

Groups of homeomorphisms of one-manifolds III: nilpotent subgroups

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(Received 9 October 2001 and accepted in revised form 3 February 2003)

Abstract. This self-contained paper is part of a series (Groups of homeomorphisms of one-manifolds I: actions of nonlinear groups. *Preprint*, 2001; Group actions on one-manifolds II: extensions of Hölder's Theorem. To appear in *Trans. Amer. Math. Soc.*) seeking to understand groups of homeomorphisms of manifolds in analogy with the theory of Lie groups and their discrete subgroups. Plante and Thurston proved that every nilpotent subgroup of $\text{Diff}^2(S^1)$ is abelian. One of our main results is a sharp converse: $\text{Diff}^1(S^1)$ contains every finitely generated, torsion-free nilpotent group.

1. Introduction

A basic aspect of the theory of linear groups is the structure of nilpotent groups. In this paper we consider nilpotent subgroups of $\text{Homeo}(M)$ and $\text{Diff}^r(M)$, where M is the line \mathbb{R} , the circle S^1 or the interval $I = [0, 1]$. As we will see, the structure theory depends dramatically on the degree r of regularity as well as on the topology of M .

Throughout this paper all homeomorphisms will be orientation-preserving and all groups will consist only of such homeomorphisms. Plante and Thurston [PT] discovered that C^2 regularity imposes a severe restriction on nilpotent groups of diffeomorphisms.

THEOREM 1.1. *Any nilpotent subgroup of $\text{Diff}^2(I)$, $\text{Diff}^2([0, 1])$ or $\text{Diff}^2(S^1)$ must be abelian.*

Remark. In the case of subgroups of $\text{Diff}^2(I)$ and $\text{Diff}^2([0, 1])$ this result was first proved by Plante and Thurston [PT]. They also proved that the group is virtually abelian in the S^1 case. For completeness of exposition (and because it is simple), we present a proof of the Plante–Thurston result about I . These results are related to a result of Ghys [Gh], who proved that any solvable subgroup of $\text{Diff}^{\omega}(S^1)$ is metabelian. The result of Plante and Thurston is familiar in the study of codimension-1 foliations and led to the consideration of the centralizer diffeomorphisms of one-manifolds (see, for example, [MT] and [Wa]). In §4 we prove the PL version of Theorem 1.1.

Several authors have considered the dynamics of abelian group actions on S^1 and \mathbb{R} and the effect of regularity (see, in particular, Pixton [Pi] and Tsuboi [T]). Our main result is that lowering the regularity from C^2 to C^1 produces a sharply contrasting situation, where every possibility can occur.

THEOREM 1.2. *Let $M = \mathbb{R}, S^1$ or I . Then every finitely generated, torsion-free nilpotent group is isomorphic to a subgroup of $\text{Diff}^1(M)$.*

Witte [Wi, Lemma 2.2] observed that the groups of orientation-preserving homeomorphisms of \mathbb{R} are precisely the right-orderable groups. Since torsion-free nilpotent groups are right-orderable (see, e.g., [MR, p. 37]), it follows that such groups are subgroups of $\text{Homeo}(\mathbb{R})$. The content of Theorem 1.2 is the increase in regularity from C^0 to the sharp regularity C^1 .

The situation for \mathbb{R} is more complicated. On the one hand, there is no limit to the degree of nilpotence, even when regularity is high.

THEOREM 1.3. *$\text{Diff}^\infty(\mathbb{R})$ contains nilpotent subgroups of every degree of nilpotency.*

On the other hand, even with just a little regularity, the *derived length* of nilpotent groups is greatly restricted.

THEOREM 1.4. *Every nilpotent subgroup of $\text{Diff}^2(\mathbb{R})$ is metabelian, i.e. has an abelian commutator subgroup.*

In particular, Theorem 1.4 shows that the group of $n \times n$ upper-triangular matrices with ones on the diagonal, while admitting an effective action on \mathbb{R} by C^1 diffeomorphisms, admits no effective C^2 action on \mathbb{R} if $n > 3$.

Closely related to this algebraic restriction on nilpotent groups which act smoothly is a topological restriction.

THEOREM 1.5. *If N is a nilpotent subgroup of $\text{Diff}^2(\mathbb{R})$ and every element of N has a fixed point, then N is abelian.*

One open problem is to extend this theory to solvable subgroups, as well as to higher-dimensional manifolds. The paper by Plante [P] contains a number of interesting results and examples concerning solvable groups acting on \mathbb{R} . Another problem is to understand what happens between the degrees of regularity $r = 0$ and $r \geq 2$, where vastly differing phenomena occur.

Residually nilpotent groups. A variation of our construction of actions of nilpotent groups can be used to construct actions of a much wider class of groups, the *residually torsion-free nilpotent* groups, i.e. those groups where the intersection of all terms in the lower central series is trivial. In §2.4 we prove the following result.

THEOREM 1.6. *Let $M = \mathbb{R}, S^1$ or I . Then $\text{Diff}_+^1(M)$ contains every finitely generated, residually torsion-free nilpotent group.*

The class of finitely generated, residually torsion-free nilpotent groups includes free groups, surface groups and the Torelli groups, as well as products of these groups.

2. Constructions

In this section we construct examples of nilpotent groups acting on one-manifolds.

2.1. *An elementary observation.* There are several obvious relations among actions on the three spaces \mathbb{R} , S^1 and I . Restricting an action on I to the interior of I gives an action on \mathbb{R} . One can also start with an action on \mathbb{R} and consider the action on the one-point compactification S^1 or the two-point compactification I . But this usually entails loss of regularity of the action. That is, a smooth or PL action on \mathbb{R} will generally give only an action by homeomorphisms on I or T^1 .

2.2. *C^1 actions on M .* Let \mathcal{N}_n denote the group of $n \times n$ lower-triangular integer matrices with ones on the diagonal. Our first main goal is to prove that \mathcal{N}_n admits C^1 actions on the real line.

The proof is somewhat technical and so we will describe the strategy before engaging in the details. The traditional proof that \mathcal{N}_n acts by homeomorphisms on the interval uses the fact that it is an ordered group. Suppose a group acts effectively on a countable ordered set in a way that preserves the order (e.g. the set might be the group itself). One can then produce an action by homeomorphisms on I by embedding the countable set in an order-preserving way in I and canonically extending the action of each group element on that set to an order-preserving homeomorphism of I , first by using continuity to extend it to the closure of the embedded set and then using affine extensions on the complementary intervals of this closure.

The approach we take is somewhat similar. We consider the group \mathbb{Z}^n of n -tuples of integers and provide it with a linear order \succ which is the lexicographic ordering, i.e. $(x_1, \dots, x_n) < (y_1, \dots, y_n)$ if and only if $x_i = y_i$ for $1 \leq i < k$ and $x_k < y_k$ for some $0 \leq k \leq n$. It is well known and easy to show that the standard linear action of \mathcal{N}_n on \mathbb{Z}^n preserves this ordering.

