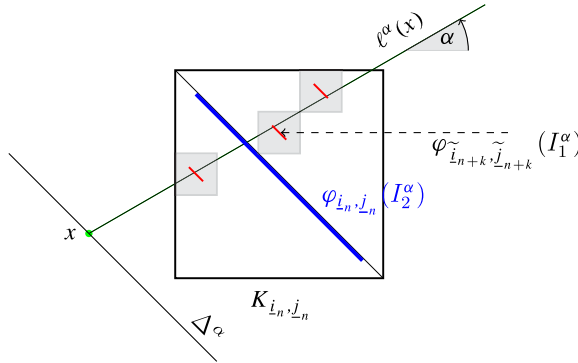


FIGURE 3. Condition A(α).

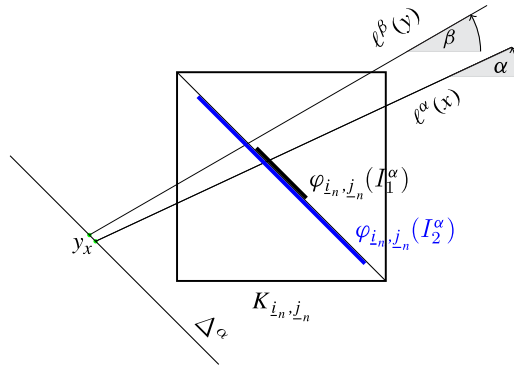


FIGURE 4. Robustness of Condition A(α).

4.3. *Robustness.* In this subsection we will explain a very simple geometric idea that we will use constantly in the last three sections.

Consider two parallel lines l_1, l_2 . On l_1 we have an interval I . Let J be the image of I under linear projection onto l_2 in direction θ . Let I' be a greater interval on l_1 , containing I together with some neighbourhood. Then not only will the projection of I' onto l_2 in direction θ contain J , but also if we perturb θ sufficiently slightly, the resulting projection of I' will still contain J . Applying to our situation, whenever $(i_n, j_n) \in D_n(x, I_1^\alpha, \alpha)$ we will have $(i_n, j_n) \in D_n(y, I_2^\alpha, \beta)$ for all y sufficiently close to x and β sufficiently close to α .

The first application of this is to prove the robustness of Condition A(α).

PROPOSITION 6. *If Condition A(α) holds for some $\alpha \in \mathcal{D}$ for some I_1^α, I_2^α and r_α then it will also hold in some neighbourhood $J \ni \alpha$. Moreover, for all $\theta \in J$ we can choose $I_1^\theta = I_1', I_2^\theta = I_2', r_\theta = r_\alpha$ not depending on θ .*

Proof. Let δ be the Hausdorff distance between I_1^α and I_2^α , i.e. the greatest number for which a δ -neighbourhood of I_1^α is still contained in I_2^α . Let I_1 be a $\delta/2$ -neighbourhood of I_1^α .

A simple geometric observation of robustness type is that if $|\alpha - \theta| < \delta M^r/3$ then

$$\Pi_\alpha \circ \varphi_{\underline{l}_r, \underline{j}_r}(I_1^\alpha) \subset \Pi_\theta \circ \varphi_{\underline{l}_r, \underline{j}_r}(I_1).$$

Hence, Condition A(α) holds for all $\theta \in [\alpha - \delta M^r/3, \alpha + \delta M^r/3]$ for intervals I_1, I_2 and positive integer r . □

A natural corollary is that the whole range \mathcal{D} can be presented as a countable union of closed intervals $J_i = [\alpha_i^-, \alpha_i^+]$ such that Condition A(α) holds for all $\alpha \in J_i$ with the same I_1^i, I_2^i, r_i . To prove Theorem 3 (in the next section) we only need to prove that for almost all E and for any i , almost surely all the sets $\Pi_\alpha(E), \alpha \in J_i$ contain intervals (the horizontal and vertical directions follow from Falconer and Grimmett [6, 7]).

