

Magnetic island suppression by electron cyclotron current drive as converse of a forced reconnection problem

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This paper addresses one aspect of the problem of the suppression of tearing mode magnetic islands by electron cyclotron current drive (ECCD) injection, formulating the problem as the converse of a forced reconnection problem. New physical conditions are discussed which should be considered in the technical approach towards a robust control strategy. Limits on the ECCD deposition are determined to avoid driving the system into regimes where secondary instabilities develop. Numerical simulations confirming the theory are also presented.

Key words: plasma instabilities, plasma nonlinear phenomena, plasma simulation

1. Introduction

One of the most serious tasks to be tackled on the way towards achieving controlled thermonuclear fusion in tokamaks is the prevention or suppression of instabilities related to magnetic reconnection processes. The latter deteriorate the plasma confinement properties and eventually destroy the equilibrium configuration. A very promising technique of counteracting these unstable magnetohydrodynamic (MHD) perturbations is based on the absorption of radiofrequency (rf) waves at the electron cyclotron frequency to drive a highly localized current on the magnetic surfaces where the perturbations grow (Fisch & Boozer 1980; Perkins *et al.* 1997). Significant technical progress has been made in recent years in the efficient generation of current with high power electron cyclotron (EC) wave beams, with the necessary characteristics of focussing and sharpness of the deposition. Similarly, control systems are rapidly progressing towards robust performance as has been recently demonstrated

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in experiments (Maraschek 2012; Koleman *et al.* 2014) and simulations (Fevrier *et al.* 2017). The delivery of large, localized power to the system may however give rise to parasitic processes such as the possible onset of smaller scale structures in a non-constant flux ψ regime (Comisso *et al.* 2016), which may blur detection and hinder the feedback stabilization action. It should be noted that the present problem does not concern some other non-inductive currents methods of magnetic island control such as lower hybrid current drive (LHCD) (Reiman 1983), because the latter can only drive a broad current profile larger than a typical island width.

A critical aspect of the electron cyclotron current drive (ECCD) technique is related to the deposition depth, δ_{CD} . A high focusing on the rational surface where the magnetic island develops is desirable to counteract efficiently the unstable reconnection process (Hegna & Callen 1997; Perkins *et al.* 1997; Welander *et al.* 2013; Rapson *et al.* 2017; Park *et al.* 2018). Experimental success in control has been associated with feedback techniques based on accurate phase tracking, while a blind modulation is expected to induce a loss of control (Monticello, White & Rosenbluth 1978). These expectations are consistent with the assumptions of the Rutherford regime of evolution of a magnetic island (Lazzaro *et al.* 2018), where an island is almost ‘self similarly’ squeezed, without topological changes. However an increasing understanding of the fast spontaneous reconnection processes in other contexts (Comisso, Grasso & Waelbroeck 2015) motivate a theoretical exploration of effects which might occur with high power density injection, considering the non-constant ψ regime. The new aspect that must be considered is related to secondary instabilities that may develop during the control itself. Recently it has been shown (Lazzaro *et al.* 2018), in a series of numerical experiments examining the response to the rf driven current of a magnetic island induced by a reconnection event, that the control current has significant effects on the magnetic topology of the final stationary state as compared to the initial one and that these effects are directly related to the beam width. Secondary instabilities, plasmoid-like (Lazzaro *et al.* 2018) or triple tearing modes (Wang, Ma & Zhang 2016), may develop when an intense driven current has a deposition depth δ_{CD} narrower than the magnetic island separatrix.

In this paper we focus our attention on the theoretical possibility that the injected current drives the system into regimes where narrow current sheets may lead to the development of secondary instabilities, that could limit the efficiency of the control strategy by destroying the Rutherford topology of a magnetic island with a single O -point. Therefore an appropriate feedback should ensure that the rf source suppresses the perturbation even in the case of a fast topological change with secondary structures, and a continuous or intermittent rf injection could be suited to produce an average stabilizing effect. Interestingly, recent experiments and numerical simulations (Felici *et al.* 2012; Fevrier *et al.* 2017) with ‘sweeping’ rf injection demonstrate a technique that can overcome the problems analysed in the present work.

In order to gain a basic understanding of this problem we consider a simple visco-resistive MHD regime, which allows us to carry out analytic calculations adopting the point of view of a converse of the Taylor problem of forced reconnection (Hahm & Kulsrud 1985; Comisso *et al.* 2015). Following this approach we derive an analytic expression for the threshold value of the ratio of the injected current amplitude over the deposition width below which the final stationary controlled state undergoes a secondary plasmoid-like instability phase.

