

ROBUSTNESS WITH RESPECT TO SMALL DELAYS FOR EXPONENTIAL STABILITY OF ABSTRACT DIFFERENTIAL EQUATIONS IN BANACH SPACES

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Abstract

This paper is concerned with robustness with respect to small delays for the exponential stability of abstract differential equations in Banach spaces. Some necessary and sufficient conditions are given in terms of the uniformly square integrability of the fundamental operator family and the uniform boundedness of its resolvent on the imaginary axis.

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1. Introduction and Preliminaries

Robustness of stability with respect to small delays, for example, as motivated by feedback systems in control theory, is of great theoretical and practical importance, but this property does not hold for many systems. In the literature (see, for example, [4, 5, 7, 9, 10] and references therein), there are many examples of systems described by distributed parameters which are exponentially stabilised by a feedback but which are destabilised by arbitrary small delays in the feedback loop. Examples of this sort first appeared in Huang [9] and Datko *et al.* [5] independently in 1986. Huang [9] gave two abstract counterexamples and proved a well-known result that a system is robust to small delays if operator A generates an immediately norm continuous C_0 -semigroup. More recently, the problem of robustness of stability has received considerable attention. Logemann, Rebarber, Townley and Weiss ([13–16]) have presented a systematic

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treatment for some distributed parameter systems. More recently, Avalos *et al.* [1] showed that it is not possible to construct a dynamic stabiliser of a general form such that the stabilisation is robust with respect to small delays for a structural acoustics model. Hale and Lunel [7] try to explain the underlying mechanisms and the role that difference equations are playing in robustness results. Batkai and Piazzera [2] show that those sufficient conditions derived in [10] and [14] also hold on the state space $\mathcal{E} = X \times L^p([0, r_0], X)$, which is a better choice for many applications.

Corduneanu [3] first introduced the fundamental matrix to study stability for integro-differential equations in finite-dimensional spaces. Liang and Xiao ([11] and [12]) extended the fundamental matrix to the fundamental operator to deal with exponential stability for abstract autonomous functional differential equations with infinite delay. In this paper we investigate whether exponential stability persists if there is a small delay in the feedback term for the abstract differential equation by using the fundamental operator family in Banach spaces.

Consider the following equation:

$$\begin{cases} \dot{u}(t) = Au(t) + Bu(t-r), & t > 0, \\ u(0) = x, \\ u_0(\theta) = f(\theta), & \theta \in [-r, 0] \end{cases} \quad (1.1)$$

on a Banach space X , where $(A, D(A))$ generates a C_0 -semigroup $T(t)$ satisfying $\|T(t)\| \leq Me^{wt}$, $w \in \mathbb{R}$, $M \geq 1$; $B \in \mathcal{L}(X)$, $x_0 \in X$, $f \in L^p([-r, 0]; X)$, $p \geq 1$. For concepts and results involving the C_0 -semigroup, we refer the reader to [6, 8] and [18].

To transform system (1.1) into operator-valued matrix form we introduce the following operator \mathcal{A}_r on $\mathcal{E} := X \times L^p([-r, 0]; X)$:

$$\mathcal{A}_r = \begin{pmatrix} A & B\delta_{-r} \\ 0 & d/d\sigma \end{pmatrix},$$

$$D(\mathcal{A}_r) = \{(x, f) \in D(A) \times W^{1,p}([-r, 0]; X) : f(0) = x\},$$

and system (1.1) is transformed into the equivalent Cauchy problem on \mathcal{E} :

$$\begin{cases} \dot{v}(t) = \mathcal{A}_r v(t), \\ v(0) = v_0. \end{cases}$$

Under these assumptions on A and B , $(A + B, D(A))$ generates a C_0 -semigroup. It is easy to prove that $(\mathcal{A}_r, D(\mathcal{A}_r))$ generates a C_0 -semigroup $\mathcal{T}_r(t) = \begin{pmatrix} u(t) \\ u_r(t) \end{pmatrix}$ on \mathcal{E} . For details, we refer to [2].

In the following section, we introduce the fundamental operator family and obtain a representation of the solution of system (1.1). In Section 3, some necessary and sufficient conditions are given in terms of the uniformly square integrability of the fundamental operator family and the uniform boundedness of its resolvent on the imaginary axis.