Instead of embedding \mathbb{Z}^n as a countable set of points, however, for each $(q_1, \dots, q_n) \in \mathbb{Z}^n$ we will embed a closed interval $I(q_1, \dots, q_n)$ in I . We do this in such a way that the intervals are disjoint except that each one intersects its successor in a common endpoint and so that the order of the intervals in I agrees with the lexicographic ordering on \mathbb{Z}^n . We also arrange that the complement of the union of these intervals is a countable set. If, for each $\alpha \in \mathcal{N}_n$, we define g_α on $I(q_1, \dots, q_n)$ to be the canonical affine map to $I(\alpha(q_1, \dots, q_n))$ this would define g_α on a dense subset of I and it would extend uniquely to a homeomorphism, giving an action of \mathcal{N}_n by homeomorphisms.

In order to improve this to a C^1 action, we must replace the affine maps from $I(q_1, \dots, q_n)$ to $I(\alpha(q_1, \dots, q_n))$ with elements of another canonical family of diffeomorphisms which has two key properties. The first is that these subinterval diffeomorphisms must have derivative 1 at both endpoints in order to fit together in a C^1 map. The second is that if I_k is a strictly monotonic sequence of these subintervals, then the restriction of g_α to I_k must have a derivative which converges uniformly to 1 as k tends to infinity. In particular, by the mean value theorem the ratio of the lengths of $\alpha(I_k)$ and I_k must tend to 1 for any element $\alpha \in \mathcal{N}_n$. This makes the choice of the lengths of

these intervals one of the key ingredients of the proof. We choose these lengths with a positive parameter K . We are then able to show that as this parameter increases to infinity, the C^1 size of any g_α goes to zero. This allows us to prove the existence of an effective C^1 action of \mathcal{N}_n on I with generators chosen from an arbitrary C^1 neighborhood of the identity.

We proceed to the details beginning with some calculus lemmas. The first of them develops a family of interval diffeomorphisms which we will use as a replacement for affine interval maps as we discussed earlier. We are indebted to Jean-Christophe Yoccoz for the proof of the following lemma which substantially simplifies our earlier approach.

LEMMA 2.1. *For each a and $b \in (0, \infty)$, there exists a C^1 orientation-preserving diffeomorphism $\phi_{a,b} : [0, a] \rightarrow [0, b]$ with the following properties.*

- (1) *For any $a, b, c \in (0, \infty)$ and for any $x \in [0, a]$, $\phi_{b,c}(\phi_{a,b}(x)) = \phi_{a,c}(x)$.*
- (2) *For all a, b , $\phi'_{a,b}(0) = \phi'_{a,b}(1) = 1$.*
- (3) *Given $\varepsilon > 0$ there exists $\delta > 0$ such that, for all $x \in [0, a]$,*

$$|\phi'_{a,b}(x) - 1| < \varepsilon, \quad \text{whenever } \left| \frac{b}{a} - 1 \right| < \delta.$$

Proof. For $u_0 \in (0, \infty)$, we define

$$L(u_0) = \int_{-\infty}^{\infty} \frac{du}{u^2 + u_0^2}.$$

A change of variables $u = u_0x$ allows one to conclude that

$$L(u_0) = \frac{1}{u_0} \int_{-\infty}^{\infty} \frac{dx}{x^2 + 1} = \frac{\pi}{u_0}.$$

For each $u_0 \in (0, \infty)$, we define $\psi_{u_0} : \mathbb{R} \rightarrow (0, L(u_0))$ by

$$\psi_{u_0}(t) = \int_{-\infty}^t \frac{du}{u^2 + u_0^2}.$$

Clearly ψ_{u_0} is a real analytic diffeomorphism from \mathbb{R} onto the open interval $(0, L(u_0))$.

Now define $\phi_{a,b} : [0, a] \rightarrow [0, b]$ by setting $\phi_{a,b}(0) = 0$, $\phi_{a,b}(a) = b$ and for $x \in (a, b)$ letting $\phi_{a,b}(x) = \psi_{u_1}(\psi_{u_0}^{-1}(x))$ where $a = L(u_0)$ and $b = L(u_1)$. This is clearly a homeomorphism of $[0, a]$ to $[0, b]$ which is real analytic on $(0, a)$. We observe that the derivative of $\phi_{a,b}(x)$ at the point $x = \psi_{u_0}(t)$ is given by

$$\phi'_{a,b}(x) = \frac{\psi'_{u_1}(t)}{\psi'_{u_0}(t)} = \frac{t^2 + u_0^2}{t^2 + u_1^2}.$$

From this it is clear that $\phi'_{a,b}(x)$ can be continuously extended to the endpoints of the interval $[0, a]$ by assigning it the value 1 there. Hence, $\phi_{a,b}(x)$ is C^1 on the closed interval $[0, a]$ and satisfies property (2). Property (1) is clear from the definition.

To check property (3), we observe that if, as before, $x = \psi_{u_0}(t)$, then

$$|\phi'_{a,b}(x) - 1| = \left| \frac{t^2 + u_0^2}{t^2 + u_1^2} - 1 \right|$$

which is easily seen to assume its maximum when $t = 0$. But

$$|\phi'_{a,b}(x) - 1| \leq \left| \frac{u_0^2}{u_1^2} - 1 \right| = \left| \frac{b^2}{a^2} - 1 \right|$$

since $u_0 = \pi/a$ and $u_1 = \pi/b$. From this it is clear that property (3) holds. □

We will also need the following technical lemma.

LEMMA 2.2. *Suppose n is a positive even integer and $K > 0$. Then, for $(x, y) \in \mathbb{R}^2$,*

$$\lim_{\|(x,y)\| \rightarrow \infty} \frac{|(x+y)^n - y^n|}{x^{n+2} + y^n + K} = 0.$$

Moreover, given $\varepsilon > 0$, for K sufficiently large

$$\frac{|(x+y)^n - y^n|}{x^{n+2} + y^n + K} < \varepsilon$$

for all $(x, y) \in \mathbb{R}^2$.

Proof. The numerator $(x+y)^n - y^n$ is a sum of monomials of the form $Cx^k y^{n-k}$ where $0 < k \leq n$. Hence, it suffices to prove that

$$\lim_{\|(x,y)\| \rightarrow \infty} \frac{|x|^k |y|^{n-k}}{x^{n+2} + y^n + K} = 0$$

for $0 < k \leq n$.

If, for some $\varepsilon > 0$,

$$\frac{|x|^k |y|^{n-k}}{x^{n+2} + y^n + K} \geq \varepsilon$$

we want to show that there is an upper bound for $|x|$ and $|y|$.

We first observe that

$$\frac{|x|^k}{|y|^k} = \frac{|x|^k |y|^{n-k}}{|y|^n} > \frac{|x|^k |y|^{n-k}}{x^{n+2} + y^n + K} \geq \varepsilon$$

or

$$|x| > \varepsilon^{1/k} |y|. \tag{1}$$

Similarly,

$$\frac{|y|^{n-k}}{|x|^{n-k+2}} = \frac{|x|^k |y|^{n-k}}{|x|^{n+2}} > \frac{|x|^k |y|^{n-k}}{x^{n+2} + y^n + K} \geq \varepsilon.$$

This implies that

$$|y|^{n-k} > \varepsilon |x|^{n-k+2} \tag{2}$$

and we note that $n - k + 2 > 0$. In the case that $k = n$ we note that equation (2) implies that $|x|$ is bounded and then equation (1) implies that $|y|$ is bounded.