4.4. *The proof.* We assume in this section that Condition A(α) holds with given I_1, I_2 and r (α is fixed, so we suppress the index α). We will prove that there is a positive probability that $\Pi_\alpha(E) \supset I_1$.

For any $x \in \Delta_\alpha$, let us define a sequence of random variables

$$V_n(x) = \#\{(\underline{l}_{nr}, \underline{j}_{nr}) \in \mathcal{E}_{nr} \cap D_{nr}(x, I_1, \alpha)\}.$$

For any n , let us define a finite set $X_n \subset I_1$ with the following properties:

- (i) X_n contains the endpoints of I_1 ;
- (ii) when we number the points of X_n in an increasing direction as x_0, \dots, x_N (with x_0, x_N being the endpoints of I_1) then whenever $(\underline{l}_{nr}, \underline{j}_{nr}) \in D_{nr}(x_i, I_1, \alpha)$, it will follow that for all $y \in [x_{i-1}, x_{i+1}]$, $(\underline{l}_{nr}, \underline{j}_{nr}) \in D_{nr}(y, I_2, \alpha)$;
- (iii) $\#X_n \leq cM^{nr}$.

To have property (ii) satisfied, it is enough to choose X_n as points in regular distances δM^{-nr} from each other, where δ is sufficiently small that the δ -neighbourhood of I_1 is still contained in I_2 . Hence, the constructed X_n will satisfy (iii) as well.

We will prove that there is a positive probability that for all $n \in \mathbb{N}$, for all $x \in X_n$ we have $V_n(x) \geq (3/2)^n$. Note that this will imply the assertion: when all the points from X_n are contained in some $\Pi_\alpha \circ \varphi_{\underline{l}_{nr}, \underline{j}_{nr}}(I_1), (\underline{l}_{nr}, \underline{j}_{nr}) \in \mathcal{E}_{nr}$, (ii) will imply that the whole of I_1 will be contained in the union of the corresponding $\Pi_\alpha \circ \varphi_{\underline{l}_{nr}, \underline{j}_{nr}}(I_2)$ and in particular in the union of the corresponding $\Pi_\alpha \circ K_{\underline{l}_{nr}, \underline{j}_{nr}}$.

For $n = 0$ the statement holds with probability 1. Assume that up to time n it holds with probability P_n and let us estimate the conditional probability with which it holds at time $n + 1$, conditioned on the assumption it holds at time n . Let $x \in X_{n+1}$.

(1) The point x does not need to belong to X_n . However, even if it does not, it is contained in some $[x_i, x_{i+1}]$ for $x_i, x_{i+1} \in X_n$. As we assume that $V_n(x_i) \geq (3/2)^n$, we know that the number of pairs $(\underline{l}_{nr}, \underline{j}_{nr}) \in \mathcal{E}_{nr} \cap D_{nr}(x_i, I_1, \alpha)$ is at least $(3/2)^n$. By part (ii) of the definition of X_n , all those $(\underline{l}_{nr}, \underline{j}_{nr})$ belong to $\mathcal{E}_{nr} \cap D_{nr}(x, I_2, \alpha)$ as well.

(2) For each square $K_{\underline{l}_{nr}, \underline{j}_{nr}}, (\underline{l}_{nr}, \underline{j}_{nr}) \in \mathcal{E}_{nr} \cap D_{nr}(x, I_2, \alpha)$, we want to calculate the number of its subsquares $K_{\underline{l}_{(n+1)r}, \underline{j}_{(n+1)r}}, (\underline{l}_{(n+1)r}, \underline{j}_{(n+1)r}) \in \mathcal{E}_{(n+1)r} \cap D_{nr}(x, I_1, \alpha)$. This

random number is given by

$$G_\alpha^{(r)} \mathbb{1}_{I_1}(\psi_{i_{nr}, j_{nr}}(x)).$$

We do not know exactly the distribution of this random variable (it depends on x). But the possible values are obviously between 0 and $2M^r$ and the expected value is not smaller than

$$F_\alpha^r \mathbb{1}_{I_1}(\psi_{i_{nr}, j_{nr}}(x)) \geq 2$$

(by Condition $A(\alpha)$ and using the fact that $\psi_{i_{(n+1)r}, j_{(n+1)r}}(x) \in I_2$).