2. Preliminaries

To characterise robustness with respect to small delays for the exponential stability of system (1.1) on the state space \mathcal{E} , we introduce the concept of the fundamental operator family for system (1.1) by means of the following integral equation:

$$\begin{cases} X_r(t)x = T(t)x + \int_0^t T(t-s)BX_r(s-r)x ds, & t > 0, \\ X_r(0) = I, & t = 0, \\ X_r(t) = 0, & t \in [-r, 0]. \end{cases} \tag{2.1}$$

In this section, we first derive the existence of the strong continuous solution $X_r(t)$, $t \geq 0$, and an exponential estimate on $X_r(t)$ which are basic to the application of the Laplace transform and to obtaining a representation of the solution $u(t)$ of system (1.1). It is easy to prove the following theorem.

THEOREM 2.1. *Suppose that the conditions on A and B are satisfied. Then there exists a unique solution $X_r(t)$, $t \geq -r$, of Equation (2.1) which is strongly continuous on $[0, \infty)$. Furthermore, $X_r(t)$ satisfies the inequality*

$$\|X_r(t)x\| \leq Me^{(w+Me^{w_1r}\|B\|)t}\|x\|, \quad t \geq r.$$

From Theorem 2.1, we can define the fundamental operator family $X_r(t)$, $t \geq -r$, as the unique solution of integral equation (2.1). From $\|X_r(t)\| \leq Me^{w_1t}$ (where $w_1 = w + Me^{w_1r}\|B\|$), we obtain that the integral $\int_0^\infty e^{-\lambda t} X_r(t)x dt$ converges for all $\text{Re } \lambda > w_1$ and all $x \in X$. Furthermore, we have the following theorem which implies that $\Delta_r^{-1}(\lambda) := (\lambda - A - e^{-\lambda r}B)^{-1}$ is the Laplace transform of $X_r(t)$.

THEOREM 2.2. *The fundamental operator family $X_r(t)$ of Equation (1.1) satisfies*

$$\int_0^\infty e^{-\lambda t} X_r(t)x dt = \Delta_r^{-1}(\lambda)x, \quad \text{Re } \lambda > w_1 > w \text{ for } x \in X.$$

PROOF. Since $X_r(t)$ satisfies

$$X_r(t)x = T(t)x + \int_0^t T(t-s)BX_r(s-r)x ds, \quad t \geq 0 \text{ and } x \in X,$$

we have

$$\int_0^\infty e^{-\lambda t} X_r(t)x dt = \int_0^\infty e^{-\lambda t} T(t)x dt + \int_0^\infty e^{-\lambda t} \int_0^t T(t-s)BX_r(s-r)x ds dt$$

$$\begin{aligned}
 &= R(\lambda, A)x + \int_0^\infty \int_0^\infty e^{-\lambda(t+s)} T(t) B X_r(s-r)x \, dt \, ds \\
 &= R(\lambda, A)x + \int_0^\infty R(\lambda, A) e^{-\lambda s} B X_r(s-r)x \, ds \\
 &= R(\lambda, A)x + \int_r^\infty R(\lambda, A) e^{-\lambda s} B X_r(s-r)x \, ds \\
 &= R(\lambda, A)x + e^{-\lambda r} R(\lambda, A) B \int_0^\infty e^{-\lambda s} X_r(s)x \, ds.
 \end{aligned}$$

Therefore

$$(\lambda - A - B e^{-\lambda r}) \int_0^\infty e^{-\lambda t} X_r(t)x \, dt = x,$$

which yields that

$$\int_0^\infty e^{-\lambda t} X_r(t)x \, dt = \Delta_r^{-1}(\lambda)x,$$

for $\text{Re } \lambda$ large enough, and hence it holds for $\text{Re } \lambda > w_1$. □

THEOREM 2.3. *Let $u(t)$ be the mild solution of (1.1). Then $u(t)$ is given by*

$$u(t) = \begin{cases} X_r(t)x_0 + \int_0^t X_r(t-s)B(S_0f)(s-r) \, ds, & t \geq 0, \\ f(t), & t \in [-r, 0), \end{cases}$$

where

$$(S_0f)(t) = \begin{cases} f(t), & t \in [-r, 0) \\ 0, & \text{otherwise.} \end{cases}$$

PROOF. (a) Since $X_r(t)$ satisfies (2.1), for $t \in [0, r]$ we have

$$\begin{aligned}
 X_r(t) &= T(t) \quad \text{and} \\
 \int_0^t X_r(t-s)B(S_0f)(s-r) \, ds &= \int_0^t T(t-s)Bf(s-r) \, ds,
 \end{aligned}$$

and consequently,

$$\begin{aligned}
 u(t) &= T(t)x_0 + \int_0^t T(t-s)Bu(s-r) \, ds \\
 &= X_r(t)x_0 + \int_0^t X_r(t-s)Bf(s-r) \, ds \\
 &= X_r(t)x_0 + \int_0^t X_r(t-s)B(S_0f)(s-r) \, ds. \tag{2.2}
 \end{aligned}$$