However, when $k < n$, we have

$$|y| > E |x|^d \tag{3}$$

where

$$E = \varepsilon^{1/(n-k)} \quad \text{and} \quad d = \frac{n-k+2}{n-k} = 1 + \frac{2}{n-k}.$$

Combining equations (1) and (3), we see that

$$|x| > \varepsilon^{1/k} |y| > \varepsilon^{1/k} E |x|^d.$$

Since $d > 1$ this clearly implies that $|x|$ is bounded by a constant depending only on n and ε . Then equation (1) implies that $|y|$ is also bounded. The contrapositive of these assertions is that for $\|(x, y)\|$ sufficiently large, we have

$$\frac{|x|^k |y|^{n-k}}{x^{n+2} + y^n + K} < \varepsilon$$

which implies the desired limit.

To prove the second assertion of the lemma, we observe that we have shown that there is a constant $M > 0$ such that

$$\frac{(x+y)^n - y^n}{x^{n+2} + y^n + K} < \varepsilon$$

whenever $\|(x, y)\| > M$. Moreover, the constant M is independent of K . Hence, clearly if K is sufficiently large, this inequality will hold for all (x, y) . □

Consider the group \mathbb{Z}^n of n -tuples of integers and provide it with a linear order \succ which is the lexicographic ordering, i.e. $(x_1, \dots, x_n) \prec (y_1, \dots, y_n)$ if and only if $x_i = y_i$ for $1 \leq i < k$ and $x_k < y_k$ for some $0 \leq k \leq n$. We are now prepared to define a set of closed intervals in one-to-one correspondence with elements of \mathbb{Z}^n . As previously mentioned, we will make this definition with a positive parameter K which will be used subsequently to get generators of our action in an arbitrary C^1 neighborhood of the identity.

Definition 2.3. For $K > 0$ let $B_K : \mathbb{Z}^n \rightarrow \mathbb{R}$ be defined by

$$\begin{aligned} B_K(q_1, q_2, \dots, q_n) &= K + \sum_{j=1}^n q_j^{2n-2j+2} \\ &= q_1^{2n} + q_2^{2n-2} + \dots + q_{n-1}^4 + q_n^2 + K \end{aligned}$$

and let the constant S_K be defined by

$$S_K = \sum_{(q_1, q_2, \dots, q_n) \in \mathbb{Z}^n} \frac{1}{B_K(q_1, q_2, \dots, q_n)}.$$

For (r_1, r_2, \dots, r_n) , we define $S_K(r_1, r_2, \dots, r_n)$ by

$$S_K(r_1, r_2, \dots, r_n) = \sum_{(q_1, q_2, \dots, q_n) \prec (r_1, r_2, \dots, r_n)} \frac{1}{B_K(q_1, q_2, \dots, q_n)}.$$

Finally we define the closed interval

$$I_K(r_1, r_2, \dots, r_n) = [S_K(r_1, r_2, \dots, r_n), S_K(r_1, r_2, \dots, r_n + 1)].$$

Note that the sum defining S_K converges, for example by the integral and comparison tests, so that S_K is well defined. We will denote the interval $[0, S_K]$ by I_K and we note that it is nearly the union of the intervals $I_K(r_1, r_2, \dots, r_n)$.

LEMMA 2.4. *There is a countable closed set J_K in the interval $I_K = [0, S_K]$, such that*

$$I_K = J_K \cup \left(\bigcup_{(q_1, q_2, \dots, q_n) \in \mathbb{Z}^n} I_K(q_1, q_2, \dots, q_n) \right).$$

Proof. Define J_K by the equality in the statement of the lemma. From the definitions it follows that every point J_k is the limit of one of the Cauchy sequences $\{S_K(r_1, \dots, r_i, \dots, r_n)\}$ as r_i ranges from 1 to either ∞ or $-\infty$ and the other $r_j, j \neq i$ are fixed. It follows that J_K is countable. The set J_K is closed since its complement is clearly open. □

We note that the intervals $\{I_K(q_1, q_2, \dots, q_n)\}$ occur in the interval I_K in exactly the order given by \prec . They have disjoint interiors but each such interval intersects its successor in a common endpoint.

Definition 2.5. Let $\nu : I_K \setminus J_K \rightarrow \mathbb{Z}^n$ be defined by setting $\nu(x) = (q_1, q_2, \dots, q_n)$ if $x \in I_K(q_1, q_2, \dots, q_n)$ and $x \notin I_K(q_1, q_2, \dots, q_{n+1})$.

LEMMA 2.6. *If K is sufficiently large, then for every $\alpha \in \mathcal{N}_n$ there exists a homeomorphism $g_\alpha : I_K \rightarrow I_K$ such that for each $(q_1, \dots, q_n) \in \mathbb{Z}^n$,*

- (1) $g_\alpha(I_K(q_1, \dots, q_n)) = I_K(\alpha(q_1, \dots, q_n))$; and
- (2) $g_{\alpha\beta}(x) = g_\alpha(g_\beta(x))$ for all $\alpha, \beta \in \mathcal{N}_n$ and all $x \in I_K$; and
- (3) for $x \in I_K(q_1, \dots, q_n)$, $g_\alpha(x) = \phi_{b_1, b_2}(x - c_1) + c_2$, where

$$\begin{aligned} b_1 &= |I_K(q_1, \dots, q_n)| = B_K(q_1, \dots, q_n)^{-1}, \\ b_2 &= |I_K(\alpha(q_1, \dots, q_n))| = B_K(\alpha(q_1, \dots, q_n))^{-1}, \\ c_1 &= S_K(q_1, \dots, q_n), \quad c_2 = S_K(\alpha(q_1, \dots, q_n)) \end{aligned}$$

and $\phi_{b_1, b_2} : [0, b_1] \rightarrow [0, b_2]$ is the diffeomorphism guaranteed by Lemma 2.1.

Proof. For $x \in I_K(q_1, \dots, q_n)$, we define $g_\alpha(x)$ to be $\phi_{b_2}(\phi_{b_1}^{-1}(x - c_1)) + c_2$. The values of the constants b_j, c_j , for $j = 1, 2$ were chosen so that (1) holds. This gives a homeomorphism g_α from $I_K \setminus J_K$ to itself which preserves the order on the interval I_K . Since J_K is a closed countable subset of I_K we may extend g_α to all of I_K in the unique way which makes it an order-preserving function on I_K . Clearly this makes g_α a homeomorphism of I_K to itself.