(3) Events that happen in different squares $K_{i_{nr}, j_{nr}}$ are jointly independent.

(4) Hence, $V_{n+1}(x)$ is bounded from below by a sum of at least $(3/2)^n$ independent random variables, each with average 2 and each bounded above and below by uniform constants. Hence, by the Azuma–Hoeffding inequality [10], the probability that this sum is strictly smaller than $(3/2)^{n+1}$ is not greater than $\gamma^{(3/2)^n}$ for some fixed $\gamma \in (0, 1)$.

What we said implies that

$$P(\forall_{x \in X_{n+1}} V_{n+1}(x) \geq (3/2)^{n+1} \mid \forall_{y \in X_n} V_n(y) \geq (3/2)^n) \geq (1 - \gamma^{(3/2)^n})^{cM^{(n+1)r}}.$$

As the infinite sum $\sum_n cM^{(n+1)r} \gamma^{(3/2)^n}$ is convergent, we get

$$P(\forall_n \forall_{x \in X_n} V_n(x) \geq (3/2)^n) > 0.$$

We are done.

4.5. *Examples.* Condition $A(\alpha)$ looks artificial, hence we should show some examples. The main goal of this subsection is to show that if all probabilities $p_{i,j} = p > M^{-1}$ then $A(\alpha)$ holds for all $\alpha \in \mathcal{D}$ (Proposition 10), but we also mention some examples with different probabilities. Our main tool will be the following.

Definition 7. We say that the fractal percolation model satisfies *Condition $B(\alpha)$* if there exists a non-negative continuous function $f : \Delta_\alpha \rightarrow \mathbb{R}$ such that f is strictly positive except at the endpoints of Δ_α and that

$$F_\alpha f \geq (1 + \varepsilon)f \tag{4.2}$$

for some $\varepsilon > 0$.

First we prove the following lemma.

LEMMA 8. *Assume that Condition $B(\alpha)$ holds for some f and $\varepsilon > 0$. Then we can choose non-empty closed intervals*

$$I_1 \subset \text{int } I_2 \quad \text{and} \quad I_2 \subset \text{int } \Delta,$$

such that for

$$g_1 = f|_{I_1}, \quad g_2 = f|_{I_2}$$

we have

$$F_\alpha g_1(x) \geq \left(1 + \frac{\varepsilon}{2}\right) \cdot g_2(x) \quad \text{for } x \in I_2. \tag{4.3}$$

Proof. For a set $H \subset \Delta_\alpha$, put $B_r(H)$ for the radius r open neighbourhood of H in Δ_α ,

$$B_r(H) := \{y \in \Delta_\alpha : \exists h \in H, |h - y| < r\}.$$

Let $W \subset \Delta_\alpha$ be the Π_α -projection of the mesh $1/M$ grid points in K ,

$$W = \left\{ x \in \Delta : \exists 0 \leq i, j \leq M, x = \Pi_\alpha \left(\frac{i}{M}, \frac{j}{M} \right) \right\}.$$

We partition W into the two endpoints of Δ (to be denoted W_0) and $W_1 := W \setminus W_0$. Fix $\eta > 0$ which satisfies

$$\frac{\varepsilon}{2} \cdot \min_{x \in B_{\eta/M}(W_1)} f(x) > (M + 1)^2 \sup_x \{f(x) : x \in B_{\eta/M}(W_0)\}$$

and define two subintervals of Δ_α ,

$$I_1 := \Delta_\alpha \setminus B_\eta(W_0) \quad \text{and} \quad I_2 := \Delta_\alpha \setminus B_{\eta/M}(W_0).$$

Let

$$B = B_{\eta/M}(W) \quad \text{and} \quad B_i = B_{\eta/M}(W_i), \quad i = 0, 1.$$

Fix an arbitrary $x \in I_2$. We divide the proof of (4.3) into two cases, of which the first is obvious.