For $t \in [r, 2r)$, from (2.1) it follows that

$$\begin{aligned} X_r(t)x_0 &= T(t)x_0 + \int_0^t T(t-s)BX_r(s-r)x_0 ds \\ &= T(t)x_0 + \int_0^t T(t-s)B(s-r)x_0 ds, \end{aligned} \quad (2.3)$$

and

$$\begin{aligned} &\int_0^t X_r(t-s)B(S_0f)(s-r) ds \\ &= \int_0^r T(t-s)Bf(s-r) ds \\ &\quad + \int_0^r \int_0^{t-s} T(t-s-\tau)BX_r(\tau-r)Bf(s-r) d\tau ds \\ &= \int_0^r T(t-s)Bf(s-r) ds \\ &\quad + \left(\int_r^t \int_0^r + \int_0^r \int_0^s \right) T(t-s)BX_r(s-\tau-r)Bf(s-r) d\tau ds \\ &= \int_0^r T(t-s)Bf(s-r) ds \\ &\quad + \int_r^t \int_0^{s-r} T(t-s)BX_r(s-\tau-r)Bf(s-r) d\tau ds. \end{aligned} \quad (2.4)$$

Using (2.3), (2.4), and the fact that $u(t)$ is the mild solution of (1.1), we deduce that

$$\begin{aligned} u(t) &= T(t)x_0 + \int_r^t T(t-s)Bu(s-r) ds + \int_0^r T(t-s)Bf(s-r) ds \\ &= T(t)x_0 + \int_r^t T(t-s)BT(s-r)x_0 ds + \int_0^r T(t-s)Bf(s-r) ds \\ &\quad + \int_0^r \int_0^{s-r} T(t-s)BT(s-r-\tau)Bf(\tau-r) d\tau ds \\ &= X_r(t)x_0 + \int_0^t X_r(t-s)B(S_0f)(s-r) ds. \end{aligned}$$

(b) Suppose that (2.2) holds for $t \in [0, (n+1)r)$. Now for $t \in [(n+1)r, (n+2)r)$, we have

$$\begin{aligned} u(t) &= T(t)x_0 + \int_r^t T(t-s)Bu(s-r) ds + \int_0^r T(t-s)Bf(s-r) ds \\ &= T(t)x_0 + \int_r^t T(t-s)BX_r(s-r)x_0 ds \end{aligned}$$

$$\begin{aligned}
& + \int_r^t \int_0^{\tau-r} T(t-\tau) B X_r(\tau-r-s) B(S_0 f)(s-r) ds d\tau \\
& + \int_0^r T(t-s) B f(s-r) ds + \int_0^r T(t-s) B f(s-r) ds \\
& = X_r(t) x_0 + \int_0^r \int_r^{t-s} T(t-s-\tau) B X_r(\tau-r) B f(s-r) d\tau ds \\
& + \int_0^r T(t-s) B f(s-r) ds, \tag{2.5}
\end{aligned}$$

and

$$\begin{aligned}
& \int_0^t X_r(t-s) B(S_0 f)(s-r) ds \\
& = \int_0^t T(t-s) B f(s-r) ds \\
& + \int_0^r \int_r^{t-s} T(t-s-\tau) B X_r(\tau-r) B f(s-r) d\tau ds. \tag{2.6}
\end{aligned}$$

From (2.5) and (2.6), it follows that

$$u(t) = X_r(t) x_0 + \int_0^t X_r(t-s) B(S_0 f)(s-r) ds, \quad t \in [(n+1)r, (n+2)r),$$

which completes the proof of the theorem. \square

3. Robustness with respect to small delays

In this section, we first introduce the concept of robustness with respect to small delays for exponential stability on the state space $\mathcal{E} = X \times L^p([-r, 0]; X)$. Secondly, the robustness is characterised via the fundamental operators. Finally, we show the analyticity of the resolvent $\Delta_r^{-1}(\lambda)$ and the resolvent identity, and furthermore, characterise the robustness in terms of the resolvent $\Delta_r^{-1}(\lambda)$.