In order to show property (2), we let $b_3 = B_K(\beta\alpha(q_1, \dots, q_n))^{-1}$ and $c_3 = S_K(\beta\alpha(q_1, \dots, q_n))$. Then if $x \in I_K(q_1, \dots, q_n)$,

$$\begin{aligned} g_\beta(g_\alpha(x)) &= \phi_{b_2, b_3}(g_\alpha(x) - c_2) + c_3 \\ &= \phi_{b_2, b_3}(\phi_{b_1, b_2}((x - c_1) + c_2 - c_2)) + c_3, \quad \text{by Lemma 2.1} \\ &= \phi_{b_1, b_3}(x - c_1) + c_3 \\ &= g_{\beta\alpha}(x). \end{aligned}$$

Since this holds for any $(q_1, \dots, q_n) \in \mathbb{Z}^n$ we have shown $g_\beta(g_\alpha(x)) = g_{\beta\alpha}(x)$ for a dense set of $x \in I_K$. Continuity then implies this holds for all $x \in I_K$. □

Definition 2.7. For $1 \leq i < n$ let $\sigma_i \in \mathcal{N}_n$ denote the matrix with all entries on the diagonal equal to 1, with entry $(i + 1, i)$ equal to 1, and with all other entries 0. We will denote the homeomorphism $g_{\sigma_i} : I_K \rightarrow I_K$ by g_i .

The elements $\{\sigma_i\}$ form a set of generators for the group \mathcal{N}_n . Our next objective is to show that, in fact, $g_i = g_{\sigma_i}$ is a C^1 diffeomorphism. For this we will need a sequence of technical lemmas.

LEMMA 2.8. Suppose x_k is a monotonic sequence in $I_K \setminus J_K$ converging to a point of J_K . Then, for each $1 \leq i < n$,

$$\lim_{k \rightarrow \infty} \frac{B_K(\sigma_i(v(x_k)))}{B_K(v(x_k))} = 1.$$

Proof. We may assume without loss of generality that the sequence $\{x_k\}$ is monotonic increasing. For $1 \leq j \leq n, k > 0$, we define $q_j(k)$ by $v(x_k) = (q_1(k), q_2(k), \dots, q_n(k))$. Then each sequence $\{q_j(k)\}_{k=1}^\infty$ is monotonic increasing. At least one of these sequences is unbounded, since any bounded ones are eventually constant and if $\{q_j(k)\}$ were eventually constant for all $j \leq n$ then the sequence of intervals $I_K(v(x_k))$ would eventually be constant and the limit of the sequence $\{x_k\}$ would be in the final interval and, hence, not in J_K . Let r be the smallest j such that $\{q_j(k)\}$ is unbounded. Then since $\{x_k\}$ is monotonic increasing we have $\lim_{k \rightarrow \infty} q_r(k) = \infty$ and for $j < r$ the sequence $\{q_j(k)\}$ is eventually constant.

We note that

$$B_K(\sigma_i(v(x_k))) = B_K(q_1(k), \dots, q_i(k), q_{i+1}(k) + q_i(k), q_{i+2}(k), \dots, q_n(k))$$

and, hence, that

$$\begin{aligned} \frac{B_K(v(x_k)) - B_K(\sigma_i(v(x_k)))}{B_K(v(x_k))} &= \frac{(q_{i+1}(k) + q_i(k))^{2n-2i} - q_{i+1}(k)^{2n-2i}}{B_K(q_1(k), \dots, q_n(k))} \\ &= \frac{P(q_i(k), q_{i+1}(k))}{B_K(q_1(k), \dots, q_n(k))} \end{aligned}$$

where $P(x, y) = (x + y)^{2n-2i} - y^{2n-2i}$.

We first consider the case that $r > i + 1$. Then, for large k , we have that $P(q_i(k), q_{i+1}(k))$ is bounded (in fact eventually constant) so

$$\lim_{k \rightarrow \infty} \frac{B_K(v(x_k)) - B_K(\sigma_i(v(x_k)))}{B_K(v(x_k))} = \lim_{k \rightarrow \infty} \frac{P(q_i(k), q_{i+1}(k))}{B_K(q_1(k), \dots, q_n(k))} = 0$$

and we have the desired result.

In the case $r = i + 1$ or $r = i$, we observe

$$\frac{P(q_i(k), q_{i+1}(k))}{q_1(k)^{2n} + \dots + q_n(k)^2 + K} \leq \frac{P(q_i(k), q_{i+1}(k))}{q_i(k)^{2n-2i+2} + q_{i+1}(k)^{2n-2i} + K}$$

and at least one of $q_i(k)^{2n-2i+2}$ and $q_{i+1}(k)^{2n-2i}$ tends to infinity so, by Lemma 2.2, we again have

$$\lim_{k \rightarrow \infty} \frac{B_K(v(x_k)) - B_K(\sigma_i(v(x_k)))}{B_K(v(x_k))} = \lim_{k \rightarrow \infty} \frac{P(q_i(k), q_{i+1}(k))}{B_K(q_1(k), \dots, q_n(k))} = 0.$$

Finally, in the case $r < i$,

$$\frac{|P(q_i(k), q_{i+1}(k))|}{B_K(q_1(k), \dots, q_n(k))} \leq \frac{|P(q_i(k), q_{i+1}(k))|}{q_r(k)^{2n-2r+2} + q_i(k)^{2n-2i+2} + q_{i+1}(k)^{2n-2i} + K}$$

and $|q_r(k)|$ tends to infinity. But given $\varepsilon > 0$, by Lemma 2.2 there is an $M > 0$ such that whenever $\|(q_i(k), q_{i+1}(k))\| > M$ we have

$$\begin{aligned} \frac{|P(q_i(k), q_{i+1}(k))|}{q_r(k)^{2n-2r+2} + q_i(k)^{2n-2i+2} + q_{i+1}(k)^{2n-2i} + K} \\ \leq \frac{|P(q_i(k), q_{i+1}(k))|}{q_i(k)^{2n-2i+2} + q_{i+1}(k)^{2n-2i} + K} < \varepsilon. \end{aligned}$$

However, if $\|(q_i(k), q_{i+1}(k))\| \leq M$ and $|q_r(k)|$ is sufficiently large,

$$\frac{|P(q_i(k), q_{i+1}(k))|}{q_r(k)^{2n-2r+2} + q_i(k)^{2n-2i+2} + q_{i+1}(k)^{2n-2i} + K} < \varepsilon.$$

So in all cases we have the desired limit

$$\lim_{k \rightarrow \infty} \frac{|B_K(v(x_k)) - B_K(\sigma_i(v(x_k)))|}{B_K(v(x_k))} = 0 \tag{4}$$

which implies

$$\lim_{k \rightarrow \infty} \left| 1 - \frac{B_K(\sigma_i(v(x_k)))}{B_K(v(x_k))} \right| = 0$$

and, hence, that

$$\lim_{k \rightarrow \infty} \frac{B_K(\sigma_i(v(x_k)))}{B_K(v(x_k))} = 1. \quad \square$$

LEMMA 2.9. Suppose x_k is a monotonic sequence in $I_K \setminus J_K$ converging to a point of J_K . Then for each $1 \leq i < n$,

$$\lim_{k \rightarrow \infty} g'_i(x_k) = 1.$$

Proof. For $x \in I_K(q_1, \dots, q_n)$, g_i is defined by $g_i(x) = \phi_{b_1, b_2}(x - c_2) + c_1$, for some constants c_1 and c_2 , where

$$b_1 = b_1(k) = \frac{1}{B_K(v(x_k))} \quad \text{and} \quad b_2 = b_2(k) = \frac{1}{B_K(\sigma_i(v(x_k)))}$$

so $g'_i(x_k) = \phi'_{b_1, b_2}(x_k)$.