The paper is organized as follows. Section 2 presents the model equations. The converse of the forced reconnection problem is analysed in § 3, where an analytical

expression for the ratio of the deposition depth and the injected current peak below which the control current may lead to a current sheet instability is derived. We will see that the presence of viscosity relax this constraint. Finally, numerical simulations are presented in §4, before our conclusions.

2. Model equations

We consider a plasma described by the two-dimensional reduced MHD model (Strauss 1976). Within this description the magnetic and the velocity fields can be written by means of the flux function ψ and the stream function φ as

$$\mathbf{B}(x, y, t) = B_z \mathbf{e}_z + \nabla \psi(x, y, t) \times \mathbf{e}_z \quad (2.1)$$

$$\mathbf{v}(x, y, t) = -\nabla \varphi(x, y, t) \times \mathbf{e}_z, \quad (2.2)$$

where \mathbf{B} and \mathbf{v} indicate the magnetic and velocity fields, while \mathbf{e}_z is the unit vector along the ignorable coordinate. The flux and the stream function are governed by the Faraday–Ohm law

$$\frac{\partial \psi}{\partial t} + [\varphi, \psi] = -\eta(J - J^{(0)} + J_{\text{CD}}), \quad (2.3)$$

and the vorticity equation

$$\frac{\partial \nabla^2 \varphi}{\partial t} + [\varphi, \nabla^2 \varphi] = [J, \psi] + \mu \nabla^4 \varphi, \quad (2.4)$$

where $J = -\nabla^2 \psi$ is the electric current density and $J^{(0)}$ its equilibrium component. The field J_{CD} represents the externally applied current source aimed at controlling the magnetic island dynamics. Since we assume a current driven by rf power absorption, namely ECCD (Fisch & Boozer 1980), which results in a uniform current distribution on the magnetic surfaces $\psi = \text{const.}$, the control current should be modelled as $J_{\text{CD}} = J_0 D(\psi)$, where $D(\psi)$ is a distribution that takes into account how the source current is deposited on the flux surfaces. Note that the Poisson bracket $[f, g] = \partial_x f \partial_y g - \partial_x g \partial_y f$ includes all of the nonlinearities and represents $\mathbf{E} \times \mathbf{B}$ advection of g when $f = \varphi$ and parallel derivation of g when $f = -\psi$. The dimensionless parameters η and μ are the plasma resistivity, corresponding to the inverse of the Lundquist number, and the kinematic viscosity, respectively. They are linked together through the magnetic Prandtl number $P = \mu/\eta$. We recall that in the adopted (standard) normalization, lengths are scaled to the macroscopic equilibrium magnetic field scale length L , while the time is normalized on the Alfvén time τ_A , defined by the equilibrium poloidal magnetic field.

3. Theoretical analysis

As shown in Lazzaro & Comisso (2011), the problem of the response of a magnetic island to a localized current injection can be analytically treated as a converse of the classical Taylor problem. This problem addresses the response of a tearing stable state to a magnetic perturbation at the boundary of a plasma slab. The solution of this problem, obtained for the first time by Hahm & Kulsrud (1985), shows that two states could formally exist, one with a current sheet at a singular surface (state I) and one with a magnetic island (state II). Lazzaro & Comisso (2011) adopted the magnetic configuration associated with the state II of the Hahm and Kulsrud solution

for analytically investigating the dynamics of a magnetic island in the presence of an external current source. Their results, valid for a resistive plasma, show that a suitable value of controlling current can lead to a new equilibrium state with no magnetic island. More recently, assuming a visco-resistive MHD plasma, it has been shown that the reconnection process in the Taylor problem depends on the external source perturbation (Comisso *et al.* 2015). In particular a new scenario has been identified for sufficiently large boundary perturbations, characterized by the onset of a plasmoid-like instability (Comisso *et al.* 2016). In this section we exploit the results reported in Comisso *et al.* (2015) to extend the previous analysis reported in Lazzaro & Comisso (2011) and to investigate the small scale effects possibly triggered by an external current injection during the magnetic island control.

The solution of the linearized version of (2.3) and (2.4), in the absence of external current sources and assuming a stable equilibrium $\psi_{\text{eq}} \propto x^2$ in the external layer, is given in Hahm & Kulsrud (1985) as:

$$\psi_{\text{out}}(x, y, t) = \left[\psi_{\text{out}}(0, t) \left(\cosh(kx) - \frac{\sinh(kx)}{\tanh(k)} \right) + \Psi_{\Sigma}(t) \frac{\sinh(kx)}{\sinh(k)} \right] \cos(ky), \quad (3.1)$$

where $\Psi_{\Sigma}(t)$ is the amplitude of the time varying magnetic flux externally imposed at the boundary, $k = 2\pi/L_y$ and L_y the slab extension in the y -direction.