DEFINITION 1. System (1.1) is said to be robust with respect to small delays for exponential stability if there exists $r_0 > 0$ such that for any $r \in [0, r_0]$, $f \in L^p([-r, 0]; X)$ and $x \in X$, system (1.1) is exponentially stable, that is, there exist constants $M, w > 0$ such that

$$\left\| \mathcal{T}(t) \begin{pmatrix} x \\ f \end{pmatrix} \right\|_{\mathcal{E}} = \left\| \begin{pmatrix} u(t) \\ u_t \end{pmatrix} \right\|_{\mathcal{E}} \leq M e^{-wt} (\|x\|^p + \|f\|_{L^p([-r, 0]; X)}^p)^{1/p}.$$

THEOREM 3.1. *System (1.1) is robust with respect to small delays for exponential stability if and only if there exists $r_0 > 0$ such that $X_r(t)$ is uniformly exponentially stable for $r \in [0, r_0]$, that is, there exist constants $r_0, M, w > 0$ such that*

$$\|X_r(t)\| \leq Me^{-wt}, \quad t \geq 0, \quad \text{uniformly for } r \in [0, r_0].$$

PROOF. For any $x \in X$, let $f = 0$. We deduce that the mild solution $u(t)$ of (1.1) satisfies

$$u(t) = \begin{cases} X_r(t)x, & t \geq 0, \\ 0, & t \in [-r, 0). \end{cases}$$

Therefore, robustness shows that $\|u(t)\| = \|X_r(t)x\| \leq Me^{-wt}\|x\|, x \in X$, which implies $\|X_r(t)\| \leq Me^{-wt}$ uniformly for $r \in [0, r_0]$.

On the other hand, for $t > r$, noticing that $B(S_0f)(s - r) = 0, s > r$, and

$$u(t) = X_r(t)x + \int_0^t X_r(t - s)B(S_0f)(s - r) ds,$$

we get

$$\begin{aligned} \|u(t)\| &\leq Me^{-wt}\|x\| + \int_0^t Me^{-w(t-s)}\|B\|\|f(s - r)\| ds \\ &\leq Me^{-wt}\|x\| + M\|B\|e^{-wt} \left(\frac{1}{qw}(e^{qw r_0} - 1)\right)^{1/q} \|f\|_{L^p([-r,0];X)} \\ &\leq M'e^{-wt}(\|x\| + \|f\|_{L^p([-r,0];X)}) \\ &\leq M'e^{-wt}2(\|x\|^p + \|f\|_{L^2([-r,0];X)}^p)^{1/p}, \end{aligned}$$

where $1/p + 1/q = 1$. Similarly, we have

$$\|u(t + \theta)\| \leq Me^{-wt}e^{-w\theta}\|x\| + \int_0^r Me^{-wt}e^{ws}e^{-w\theta}\|B\|\|f(s - r)\| ds,$$

and consequently,

$$\begin{aligned} \|u_t(\cdot)\|_{L^p([-r,0];X)} &\leq M \left(\frac{1}{pw}(e^{pw r_0} - 1)\right)^{1/p} e^{-wt}\|x\| \\ &\quad + Me^{-wt}\|B\| \left(\frac{1}{pw}(e^{pw r_0} - 1)\right)^{1/p} \int_0^r e^{ws}f(s - r) ds \\ &\leq 2M''e^{-wt}(\|x\|^p + \|f\|_{L^p([-r,0];X)}^p)^{1/p}. \end{aligned}$$

From the above discussion, we deduce that

$$\left\| \mathcal{T}(t) \begin{pmatrix} x \\ f \end{pmatrix} \right\|_{\mathcal{E}} = \left\| \begin{pmatrix} u(t) \\ u_t(\cdot) \end{pmatrix} \right\|_{\mathcal{E}} \leq 2 \max\{M', M''\}e^{-wt}(\|x\|^p + \|f\|_{L^p([-r,0];X)}^p)^{1/p},$$

which implies robustness. □

THEOREM 3.2. $X_r(t)$ is uniformly exponentially stable for $r \in [0, r_0]$ if and only if there exists $M > 0$ such that

$$\left(\int_0^\infty \|X_r(t)x\|^2 dt \right)^{1/2} \leq M\|x\|, \quad \text{for } x \in X \text{ and uniformly for } r \in [0, r_0].$$

PROOF. It suffices to show sufficiency for $p = 2$. Indeed, if $u(t)$ is the mild solution of (1.1), then for $t > 0$, we have

$$u(t) = X_r(t)x + \int_0^t X_r(t-s)B(S_0f)(s-r) ds,$$

which implies

$$\begin{aligned} \|u(\cdot)\|_{L^2(0,\infty;X)} &\leq \|X_r(\cdot)x\|_{L^2(0,\infty;X)} \\ &\quad + \left\{ \int_0^\infty \left(\int_0^t \|X_r(t-s)B(S_0f)(s-r)\| ds \right)^2 dt \right\}^{1/2} \\ &\leq M\|x\| + \int_0^\infty \left(\int_0^\infty \|X_r(t-s)B(S_0f)(s-r)\|^2 dt \right)^{1/2} ds \\ &\leq M\|x\| + \int_0^\infty M\|B(S_0f)(s-r)\| ds \\ &\leq M'(\|x\|^2 + \|f\|_{L^2([-r,0];X)}^2)^{1/2}. \end{aligned} \tag{3.1}$$