We wish to show that, given $\varepsilon > 0$ for k sufficiently large, $|1 - g'_i(x_k)| < \varepsilon$. To do this, by Lemma 2.1 we need only show that, for any $\delta > 0$,

$$\left| \frac{b_2(k)}{b_1(k)} - 1 \right| < \delta$$

for sufficiently large k .

But

$$\left| \frac{b_2(k)}{b_1(k)} - 1 \right| = \left| \frac{B_K(v(x_k))}{B_K(\sigma_i(v(x_k)))} - 1 \right|$$

which, by Lemma 2.8, tends to zero as k tends to infinity. Hence,

$$\left| \frac{b_2(k)}{b_1(k)} - 1 \right| < \delta$$

for k sufficiently large. □

The proofs of Lemmas 2.10 and 2.11 are parallel to those of Lemmas 2.8 and 2.9. The difference is that before we were interested in the limiting values of some quantities as a sequence $\{x_k\}$ of values of x in $I_K \setminus J_K$ converged, while now we are interested in estimating the same quantities but, uniformly in x , as the parameter K tends to infinity.

LEMMA 2.10. *Suppose $1 \leq i < n$. Given $\varepsilon > 0$ there is a $K_0 > 0$ such that, whenever $K > K_0$,*

$$\left| \frac{B_K(\sigma_i(v(x)))}{B_K(v(x))} - 1 \right| < \varepsilon$$

for all $x \in I_K \setminus J_K$.

Proof. For $1 \leq j \leq n$, we define $q_j(x)$ by $v(x) = (q_1(x), q_2(x), \dots, q_n(x))$.

We note that

$$B_K(\sigma_i(v(x))) = B_K(q_1(x), \dots, q_i(x), q_{i+1}(x) + q_i(x), q_{i+2}(x), \dots, q_n(x))$$

and, hence, if $P(u, v) = (u + v)^{2n-2i} - v^{2n-2i}$, we have

$$\begin{aligned} \left| \frac{B_K(v(x)) - B_K(\sigma_i(v(x)))}{B_K(v(x))} \right| &= \left| \frac{(q_{i+1}(x) + q_i(x))^{2n-2i} - q_{i+1}(x)^{2n-2i}}{B_K(q_1(x), \dots, q_n(x))} \right| \\ &= \frac{|P(q_i(x), q_{i+1}(x))|}{B_K(q_1(x), \dots, q_n(x))} \\ &\leq \frac{|P(q_i(x), q_{i+1}(x))|}{q_i(x)^{2n-2i+2} + q_{i+1}(x)^{2n-2i} + K}. \end{aligned}$$

So by the second part of Lemma 2.2, we conclude that if K is sufficiently large,

$$\left| \frac{B_K(v(x)) - B_K(\sigma_i(v(x)))}{B_K(v(x))} \right| < \varepsilon. \tag{5}$$

From this we see that

$$\left| 1 - \frac{B_K(\sigma_i(v(x)))}{B_K(v(x))} \right| < \varepsilon$$

as desired. □

LEMMA 2.11. *Given $\varepsilon > 0$, if K is chosen sufficiently large then, for all $x \in I_K \setminus J_K$ and all $1 \leq i < n$,*

$$|g'_i(x) - 1| < \varepsilon.$$

Proof. For $x \in I_K(q_1, \dots, q_n)$, g_i is defined by $g_i(x) = \phi_{b_1, b_2}(x - c_2) + c_1$, for some constants c_1 and c_2 , where

$$b_1 = b_1(x) = \frac{1}{B_K(v(x))} \quad \text{and} \quad b_2 = b_2(x) = \frac{1}{B_K(\sigma_i(v(x)))}.$$

So $g'_i(x) = \phi'_{b_1, b_2}(x)$.

We wish to show that given $\varepsilon > 0$, if K is sufficiently large then $|1 - g'_i(x)| < \varepsilon$. To do this, by Lemma 2.1, we need only show that given any $\delta > 0$ there is a $K_0 > 0$ such that $K > K_0$ implies

$$\left| \frac{b_2(x)}{b_1(x)} - 1 \right| < \delta$$

for all $x \in I_K \setminus J_K$.

But

$$\left| \frac{b_2(x)}{b_1(x)} - 1 \right| = \left| \frac{B_K(\sigma_i(v(x)))}{B_K(v(x))} - 1 \right|$$

and the result follows from Lemma 2.10. □

PROPOSITION 2.12. *For K sufficiently large, the homeomorphism $g_i : I_K \rightarrow I_K$ is a C^1 diffeomorphism with derivative 1 at both endpoints. Given $\varepsilon > 0$, there exists K_0 such that whenever $K > K_0$, we have*

$$|g'_i(x) - 1| < \varepsilon$$

for all $x \in I_K$.

Proof. We know that the function $f(x) = g'_i(x)$ exists and is continuous on $I_K \setminus J_K$. By Lemma 2.9, we can extend it continuously to all of I_K by setting $f(x) = 1$ for $x \in J_K$.

We define a C^1 function F by

$$F(x) = \int_0^x f(t) dt$$

and will show that $F(x) = g_i(x)$. To see this, let $\phi(x) = g_i(x) - F(x)$. Then $\phi(0) = 0$ and $\phi(x)$ is a continuous function whose derivative exists and is zero on $I_K \setminus J_K$. Since J_K is countable, $\phi(J_K)$ has measure zero. But $I_K \setminus J_K$ has countably many components on each of which ϕ is constant. It follows that $\phi(I_K)$ has measure zero and, hence, $\phi(I_K) = \{0\}$. Therefore, $g_i(x) = F(x)$ is C^1 .

Lemma 2.11 and the fact that $g'_i(x) = 1$ for $x \in J_K$ imply that, for K sufficiently large,

$$|g'_i(x) - 1| < \varepsilon$$

for all $x \in I_K$. The inverse function theorem then implies that g_i is a C^1 diffeomorphism. □

Recall that we have given the group \mathbb{Z}^n the lexicographic ordering, \succ i.e. $(x_1, \dots, x_n) \succ (y_1, \dots, y_n)$ if and only if $x_i = y_i$ for $1 \leq i < k$ and $x_k > y_k$ for some $0 \leq k \leq n$. We note that this order is translation invariant; indeed, $(x_1, \dots, x_n) \succ (y_1, \dots, y_n)$ if and only if $(x_1 - y_1, \dots, x_n - y_n) \succ (0, \dots, 0)$.

It is well known and easy to check that the nilpotent group \mathcal{N}_n of $n \times n$ lower-triangular integer matrices with ones on the diagonal acts on \mathbb{Z}^n preserving the order \succ .