Around the rational surface, at $x = 0$, the previous expression can be Taylor expanded and, adopting the same notation of Comisso *et al.* (2015), we can write the outer flux as

$$\psi_{\text{out}}(x, t) = \psi_{\text{out}}(0, t) + \frac{1}{2} (\Delta'_0 \psi_{\text{out}}(t) |x| + \Delta'_s \Psi_{\Sigma}(t)), \quad (3.2)$$

where

$$\Delta'_0 = -\frac{2k}{\tanh(k)} \quad (3.3)$$

is the standard tearing stability parameter (Furth, Killeen & Rosenbluth 1963) and

$$\Delta'_s = \frac{2k}{\sinh(k)} \quad (3.4)$$

parametrizes the discontinuity gradient related to the boundary perturbation.

In the presence of the externally applied control current, the linearized system of equations (2.3) and (2.4) reads

$$\partial_t \psi_1 + kx\phi_1 = \eta[\psi_1'' - J_0 D(\psi)] \quad (3.5)$$

$$\partial_t \phi_1'' = kx\psi_1'' + \mu\phi_1^{IV}, \quad (3.6)$$

where we recall that $D(\psi)$ models the spatial distribution of the control current. Following the calculations carried out in Comisso *et al.* (2015), we consider the change of variable $\hat{x} = kx$. Then, dropping the hats for the sake of clearness, Laplace and Fourier transforming as:

$$f_L(x, g) = \int_0^{\infty} f_1(x, t) e^{-gt} dt \quad (3.7)$$

$$f_F(\theta, g) = \int_{-\infty}^{\infty} f_L(x, g) e^{-i\theta x} dx, \quad (3.8)$$

the set of equations (3.5) and (3.6) become:

$$g\psi_F + i\partial_\theta\phi_F = -\eta(k^2\theta^2\psi_F - J_0D_F), \tag{3.9}$$

$$gk^2\theta^2\phi_F = ik^2\partial_\theta(\theta^2\psi_F) - \mu k^4\theta^4\phi_F. \tag{3.10}$$

Then, eliminating ψ_F from (3.10) by means of (3.9), we obtain the layer equation

$$\partial_\theta \left(\frac{\theta^2}{g + \eta k^2 \theta^2} \partial_\theta \phi_F \right) - \theta^2 (g + \mu k^2 \theta^2) \phi_F = i\eta J_0 \partial_\theta \frac{\theta^2 D_F}{g + \eta k^2 \theta^2}. \tag{3.11}$$

This equation must be solved subject to the condition

$$\lim_{\theta \rightarrow \infty} \phi_F(g, \theta) = 0. \tag{3.12}$$

In addition, the inner solution has to match the outer solution at (relatively) large x , i.e. small θ . This boundary condition can be obtained by neglecting resistivity in the linearized form of (2.3), and substituting $\psi_{out}(x, t)$ with its Taylor expansion around $x=0$. Then, after using the Fourier–Laplace transform, the boundary condition for the inner solution reads:

$$\lim_{\theta \rightarrow 0} \phi_F(g, \theta) = \frac{ig\psi_{Lout}(0, g)}{2} \left(\frac{\Delta(g)}{\pi k\theta} + 1 \right), \tag{3.13}$$

where

$$\Delta(g) \equiv \frac{\Delta_L \psi_{out}(g)}{\psi_{Lout}(0, g)}. \tag{3.14}$$

Applying the Laplace transform to (3.5) and substituting $\psi_L'' = -\int_{-\infty}^{\infty} \theta^2 \psi_F e^{i\theta x} d\theta$ we get the expression of the Laplace transformed flux evaluated at $x=0$ as:

$$\psi_L(0, g) = -\frac{\eta k^2}{g} \lim_{x \rightarrow 0} \int_{-\infty}^{\infty} \theta^2 \psi_F e^{i\theta x} d\theta - \frac{\eta}{g} J_0 D_L(0, g). \tag{3.15}$$

Then ψ_F can be expressed in terms of ϕ_F from (3.10) as

$$\psi_F = \frac{-i\partial_\theta\phi_F - \eta J_0 D_F}{g + \eta k^2 \theta^2}, \tag{3.16}$$

to finally obtain

$$\begin{aligned} \psi_L(0, g) &= \lim_{x \rightarrow 0} \frac{2\eta k^2}{g} \int_0^\infty \frac{i\theta^2 \partial_\theta \phi_F}{g + \eta k^2 \theta^2} e^{i\theta x} d\theta \\ &+ \lim_{x \rightarrow 0} \frac{2\eta^2 k^2 J_0}{g} \int_{-\infty}^\infty \frac{\theta^2 D_F}{g + \eta k^2 \theta^2} e^{i\theta x} d\theta - \frac{\eta J_0 D_L(0, g)}{g}. \end{aligned} \tag{3.17}$$