On the other hand, for $t > r$, we can deduce

$$\begin{aligned} &\left(\int_r^\infty \int_{-r}^0 \|u_r(\theta)\|^2 d\theta dt \right)^{1/2} \\ &\leq \left(\int_0^\infty \int_{-r}^0 \|X_r(t+\theta)x\|^2 d\theta dt \right)^{1/2} \\ &\quad + \left(\int_r^\infty \int_{-r}^0 \left(\int_0^{t+\theta} \|X_r(t+\theta-s)B(S_0f)(s-r)\| ds \right)^2 d\theta dt \right)^{1/2} \\ &\leq \left(\int_{-r}^0 \int_r^\infty \|X_r(t+\theta)x\|^2 dt d\theta \right)^{1/2} \\ &\quad + \left(\int_{-r}^0 \int_0^\infty \int_r^\infty \|X_r(t+\theta-s)B(S_0f)(s-r)\|^2 dt ds d\theta \right)^{1/2} \\ &\leq Mr\|x\| + \left(\int_{-r}^0 \int_0^\infty M\|B(S_0f)(s-r)\|^2 ds d\theta \right)^{1/2} \\ &\leq M''(\|x\| + \|f\|_{L^2([-r,0];X)}). \end{aligned} \tag{3.2}$$

From (3.1) and (3.2), it follows that

$$\left(\int_0^\infty \left\| \mathcal{T}(t) \begin{pmatrix} x \\ f \end{pmatrix} \right\|_\varepsilon^2 dt \right)^{1/2} = \left(\int_0^\infty \left\| \begin{pmatrix} u(t) \\ u_r(\cdot) \end{pmatrix} \right\|_{X \times L^p([-r,0];X)}^2 dt \right)^{1/2} < +\infty.$$

By Datko-Pazy’s theorem ([6, 18]) for exponential stability, we obtain that $\mathcal{T}(t)$ is exponentially stable which implies that $X_r(t)$ is uniformly exponentially stable for $r \in [0, r_0]$. □

In what follows, suppose that $D_r := \{\lambda \in C \mid \Delta_r^{-1}(\lambda) \text{ exists and } \Delta_r^{-1}(\lambda) \in \mathcal{L}(X)\}$. We will show the $\mathcal{L}(X)$ -valued analyticity and the resolvent identity of $\Delta_r^{-1}(\lambda)$ on D_r , and characterise the robustness of the stability by $\Delta_r^{-1}(\lambda)$.

THEOREM 3.3. (i) *For all $\mu, \lambda \in D_r$, we have the following resolvent identity:*

$$\Delta_r^{-1}(\mu) - \Delta_r^{-1}(\lambda) = \Delta_r^{-1}(\mu)(\lambda - \mu + Be^{-\mu r} - Be^{-\lambda r})\Delta_r^{-1}(\lambda). \tag{3.3}$$

(ii) *The resolvent $\Delta_r^{-1}(\cdot)$ is analytic on D_r , and*

$$\frac{d}{d\lambda} \Delta_r^{-1}(\lambda) = -\Delta_r^{-1}(\lambda)^2 - re^{-\lambda r} \Delta_r^{-1}(\lambda) B \Delta_r^{-1}(\lambda), \quad \lambda \in D_r.$$

PROOF. For $\mu, \lambda \in D_r$, we have

$$\begin{aligned} \Delta_r^{-1}(\mu) &= \Delta_r^{-1}(\mu)(\lambda - A - Be^{-\lambda r})\Delta_r^{-1}(\lambda) \\ &= \Delta_r^{-1}(\mu)(\mu - A - Be^{-\mu r} + \lambda - \mu + Be^{-\mu r} - Be^{-\lambda r})\Delta_r^{-1}(\lambda) \\ &= \Delta_r^{-1}(\lambda) + \Delta_r^{-1}(\mu)(\lambda - \mu + Be^{-\mu r} - Be^{-\lambda r})\Delta_r^{-1}(\lambda), \end{aligned}$$

or equivalently,

$$\Delta_r^{-1}(\mu) - \Delta_r^{-1}(\lambda) = \Delta_r^{-1}(\mu)(\lambda - \mu + Be^{-\mu r} - Be^{-\lambda r})\Delta_r^{-1}(\lambda).$$