THEOREM 2.13. *The group \mathcal{N}_n is isomorphic to a subgroup of $\text{Diff}^1(M)$ for $M = \mathbb{R}, S^1$ or I . For $M = S^1$ or I the elements of this subgroup corresponding to the generators $\{\sigma_i\}$ of \mathcal{N}_n may be chosen to be in an arbitrary neighborhood of the identity in $\text{Diff}^1(M)$.*

Proof. We first consider the case that $M = I$. Given $\varepsilon > 0$, we choose K sufficiently large that the conclusion of Proposition 2.12 holds. We define $\Phi : \mathcal{N}_n \rightarrow \text{Homeo}(I_K)$ by

$\Phi(\alpha) = g_\alpha$. Lemma 2.6 asserts that Φ is an injective homomorphism. Proposition 2.12 asserts that $g_i = \Phi(\sigma_i)$ is a C^1 diffeomorphism so, in fact, $\Phi(\mathcal{N}_n)$ lies in $\text{Diff}^1(I_K)$.

Define the injective homomorphism $\Psi : \mathcal{N}_n \rightarrow \text{Diff}^1(I)$ by $\Psi(\alpha)(x) = S_K \Phi(\alpha)(x/S_K) = S_K g_\alpha(x/S_K)$. Restricting this action to the interior of I gives an action on \mathbb{R} .

Note that every element of $\Psi(\mathcal{N}_n)$ has derivative 1 at both endpoints of I . Gluing endpoints together gives an action on S^1 .

In the case $M = S^1$ or I , we clearly have $|\Psi(\sigma_i)'(x) - 1| < \varepsilon$ by Proposition 2.12 \square

Now every finitely-generated, torsion-free nilpotent group N is isomorphic to a subgroup of \mathcal{N}_n for some n (see Theorem 4.12 of [Ra] and its proof). This together with Theorem 2.13 immediately implies Theorem 1.2.

2.3. C^∞ actions on \mathbb{R} . For certain nilpotent groups we can give a C^∞ action on \mathbb{R} . However, we will see in the next section that for $n > 2$ there is no C^2 action of \mathcal{N}_n on \mathbb{R} .

Proof of Theorem 1.3. Choose a non-trivial C^∞ diffeomorphism α of $[0, 1]$ to itself such that for $j = 0, 1$ we have $\alpha(j) = j$, $\alpha'(j) = 1$, and $\alpha^{[k]}(j) = 0$, for all $k > 1$.

Define three C^∞ diffeomorphisms $f, h_0, h_1 : \mathbb{R} \rightarrow \mathbb{R}$ by

$$\begin{aligned} f(x) &= x - 1, \\ h_0(x) &= \alpha(x - m) + m \quad \text{for } x \in [m, m + 1], \\ h_1(x) &= \alpha^m(x - m) + m \quad \text{for } x \in [m, m + 1]. \end{aligned}$$

Then it is easy to check that h_0 and h_1 commute, f and h_0 commute and $[f, h_1] = f^{-1}h_1^{-1}fh_1 = h_0$. Hence, the group generated by f and h_1 is nilpotent with degree of nilpotency 2.

Given any $n > 0$, we will inductively define h_k for $0 \leq k \leq n$ in such a way that $h_k(m) = m$ for $m \in \mathbb{Z}$, $[f, h_k] = h_{k-1}$ for $k > 1$ and $h_i h_j = h_j h_i$. We do this by letting $h_k(x) = x$ for $x \in [0, 1]$ and recursively defining h_k^{-1} . We first define it for $x > 1$ by

$$h_k^{-1}(x) = h_{k-1}^{-1} f^{-1} h_k^{-1} f(x) \quad \text{for } x > 1.$$

Note this is well defined recursively because if $x \in [n, n + 1]$ the right-hand side requires only that we know the value of $h_k^{-1}(f(x))$ and $f(x) \in [n - 1, n]$. We also note that $h_k^{-1} = h_{k-1}^{-1} f^{-1} h_k^{-1} f$ implies $h_{k-1} h_k^{-1} = f^{-1} h_k^{-1} f$, so $h_{k-1}(x) = f^{-1} h_k^{-1} f h_k(x)$ for all $x > 1$.

Negative values of x are handled similarly. We define

$$h_k^{-1}(x) = f h_{k-1} h_k^{-1} f^{-1}(x) \quad \text{for } x < 0.$$

This is well defined recursively for $x < 0$ because if $x \in [-n, -n + 1]$ the right-hand side only requires that we know the value of $h_k^{-1}(f^{-1}(x))$ and $f^{-1}(x) \in [-n + 1, -n + 2]$. Again $h_k^{-1} = f h_{k-1} h_k^{-1} f^{-1}$ implies $f^{-1} h_k^{-1} f = h_{k-1} h_k^{-1}$ so $h_{k-1}(x) = f^{-1} h_k^{-1} f h_k(x)$ for all $x < 0$.

We further note that, from this definition, one easily sees inductively that $h_k(x) = x$ for $x \in [-1, 0]$ for all $k \geq 2$. Finally we observe that this implies for $x \in [0, 1]$ that we have $f^{-1} h_k^{-1} f h_k(x) = x$ so $f^{-1} h_k^{-1} f h_k(x) = h_{k-1}(x)$.

It is clear from the relations $[f, h_k] = h_{k-1}$ for $k > 1$, $[f, h_0] = \text{id}$ and $h_i h_j = h_j h_i$ that the group generated by f and the h_k is nilpotent of degree at most n . The degree of nilpotency is at least n since h_0 is a non-trivial n -fold commutator. \square

If $n = 2$, the group G previously constructed is isomorphic to the group \mathcal{N}_3 of 3×3 lower triangular matrices. In general, G is isomorphic to a semi-direct product of Z^n and Z , where the Z action on Z^n is given by the $n \times n$ lower triangular matrix with ones on the diagonal and subdiagonal and zeroes elsewhere. It is metabelian, i.e. solvable with derived length two. We will see later that this is a necessary condition for a smooth action on \mathbb{R} .

2.4. *Residually torsion-free nilpotent groups.* In this section we give a construction of actions on \mathbb{R} of a fairly large class of groups. These actions will typically not be irreducible.

Definition 2.14. A group G is called *residually torsion-free nilpotent* if, for every non-trivial element $g \in G$, there is a torsion-free nilpotent group N and a homomorphism $\phi : G \rightarrow N$ such that $\phi(g)$ is non-trivial. Equivalently, the intersection of every term in the lower central series for G is trivial.

Proof of Theorem 1.6. Since G is finitely generated, it contains countably many elements. Let $\{g_m \mid m \in \mathbb{Z}^+\}$ be an enumeration of the non-trivial elements of G . Let $\phi_m : G \rightarrow N_m$ be the homomorphism to a torsion-free nilpotent group guaranteed by residual nilpotence, so $\phi_m(g_m)$ is non-trivial. Replacing N_m by $\phi_m(G)$ if necessary we may assume N_m is finitely generated.

Let $I_m = [1/(m + 1), 1/m]$. Using Theorem 1.2, choose an effective action of N_m by C^1 diffeomorphisms on the interval I_m . Recall that this action has the property that the derivative of every element is 1 at the endpoints of I_m . In addition, by Theorem 1.2, we may choose this action so that the derivative of $\phi_m(g_i)$ satisfies

$$|\phi_m(g_i)'(x) - 1| < \frac{1}{2^m}$$

for all $x \in I_m$ and all $1 \leq i \leq m$.