$x \in \Delta \setminus B$: Using the definition of F_α and then (4.2) we obtain

$$F_\alpha g_1(x) = F_\alpha f(x) \geq (1 + \varepsilon)f(x) \geq \left(1 + \frac{\varepsilon}{2}\right) \cdot g_2(x).$$

$x \in B_1$: By the definition of F_α ,

$$F_\alpha g_1(x) \geq F_\alpha f - (M + 1)^2 \|f - \tilde{g}_1\|_\infty \quad \text{for all } x \in \Delta.$$

From this and from (4.2), we obtain

$$F_\alpha g_1(x) \geq \left(1 + \frac{\varepsilon}{2}\right) f(x) + \left(\frac{\varepsilon}{2} f(x) - (M + 1)^2 \|f - \tilde{g}_1\|_\infty\right).$$

The definition of η yields that the expression in the second bracket is positive. This implies that

$$F_\alpha g_1(x) > \left(1 + \frac{\varepsilon}{2}\right) g_2(x) \quad \text{for } x \in \Delta_2. \quad \square$$

PROPOSITION 9. *Condition $B(\alpha)$ implies Condition $A(\alpha)$.*

Proof. Using the notation of Lemma 8 we define r as the smallest integer satisfying

$$\left(1 + \frac{\varepsilon}{2}\right)^r \geq 2 \cdot \frac{\max_{x \in I_1} g_1(x)}{\min_{x \in I_2} g_2(x)}.$$

Then clearly,

$$F_\alpha^r \mathbb{1}_{I_1}(x) \geq 2 \cdot \mathbb{1}_{I_2}(x) \quad \text{for all } x \in I_2. \quad \square$$

PROPOSITION 10. *If*

$$\text{for all } i, j \quad p_{ij} = p > \frac{1}{M}$$

then Condition $A(\alpha)$ is satisfied for all $\alpha \in \mathcal{D}$.

Proof. We will actually prove $B(\alpha)$. Fix $\alpha \in \mathcal{D}$. For an arbitrary $x \in \Delta^\alpha$ we define $f_\alpha(x) := |\ell^\alpha(x) \cap K|$. It is straightforward that f_α satisfies (4.2) with $\varepsilon = M \cdot p - 1 > 0$. \square

Let us now give some examples of percolations with not all probabilities equal and still satisfying Condition $A(\alpha)$. There is a large class of trivial examples given by the following lemma.

LEMMA 11. *If the percolation $\{p_{i,j}\}$ satisfies Condition $A(\alpha)$ and $p'_{i,j} \geq p_{i,j}$ for all i, j then the percolation $\{p'_{i,j}\}$ satisfies Condition $A(\alpha)$ as well.*

So, non-trivial examples should have at least some $p_{i,j} \leq M^{-1}$. A natural class of examples is motivated by the work of Dekking and Meester [3] and by the question of the anonymous referee.

LEMMA 12. *Let $M = 3$. Let $p_{1,1} = p_0$ and let all the other $p_{i,j} = p$. Then if*

$$p > \max\left(\frac{1}{3}, \frac{1 - p_0}{2}\right)$$

then Condition $A(\alpha)$ is satisfied for all $\alpha \in \mathcal{D}$.

Proof. One can check that Condition $B(\alpha)$ is satisfied for the same function f_α as in the proof of Proposition 10. \square

In the case $p_0 = 0$ we get the random Sierpiński carpet and Condition A is satisfied if $p > 1/2$. Note that the bounds in Lemma 12 are sharp: for $p_0 \leq 1/3$ and $p \leq (1 - p_0)/2$ the horizontal and vertical projections of E almost surely contain no intervals, by Falconer and Grimmett [6, 7].