Next, for $\lambda_0 \in D_r$, we get

$$\begin{aligned} \Delta_r(\lambda) &= \lambda_0 - A - e^{-\lambda_0 r} B + (\lambda - \lambda_0) - Be^{-\lambda r} + Be^{-\lambda_0 r} \\ &= \Delta_r(\lambda_0)(I + \Delta_r^{-1}(\lambda_0)(\lambda - \lambda_0 - Be^{-\lambda r} + Be^{-\lambda_0 r})). \end{aligned}$$

Let $\lambda - \lambda_0$ be small enough such that

$$\|\lambda - \lambda_0 + e^{-\lambda_0 r} B - e^{-\lambda r} B\| \leq \frac{1}{2\|\Delta_r^{-1}(\lambda_0)\|}, \tag{3.4}$$

which yields that $(I + \Delta_r^{-1}(\lambda_0)(\lambda - \lambda_0 + e^{-\lambda_0 r} B - e^{-\lambda r} B))^{-1}$ exists and belongs to $\mathcal{L}(X)$, and $\|(I + \Delta_r^{-1}(\lambda_0)(\lambda - \lambda_0 + e^{-\lambda_0 r} B - e^{-\lambda r} B))^{-1}\| \leq 2$. Therefore, we obtain

$$\Delta_r^{-1}(\lambda) = (I + \Delta_r^{-1}(\lambda_0)(\lambda - \lambda_0 + e^{-\lambda_0 r} B - e^{-\lambda r} B))^{-1} \Delta_r^{-1}(\lambda_0)$$

and $\Delta_r^{-1}(\lambda) \leq 2\|\Delta_r^{-1}(\lambda_0)\|$.

On the other hand, for λ satisfying (3.4), using the resolvent identity (3.3), we deduce that

$$\Delta_r^{-1}(\lambda) - \Delta_r^{-1}(\lambda_0) = \Delta_r^{-1}(\lambda)(\lambda_0 - \lambda + Be^{-\lambda r} - Be^{-\lambda_0 r})\Delta_r^{-1}(\lambda_0),$$

and consequently,

$$\begin{aligned} \|\Delta_r^{-1}(\lambda) - \Delta_r^{-1}(\lambda_0)\| &\leq \|\Delta_r^{-1}(\lambda)\|\|\lambda_0 - \lambda + Be^{-\lambda r} - Be^{-\lambda_0 r}\|\|\Delta_r^{-1}(\lambda_0)\| \\ &\leq 2\|\Delta_r^{-1}(\lambda_0)\|\|\lambda_0 - \lambda + Be^{-\lambda r} - Be^{-\lambda_0 r}\| \xrightarrow{\lambda \rightarrow \lambda_0} 0, \end{aligned}$$

which shows the continuity of $\Delta_r^{-1}(\cdot)$. Finally, using continuity and the resolvent identity (3.3) of $\Delta_r^{-1}(\cdot)$, it is easy to see the analyticity. Indeed, for $\lambda, \mu \in D_r$, from (3.3) it follows that

$$\frac{\Delta_r^{-1}(\mu) - \Delta_r^{-1}(\lambda)}{\mu - \lambda} = -\Delta_r^{-1}(\mu) \left(I - B \frac{e^{-\mu r} - e^{-\lambda r}}{\mu - \lambda} \right) \Delta_r^{-1}(\lambda).$$

Let $\mu \rightarrow \lambda$, then using the continuity of $\Delta_r^{-1}(\cdot)$, we obtain

$$\frac{d}{d\lambda} \Delta_r^{-1}(\lambda) = -\Delta_r^{-1}(\lambda)^2 - re^{-\lambda r} \Delta_r^{-1}(\lambda) B \Delta_r^{-1}(\lambda). \quad \square$$

THEOREM 3.4. *Let $\|X_r(t)\| \leq Me^{w_0 t}$, $s_0^r := \inf\{\text{Re } \lambda \mid \lambda \in D_r \text{ and } \|\Delta_r^{-1}(\lambda)\| < +\infty\}$, $w_0^r := \inf\{w \in R \mid \text{there exists } M \geq 1 \text{ such that } \|X_r(t)\| \leq Me^{wt}, t \geq 0\}$, and let $\tau_1 > \tau_2 > s_0^r$. Then for all $x \in X$ we have $\lim_{|s| \rightarrow \infty} \|\Delta_r^{-1}(\tau + is)x\| = 0$, uniformly for $\tau \in [\tau_1, \tau_2]$.*