We then define the action of G by $g(x) = \phi_m(g)(x)$ for $x \in I_m$ and $g(0) = 0$ for all $g \in G$. Clearly each g_m is a C^1 diffeomorphism with $g'_m(0) = 1$. The action is effective because $\phi_m(g)$ acts non-trivially on I_m .

Since every element of G has derivative 1 at both endpoints of I , we may glue the endpoints together to give a C^1 action on S^1 . \square

It is an old result of Magnus that free groups and surface groups are residually torsion-free nilpotent. In particular, Theorem 1.6 gives a C^1 action of surface groups on \mathbb{R} , I and S^1 : we do not know another proof that such actions exist.

Another interesting example is the *Torelli group* T_g , which is defined to be the kernel of the natural action of the mapping class group of a genus g surface Σ_g on $H_1(\Sigma_g, \mathbb{Z})$. For $g \geq 3$, Johnson proved that T_g is finitely generated and Bass and Lubotzky proved that T_g is residually torsion-free nilpotent. Similarly, the kernel of the action of the outer automorphism group of a free group is finitely generated and residually torsion-free nilpotent. Hence, by Theorem 1.6, both of these groups are subgroups of $\text{Diff}^1(M)$ for

$M = \mathbb{R}, I, S^1$. In particular, the Torelli group is left-orderable. It is not known whether or not mapping class groups are left-orderable, although Thurston has proven that braid groups are left-orderable.

3. Restrictions on C^2 actions

In the previous sections we showed that actions by nilpotent subgroups of homeomorphisms are abundant. By way of contrast in the next two sections, we show that nilpotent groups of C^2 diffeomorphisms or PL homeomorphisms are very restricted. In this section we focus on C^2 actions.

3.1. *Kopell's Lemma.* Our primary tool is the following remarkable result of Nancy Kopell, which is Lemma 1 of [K].

THEOREM 3.1. (Kopell's Lemma) *Suppose f and g are C^2 orientation-preserving diffeomorphisms of an interval $[a, b]$ or (a, b) and $fg = gf$. If f has no fixed point in (a, b) and g has a fixed point in (a, b) , then $g = \text{id}$.*

We will primarily use a consequence of this result which we now present.

Definition 3.2. We will denote the frontier of $\text{Fix}(f)$ by $\partial \text{Fix}(f)$, i.e. the set $\partial \text{Fix}(f) = \text{Fix}(f) \setminus \text{Int}(\text{Fix}(f))$.

LEMMA 3.3. *Suppose f and g are commuting orientation-preserving C^2 diffeomorphisms of \mathbb{R} , each of which has a fixed point. Then f preserves each component of $\text{Fix}(g)$ and vice versa. Moreover, $\partial \text{Fix}(g) \subset \text{Fix}(f)$ and vice versa. The same result is true for C^2 diffeomorphisms of a closed or half-open interval, in which case the requirement that f and g have fixed points is automatically satisfied by an endpoint.*

Proof. The proof is by contradiction. Assume X is a component of $\text{Fix}(g)$ and $f(X) \neq X$. Since f and g commute, $f(\text{Fix}(g)) = \text{Fix}(g)$ so $f(X)$ is some component of $\text{Fix}(g)$. Hence, $f(X) \neq X$ implies $f(X) \cap X = \emptyset$. Let x be an element of X and, without loss of generality, assume $f(x) < x$. Define

$$a = \lim_{n \rightarrow \infty} f^n(x) \quad \text{and} \quad b = \lim_{n \rightarrow -\infty} f^n(x).$$

Then at least one of the points a and b is finite since f has a fixed point. Also a and b (if finite) are fixed under both f and g , and f has no fixed points in (a, b) . Thus Kopell's Lemma (Theorem 3.1) implies that $g(y) = y$ for all $y \in (a, b)$ contradicting the hypothesis that X is a component of $\text{Fix}(g)$. The observation that $\partial \text{Fix}(f) \subset \text{Fix}(g)$ follows from the fact that components of $\text{Fix}(f)$ are either points or closed intervals so $x \in \partial \text{Fix}(f)$ implies that either $\{x\}$ is a component of $\text{Fix}(f)$ or x is the endpoint of an interval which is a component of $\text{Fix}(f)$ so, in either case, the fact that g preserves this component implies $x \in \text{Fix}(g)$.

The proof in the cases that f and g are diffeomorphisms of a closed or half-open interval is the same. \square

Another useful tool is the following folklore theorem (see, e.g., [FS] for a proof).

THEOREM 3.4. (Hölder's Theorem) *Let G be a group acting freely and effectively by homeomorphisms on any closed subset of \mathbb{R} . Then G is abelian.*

3.2. Measure and the translation number. A basic property of finitely generated nilpotent groups of homeomorphisms of a one-manifold M is that they have invariant Borel measures. Of course in the case $M = I$ or T^1 , this follows from the fact that nilpotent groups are amenable and any amenable group acting on a compact Hausdorff space has an invariant Borel probability measure. In the case $M = \mathbb{R}$, this is a special case of a result due to Plante [P] who showed that any finitely generated subgroup of $\text{Homeo}(\mathbb{R})$ with polynomial growth has an invariant measure which is finite on compact sets.

We summarize these facts in the following theorem.

THEOREM 3.5. *Let $M = \mathbb{R}$, S^1 or I . Then any finitely generated nilpotent subgroup of $\text{Homeo}(M)$ has an invariant Borel measure μ which is finite on compact sets.*

If one has an invariant measure for a subgroup of $\text{Homeo}(\mathbb{R})$, it is useful to consider the translation number which was discussed by Plante in [P]. It is an analogue of the rotation number for circle homeomorphisms.

Suppose G is a subgroup of $\text{Homeo}(\mathbb{R})$ which preserves a Borel measure μ that is finite on compact sets. Fix a point $x \in \mathbb{R}$ and for each $f \in G$ define

$$\tau(f) = \begin{cases} \mu([x, f(x))) & \text{if } x < f(x) \\ 0 & \text{if } x = f(x) \\ -\mu([f(x), x)) & \text{if } x > f(x). \end{cases}$$

The function $\tau : G \rightarrow \mathbb{R}$ is called the *translation number*. The following properties observed by Plante in [P] are easy to verify.

PROPOSITION 3.6. *The translation number $\tau : G \rightarrow \mathbb{R}$ is independent of the choice of $x \in \mathbb{R}$ used in its definition. It is a homomorphism from G to the additive group \mathbb{R} . For any $f \in G$ the set $\text{Fix}(f) \neq \emptyset$ if and only if $\tau(f) = 0$.*

3.3. Proof of Theorem 1.1.

THEOREM 1.1. *Any nilpotent subgroup of $\text{Diff}^2(I)$, $\text{Diff}^2([0, 1])$ or $\text{Diff}^2(S^1)$ must be abelian.*

Proof. Since it suffices to show the action is abelian when restricted to any invariant interval, we may assume our action is irreducible.

The case $M = I$ or $M = [0, 1]$. The argument we present here is essentially the same as that given by Plante and Thurston in (4.5) of [PT]. We give it here for completeness and because it is quite simple.