5. *Projections in many directions, proof of Theorem 3*

We restrict ourselves to one such range $J = [\alpha_-, \alpha_+]$. Let I_1, I_2 and r be such that Condition $A(\alpha)$ holds for all $\alpha \in J$. Let δ be the Hausdorff distance between I_1 and I_2 .

Another simple robustness-related geometric observation: assume $x, y \in \Delta_\alpha$ and the distance between them is at most $\delta M^{-nr}/3$. Assume $\alpha, \beta \in J$ and $|\alpha - \beta| \leq \delta M^{-nr}/3$. Assume that $(\underline{i}_{nr}, \underline{j}_{nr}) \in D_{nr}(x, I_1, \alpha)$. Then $(\underline{i}_{nr}, \underline{j}_{nr}) \in D_{nr}(y, I_2, \beta)$. We can write this as

$$G_\beta^{(r)} \mathbb{1}_{I_2}(\psi_{\underline{i}_{nr}, \underline{j}_{nr}}(y)) \geq G_\alpha^{(r)} \mathbb{1}_{I_1}(\psi_{\underline{i}_{nr}, \underline{j}_{nr}}(x)). \tag{5.1}$$

We are now starting the proof. Compare this to the proof of Theorem 2. Given n , let X_n be a $\delta M^{-nr}/3$ -dense finite subset of I_1 and let Y_n be a $\delta M^{-nr}/3$ -dense finite subset of J . We choose them in such a way that

$$\#(X_n \times Y_n) \leq cM^{2nr}.$$

For any $(x, \theta) \in I_1 \times J$, let us define a sequence of random variables

$$V_n(x, \theta) = \#\{(\underline{i}_{nr}, \underline{j}_{nr}) \in \mathcal{E}_{nr} \cap D_{nr}(x, I_1, \theta)\}.$$

We will prove that with positive probability $V_n(x, \theta) \geq (3/2)^n$ for all n, x, θ , estimating inductively the probability that this event holds up to time $(n + 1)$ conditioned on the

assumption that it holds at time n . For $n = 0$ this event holds with probability 1. Let us start the inductive step.

(1) Given $(y, \kappa) \in X_{n+1} \times Y_{n+1}$, let $Z(y, \kappa)$ be the set of points from $I_1 \times J$ such that x is $\delta M^{-(n+1)r}/3$ -close to y and θ is $\delta M^{-(n+1)r}/3$ -close to κ . The sets $Z(y, \kappa)$ cover $I_1 \times J$.

By the inductive assumption, $V_n(y, \kappa) \geq (3/2)^n$. Hence, we know that there are at least $(3/2)^n$ pairs $(\underline{i}_{nr}, \underline{j}_{nr}) \in \mathcal{E}_{nr} \cap D_{nr}(y, I_2, \kappa)$.

(2) For each square $K_{\underline{i}_{nr}, \underline{j}_{nr}}$ such that $(\underline{i}_{nr}, \underline{j}_{nr}) \in \mathcal{E}_{nr} \cap D_{nr}(x, I_1, \theta)$, we want to calculate the number of its subsquares $K_{\underline{i}_{(n+1)r}, \underline{j}_{(n+1)r}}$ such that $(\underline{i}_{(n+1)r}, \underline{j}_{(n+1)r}) \in \mathcal{E}_{(n+1)r} \cap D_{(n+1)r}(x, I_2, \theta)$. This random number is given by $G_\theta^{(r)} \mathbb{1}_{I_2}(\psi_{\underline{i}_{nr}, \underline{j}_{nr}}(x))$ and by (5.1)

$$G_\theta^{(r)} \mathbb{1}_{I_2}(\psi_{\underline{i}_{nr}, \underline{j}_{nr}}(x)) \geq G_\kappa^{(r)} \mathbb{1}_{I_1}(\psi_{\underline{i}_{nr}, \underline{j}_{nr}}(y)). \tag{5.2}$$

As before, this random variable is bounded (independently of n) and its expected value is at least 2. Moreover, those random variables coming from different $(\underline{i}_{(n+1)r}, \underline{j}_{(n+1)r})$ are independent.