PROOF. Upon replacing τ_2 by some large number, we may assume that $\tau_2 > w_0^r$. By the Riemann-Lebesgue lemma, for $x \in X$ we have $\lim_{|s| \rightarrow \infty} \|\Delta_r^{-1}(\tau_2 + is)x\| = 0$. Using the resolvent identity (3.3), for all $\tau \in [\tau_1, \tau_2]$, we deduce

$$\begin{aligned} \Delta_r^{-1}(\tau + is)x &= \{I + \Delta_r^{-1}(\tau + is)(\tau_2 - \tau - Be^{-(\tau_2+is)r} + Be^{-(\tau+is)r})\} \\ &\quad \times \Delta_r^{-1}(\tau_2 + is)x, \end{aligned}$$

and hence

$$\begin{aligned} \|\Delta_r^{-1}(\tau + is)x\| &\leq \{1 + \|\Delta_r^{-1}(\tau + is)\|(|\tau_2 - \tau| + \|B\||e^{-(\tau_2+is)r} - e^{-(\tau+is)r}||)\} \\ &\quad \times \|\Delta_r^{-1}(\tau_2 + is)x\| \\ &\leq \left\{ 1 + \sup_{\tau \in [\tau_1, \tau_2]} \|\Delta_r^{-1}(\tau + is)\|(|\tau_2 - \tau| + \|B\|(e^{-\tau_2 r} + e^{-\tau r})) \right\} \\ &\quad \times \|\Delta_r^{-1}(\tau_2 + is)x\| \\ &\rightarrow 0 \quad (|s| \rightarrow \infty), \end{aligned}$$

uniformly for $\tau \in [\tau_1, \tau_2]$. □

THEOREM 3.5. *Let $X_r(t)$ be the fundamental operator family of system (1.1). Then for all $x \in X$ and $\omega > s_0^r$ we have*

$$X_r(t)x = \frac{1}{2\pi i} (C, 1) \int_{\text{Re } \lambda = \omega} e^{\lambda t} \Delta_r^{-1}(\lambda)x \, d\lambda,$$

where $(C, 1)$ denotes convergence of the integral in the Césaro mean, that is,

$$(C, 1) \int_{-\infty}^{+\infty} f(s) \, ds := \lim_{t \rightarrow +\infty} \frac{1}{t} \int_0^t \int_{-\tau}^{+\tau} f(s) \, ds \, d\tau.$$

PROOF. For $w > w_0^r$, see the definition in Theorem 3.4. From Fejer’s theorem [17], it follows that

$$e^{-wt} X_r(t)x = \frac{1}{2\pi} (C, 1) \int_{\mathbb{R}} e^{ist} e^{-w \wedge X_r(\cdot)} x(s) \, ds,$$

where \wedge denotes the Fourier transform. On the other hand, by Theorem 2.2, we have

$$\Delta_r^{-1}(w + is)x = \int_0^{\infty} e^{-(w+is)t} X_r(t)x \, dt = e^{-w \wedge X_r(\cdot)} x(s).$$

Therefore, we have

$$\begin{aligned} X_r(t)x &= \frac{e^{wt}}{2\pi} (C, 1) \int_{\mathbb{R}} e^{ist} \Delta_r^{-1}(w + is)x \, ds \\ &= \frac{1}{2\pi i} (C, 1) \int_{\text{Re } \lambda = w} e^{\lambda t} \Delta_r^{-1}(\lambda)x \, d\lambda. \end{aligned}$$

Finally, for general $w > s_0^r$, using Theorem 3.4 and Cauchy’s theorem to shift the path of the integral to a vertical line to the right of ω_0^r , we obtain

$$(C, 1) \int_{\text{Re } \lambda = w} e^{\lambda t} \Delta_r^{-1}(\lambda)x \, d\lambda = (C, 1) \int_{\text{Re } \lambda = \omega_0^r} e^{\lambda t} \Delta_r^{-1}(\lambda)x \, d\lambda. \quad \square$$

THEOREM 3.6. *If there exists an $w' > w_0^r$ and $M_r > 0$ such that*

$$\int_{\mathbb{R}} \|\Delta_r^{-1}(w' + is)x\|^2 \, ds < M_r \|x\|^2, \quad x \in X, \tag{3.5}$$

and

$$\int_{\mathbb{R}} \|\Delta_r^{-1}(w' + is)^* x^*\|^2 \, ds < M_r \|x^*\|^2, \quad x^* \in X^*, \tag{3.6}$$

then $w_0^r = s_0^r$.

Suppose that (3.5)–(3.6) are satisfied uniformly for $r \in [0, r_0]$ and $\sup\{\|\Delta_r^{-1}(\lambda)\| : \text{Re } \lambda > 0\} \leq M$, uniformly for $r \in [0, r_0]$. Then $X_r(t)$ is uniformly exponentially stable for $r \in [0, r_0]$.