Consider the restriction of N to $(0, 1)$. If no element of N has a fixed point then N is abelian by Hölder's Theorem. Hence we may assume that there is a non-trivial element f with a fixed point. Thus, if h is in the center of N , Lemma 3.3 implies that $\text{Fix}(h) \supset \partial \text{Fix}(f)$ which is non-empty. Another application of Lemma 3.3, states that the

non-empty set $\partial \text{Fix}(h) \subset \text{Fix}(g)$ for any $g \in N$. We have found a global fixed point and contradicted the assumption that N acted irreducibly. We conclude that N is abelian. \square

The case $M = S^1$. Let $N < \text{Diff}^2(S^1)$ be nilpotent. As we observed in Theorem 3.5 there is an invariant measure μ_0 for the action. If any one element has no periodic points then since it is C^2 it is topologically conjugate to an irrational rotation by Denjoy's Theorem (see, e.g., [dM]). Irrational rotations are uniquely ergodic so the invariant measure must be conjugate to Lebesgue measure. It follows that every element is conjugate to a rotation so N is abelian. Hence, we may assume that every element of N has periodic points.

For a homeomorphism of the circle with periodic points, every point which is not periodic is wandering and, hence, not in the support of any invariant measure. We conclude that the periodic points of any element contain the support P of the measure μ_0 . It follows that P is a subset of the periodic points of every element of N .

Since N preserves μ_0 , the group \hat{N} of all lifts to \mathbb{R} of elements of N preserves a measure μ which is the lift of the measure μ_0 on S^1 . We can use μ to define the translation number homomorphism $\tau_\mu: \hat{N} \rightarrow \mathbb{R}$ as previously described.

We observe that commutators of elements in \hat{N} must have translation number 0. The covering translations in \hat{N} are in its center so if \hat{f} and \hat{g} are lifts of f and g , respectively, then $[\hat{f}, \hat{g}]$ is a lift of $[f, g]$. Since $\tau_\mu([\hat{f}, \hat{g}]) = 0$ implies $[\hat{f}, \hat{g}]$ has a fixed point, we may conclude that every element of the commutator subgroup $N_1 = [N, N]$ must have a fixed point. Hence, any commutator fixes every element of P because it fixes one point and, hence, all its periodic points are fixed.

If N is not abelian, there are f and g in N such that $h = [f, g]$ is a non-trivial element of the center of N . Conjugating the equation $f^{-1}g^{-1}fg = h$ by f gives $g^{-1}fgf^{-1} = h$, so $fgf^{-1} = hg$. Repeatedly conjugating by f gives $f^n g f^{-n} = h^n g$. From this we get $g^{-1} f^n g = h^n f^n$ and by repeatedly conjugating with g we obtain $g^{-m} f^n g^m = h^{mn} f^n$. We conclude $g^{-m} f^n g^m f^{-n} = [g^m, f^{-n}] = h^{mn}$. Now let $x \in P$ and let m and n be its period under the maps f and g , respectively. Then h , f^n and g^m all fix the point x . If we split the circle at x , we get an interval and a C^2 nilpotent group of diffeomorphisms generated by h , f^n and g^m . By Theorem 1.1, this group is abelian. Hence, $[g^m, f^{-n}] = h^{mn}$ is the identity. But the only finite-order orientation-preserving homeomorphism of an interval is the identity. We have contradicted the assumption that N is not abelian. \square

3.4. The proof of Theorem 1.5.

THEOREM 1.5. *If N is a nilpotent subgroup of $\text{Diff}^2(\mathbb{R})$ and every element of N has a fixed point, then N is abelian.*

Proof. We first show that there is a global fixed point for N . Consider $\text{Fix}(h)$ the fixed point set of some non-trivial element h of the center of N . We can apply Lemma 3.3 and observe that for any $f \in N$, $\partial \text{Fix}(h) \subset \text{Fix}(f)$. Thus the non-empty set $\partial \text{Fix}(h)$ is fixed pointwise by every element of N .

If $a \in \text{Fix}(h)$ then both $[a, \infty)$ and $(-\infty, a]$ are invariant by N and each is diffeomorphic to $[0, 1)$. We can thus apply Theorem 1.1 and conclude that the restriction of N to each of them is abelian. \square

3.5. The proof of Theorem 1.4.

THEOREM 1.4. *Every nilpotent subgroup of $\text{Diff}^2(\mathbb{R})$ is metabelian, i.e. has an abelian commutator subgroup.*

Proof. Let $N < \text{Diff}^2(\mathbb{R})$ be nilpotent. By Theorem 3.5 there is an invariant Borel measure μ on \mathbb{R} which is finite on compact sets and from it we can define a translation number homomorphism $\tau_\mu : N \rightarrow \mathbb{R}$. According to Proposition 3.6, if N_0 is the kernel of τ_μ then every element of N_0 has a fixed point. Hence, the result follows from Theorem 1.5. \square

4. PL actions

Recall that a *piecewise linear homeomorphism* of a one-manifold M is a homeomorphism f for which there exist finitely many subintervals of M on which f is linear. Let $\text{PL}(M)$ denote the group of piecewise-linear homeomorphisms of M . This group has been studied by several authors (see, for example, [BS] and [T2]).

THEOREM 4.1. *Any nilpotent subgroup of $\text{PL}(I)$ or $\text{PL}(S^1)$ is abelian.*

Proof. Suppose first that $N < \text{PL}(I)$. Note that there is a natural homomorphism $\psi : \text{PL}(I) \rightarrow \mathbb{R}^* \times \mathbb{R}^*$ given by

$$\psi(f) = (f'(0), f'(1)).$$

As $\mathbb{R} \times \mathbb{R}$ is abelian, $\psi(f) = (1, 1)$ for any non-trivial commutator in $\text{PL}(I)$.

If N is not abelian, then there is a non-trivial commutator f lying in the center of N . Hence, $f'(0) = 1$, so that f is the identity on some interval $[0, a]$ which we take to be maximal. Since every element of N commutes with f , we must have that $g([0, a]) = [0, a]$ for every $g \in N$. But then a is also a fixed point of every element of N , so that f is a non-trivial commutator of elements which fixes a . We conclude that $f'(a) = 1$ also. Hence, f is the identity on $[a, b]$ for some $b > a$ and we contradict the maximality of a . We conclude that the center of N has no non-trivial commutator, so N is abelian.

Now if $N < \text{PL}(S^1)$ then the proof is nearly word for word identical to the proof of Theorem 1.1. We note that Denjoy's Theorem (see [dM]) is also valid for PL homeomorphisms of the circle, i.e. any PL homeomorphism of S^1 without periodic points is topologically conjugate to an irrational rotation. With that observation the proof that a PL action of N on S^1 is abelian is identical to the proof of Theorem 1.1 except that the appeal to Theorem 1.1 in the case of the interval is replaced by an appeal to the first part of this theorem, namely the fact that a PL action of a nilpotent group on I is abelian. \square

Acknowledgements. BF was supported in part by the NSF and by the Sloan Foundation. JF was supported in part by NSF grants DMS9803346 and DMS0099640.

It is a pleasure to thank Dave Witte for making several useful suggestions, in particular pointing us to the references [Ra], [P] and [MR].

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