(3) An important note: the bound in equation (5.2) works for all $(x, \theta) \in Z(y, \kappa)$. That means that we only need to check the behaviour of this random variable for finitely many pairs (y, κ) to prove the inductive step at all (x, θ) .

(4) By the Azuma–Hoeffding inequality the conditional probability that

$$\sum_{(\underline{i}_{nr}, \underline{j}_{nr}) \in \mathcal{E}_{nr} \cap D_{nr}(y, I_2, \kappa)} G_\kappa^{(r)} \mathbb{1}_{I_1}(\psi_{\underline{i}_{nr}, \underline{j}_{nr}}(y)) < (3/2)^{n+1}$$

conditioned on $V_n(y, \kappa) \geq (3/2)^n$ is not greater than $\gamma^{(3/2)^n}$ for some fixed $\gamma \in (0, 1)$. As the number of possible pairs (y, κ) is at most cM^{2nr} , which is increasing only exponentially fast, we are done.

6. Nonlinear projections, proof of Theorem 4

6.1. *Almost linear projections.* Let us consider carefully what the real assumptions of the proof of Theorem 3 are. Consider a family of projections $S_t : K \rightarrow \Delta$ parametrized by $t \in T$. A convenient way will be to write

$$S_t(x) = \Pi_{\alpha_t(x)}(x) \tag{6.1}$$

for all $x \in K$. What assumptions about α_t would we need for the proof from the previous section to work?

We want to use Condition A. So, our first necessary assumption is that for some range J in which Condition A holds (for some fixed I_1, I_2, r), $\alpha_t(x) \in J$ for all t, x . Let δ be, like before, the Hausdorff distance between I_1 and I_2 .

We also want the following robustness property. For any n we want to be able to divide $I_1 \times T$ into a finite family of subsets $\{X_i \times Z_j\}$ and in each $X_i \times Z_j$ we want to choose a special pair $(x_i, t_j) \in X_i \times Z_j$ such that for any $(x, t) \in X_i \times Z_j$ and for any $\underline{i}_{nr}, \underline{j}_{nr}$,

$$x_i \in S_{t_j} \circ \varphi_{\underline{i}_{nr}, \underline{j}_{nr}}(I_1) \implies x \in \Pi_{\alpha_t(X_{\underline{i}_{nr}, \underline{j}_{nr}})} \circ \varphi_{\underline{i}_{nr}, \underline{j}_{nr}}(I_2),$$

where $X_{\underline{i}_{nr}, \underline{j}_{nr}}$ is the centre of $K_{\underline{i}_{nr}, \underline{j}_{nr}}$. This will let us proceed with the inductive part of the argument.

Finally, we need the size of the family $\{Z_i\}$ to grow only exponentially fast with n , so that we can apply the large deviation argument and the resulting infinite product is convergent.

Definition 13. We say that a family $\{S_t\}_{t \in T} : K \rightarrow \Delta$ is an *almost linear family of projections* if the following properties are satisfied. We use notation from (6.1). We set $J \subset \mathcal{D}$ as the range of angles for which Condition A(α) is satisfied with the same I_1, I_2, r . We denote by δ the Hausdorff distance between I_1 and I_2 .