PROOF. It suffices to prove $s'_0 \geq w'_0$. Indeed, for any $\varepsilon > 0$, from (3.3), we deduce

$$\begin{aligned} \Delta_r^{-1}(s'_0 + \varepsilon + is) &= \Delta_r^{-1}(w' + is) + \Delta_r^{-1}(s'_0 + \varepsilon + is) \\ &\quad \times (w' - s'_0 - \varepsilon + Be^{-(s'_0 + \varepsilon + is)r} - Be^{-(w' + is)r})\Delta_r^{-1}(w' + is), \end{aligned}$$

and hence

$$\begin{aligned} (C, 1) \int_R e^{ist} \Delta_r^{-1}(s'_0 + \varepsilon + is)x \, ds &= (C, 1) \int_R e^{ist} \Delta_r^{-1}(w' + is)x \, ds \\ &\quad + (C, 1) \int_R e^{ist} \Delta_r^{-1}(s'_0 + \varepsilon + is)(w' - s'_0 - \varepsilon \\ &\quad + Be^{-(s'_0 + \varepsilon + is)r} - Be^{-(w' + is)r})^{-1} \Delta_r^{-1}(w' + is)x \, ds. \end{aligned} \tag{3.7}$$

On the other hand, we estimate

$$\left\| \frac{1}{2\pi} (C, 1) \int_R e^{ist} \Delta_r^{-1}(w' + is)x \, ds \right\| \leq \|e^{-w't} X_r(t)x\| \leq M\|x\|, \tag{3.8}$$

and from (3.5) and (3.6) we estimate

$$\begin{aligned} &\left\| (C, 1) \int_R e^{ist} \Delta_r^{-1}(s'_0 + \varepsilon + is)(w' - s'_0 - \varepsilon + Be^{-(s'_0 + \varepsilon + is)r} - Be^{-(w' + is)r}) \right. \\ &\quad \left. \times \Delta_r^{-1}(w' + is)x \, ds \right\| \\ &= \sup_{\|x^*\| \leq 1} \left| (C, 1) \int_R e^{ist} x^* \{ \Delta_r^{-1}(s'_0 + \varepsilon + is) \right. \\ &\quad \left. \times (w' - s'_0 - \varepsilon + Be^{-(s'_0 + \varepsilon + is)r} - Be^{-(w' + is)r})\Delta_r^{-1}(w' + is)x \} \, ds \right| \\ &\leq \sup_{\|x^*\| \leq 1} \int_R \|\Delta_r^{-1}(s'_0 + \varepsilon + is)^* x^*\| \\ &\quad \times \|(w' - s'_0 - \varepsilon + Be^{-(s'_0 + \varepsilon + is)r} - Be^{-(w' + is)r})\Delta_r^{-1}(w' + is)x\| \, ds \\ &\leq \sup_{\|x^*\| \leq 1} \left\{ \int_R \|\Delta_r^{-1}(s'_0 + \varepsilon + is)^* x^*\|^2 \, ds \right\}^{1/2} \\ &\quad \times \left(\int_R \|(w' - s'_0 - \varepsilon + Be^{-(s'_0 + \varepsilon + is)r} - Be^{-(w' + is)r})\|^2 \|\Delta_r^{-1}(w' + is)x\|^2 \, ds \right)^{1/2} \\ &\leq M (|w' - s'_0 - \varepsilon| + \|B\| (e^{1s'_0 + \varepsilon|r_0} + e^{|w'|r_0})) \left(\int_R \|\Delta_r^{-1}(w' + is)x\|^2 \, ds \right)^{1/2} \\ &\leq M'\|x\|. \end{aligned} \tag{3.9}$$

Therefore, using Theorem 3.5 and Equations (3.7)–(3.9), we obtain

$$\begin{aligned} \|X_r(t)x\| &= \left\| \frac{1}{2\pi}(C, 1) \int_R e^{(s_0^r + \varepsilon + is)t} \Delta_r^{-1}(s_0^r + \varepsilon + is)x \, ds \right\| \\ &= \left\| \frac{e^{(s_0^r + \varepsilon)t}}{2\pi}(C, 1) \int_R e^{ist} \Delta_r^{-1}(s_0^r + \varepsilon + is)x \, ds \right\| \\ &\leq M_\varepsilon e^{(s_0^r + \varepsilon)t} \|x\|, \end{aligned}$$

which, observing the arbitrariness of $\varepsilon > 0$, completes the proof. \square

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