- (i) We have $\alpha_t(x) \in J$ for all $t \in T$ and $x \in K$. In particular, $\alpha_t(x)$ is contained in one of two components of \mathcal{D} .
- (ii) We have that $\alpha_t(x)$ is a Lipschitz function of x , with the Lipschitz constant not greater than $\delta/3$. This guarantees in particular that $S_t(K_{\underline{i}_n, \underline{j}_n})$ is an interval.
- (iii) For any n we can divide T into subsets $Z_i^{(n)}$ such that whenever $t, s \in Z_i^{(n)}$ and $x, y \in K_{\underline{i}_n, \underline{j}_n}$, we have

$$|\alpha_t(x) - \alpha_s(y)| \leq \delta M^{-n}/3.$$

Moreover, we can do that in such a way that $\#\{Z_i^{(n)}\}$ grows only exponentially fast with n .

Then the proof of Theorem 3 easily yields the following.

THEOREM 14. *Let $\{S_t\}_{t \in T}$ be an almost linear family of projections. Then for almost all non-empty realizations E of the percolation fractal, $S_t(E)$ contains an interval for all $t \in T$.*

Proof. We denote by $V_n(x, t)$ the number of pairs $(\underline{i}_{nr}, \underline{j}_{nr}) \in \mathcal{E}_{nr}$ for which $x \in S_t \circ \varphi_{\underline{i}_{nr}, \underline{j}_{nr}}(I_2)$. We want to prove inductively that (with positive probability) $V_n(x, t) \geq (3/2)^n$ for all $x \in I_1, t \in T$. The statement is obvious for $n = 0$. The inductive step is as follows.

(1) We choose in I_1 a $\delta M^{-(n+1)r}/3$ -dense finite subset X_{n+1} . We can cover $I_1 \times T$ with sets $B_{\delta M^{-(n+1)r}/3}(x_i) \times Z_j^{((n+1)r)}$, $x_i \in X_{n+1}$. The inductive assumption says that for any (y, s) there are at least $(3/2)^n$ pairs $(\underline{i}_{nr}, \underline{j}_{nr}) \in \mathcal{E}_{nr}$ such that $y \in S_s \circ \varphi_{\underline{i}_{nr}, \underline{j}_{nr}}(I_2)$.

(2) For each $K_{\underline{i}_{nr}, \underline{j}_{nr}}, (\underline{i}_{nr}, \underline{j}_{nr})$ as above, we want to estimate from below the number of its subsquares $K_{\underline{i}_{(n+1)r}, \underline{j}_{(n+1)r}}$ such that $y \in S_s \circ \varphi_{\underline{i}_{(n+1)r}, \underline{j}_{(n+1)r}}(I_2)$. For all $(y, s) \in B_{\delta M^{-(n+1)r}/3}(x_i) \times Z_j^{((n+1)r)}$ this random variable can be uniformly estimated from below by

$$G_{\alpha_t(X_{\underline{i}_{nr}, \underline{j}_{nr}})}^{(r)} \mathbb{1}_{I_1}(\psi_{\underline{i}_{nr}, \underline{j}_{nr}}(x_i)),$$

where $t \in Z_j^{((n+1)r)}$ is arbitrary.

(3) As we approximate the almost linear projection by a linear one, we can apply Condition A($\alpha_t(X_{\underline{i}_{nr}, \underline{j}_{nr}})$).

(4) As the number of sets $B_{\delta M^{-(n+1)r}/3}(x_i) \times Z_j^{((n+1)r)}$ grows only exponentially fast with n , we finish the proof using the Azuma–Hoeffding inequality, like before. \square

6.2. *Radial and co-radial projections.* Families of radial and co-radial projections are not in general almost linear families of projections. However, as explained in §3, we only need to consider radial/co-radial projections with centre in uniformly non-horizontal, non-vertical direction and at an arbitrarily big distance from K . If we fix any non-horizontal and non-vertical direction and consider only centres at a sufficiently large distance, the resulting family of radial projections and family of co-radial projections will satisfy conditions (ii), (iii) of Definition 13. To have condition (i) satisfied as well, we only need to subdivide the family. Hence, Theorem 4 follows from Theorem 14.

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