Now assuming the control current as a compact distribution, or in the limit case of Dirac’s delta, equations (3.17) and (3.11) reduce respectively to

$$\psi_L(0, g) = \frac{2\eta k^2}{g} \int_0^\infty \frac{i\theta^2 \partial_\theta \phi_F}{g + \eta k^2 \theta^2} d\theta - \frac{\eta J_0 D_L(0, g)}{g} \tag{3.18}$$

and

$$\partial_\theta \left(\frac{\theta^2}{g + \eta k^2 \theta^2} \partial_\theta \phi_F \right) - \theta^2 (g + \mu k^2 \theta^2) \phi_F = i \eta J_0 \partial_\theta \frac{\theta^2}{g + \eta k^2 \theta^2}. \tag{3.19}$$

We use the standard asymptotic matching technique to solve (3.19). First, we look for the solution at large values of θ , defined by $g \ll \eta k^2 \theta^2$. In this limit (3.19) reduces to

$$\partial_\theta \frac{\theta^2}{g + \eta k^2 \theta^2} = \frac{2\theta(g + \eta k^2 \theta^2) - 2\eta k^2 \theta^3}{(g + \eta k^2 \theta^2)^2} = \frac{2\theta g}{(g + \eta k^2 \theta^2)^2}. \tag{3.20}$$

This equation can be solved following Comisso *et al.* (2015). The final solution that vanishes correctly as $\theta \rightarrow \infty$ is

$$\phi_{F>} = c_2 \theta^{1/2} K_{1/6} \left(\frac{\theta^3}{3\omega^3} \right), \tag{3.21}$$

where $\omega \equiv (\eta \mu k^4)^{-1/6}$.

In the inequality limit of small θ (i.e. large x), defined by the inequality $\theta < (\mu \eta k^4)^{-1/6}$, the right-hand side of (3.19) reduces to $2\theta g / (g + \eta k^2 \theta^2)^2 \approx 2\theta \rightarrow 0$ and thus

$$\partial_\theta \left(\frac{\theta^2}{g + \eta k^2 \theta^2} \partial_\theta \phi_{F<} \right) = 0. \tag{3.22}$$

Again we follow exactly Comisso *et al.* (2015) and, applying the boundary conditions (3.13), write the final solution as:

$$\phi_{F<} = \left(-\frac{g}{\theta} + \eta k^2 \theta \right) i \frac{\Delta(g)}{2\pi k} \psi_{\text{Lout}}(0, g) - i \frac{g}{2} \psi_{\text{Lout}}(0, g). \tag{3.23}$$

By matching the solutions $\phi_{F>}$ and $\phi_{F<}$ in the overlapping interval we end up with

$$\Delta(g) = g \tau_*, \tag{3.24}$$

where

$$\tau_* = \pi 6^{2/3} \frac{\Gamma(\frac{5}{6})}{\Gamma(\frac{1}{6})} \frac{\mu^{1/6}}{k^{1/3} \eta^{5/6}}. \tag{3.25}$$

When $g \ll \eta k^2 \theta^2$ from (3.18) we can evaluate the reconnected Laplace transformed flux as

$$\psi_L(0, g) = \psi_{\text{Lout}}(0, g) - \frac{\eta J_0 D_L(0, g)}{g}. \tag{3.26}$$

$\psi_{\text{Lout}}(0, g)$ can now be obtained by Laplace transforming the gradient discontinuity evaluated at the rational surface $x = 0$ to get

$$\psi_{\text{Lout}}(0, g) = \frac{\Delta'_s \Psi_\Sigma(g)}{g(\Delta(g) - \Delta'_0)}. \tag{3.27}$$

Then inserting the expression (3.27) into (3.26) we obtain

$$\psi_L(0, g) = \frac{\Delta'_s \Psi_\Sigma(g)}{g(\Delta(g) - \Delta'_0)} - \frac{\eta J_0 D_L(0, g)}{g}. \tag{3.28}$$

If we now define the total external contribution as

$$\Psi_{\text{ext}}(g) = \Psi_{\Sigma} - \eta J_0 D_L(0, g) \frac{\Delta(g) - \Delta'_0}{\Delta'_s}, \tag{3.29}$$

it is clear from (3.29) that a good choice of $J_0(t)$ can control the reconnected flux amplitude, i.e. the island width. This condition can be expressed in terms of a partial suppression parameter G , ($0 < G < 1$), writing $\Psi_{\Sigma} - \Psi_{\text{ext}} = G\Psi_{\Sigma}$. Combining then (3.28) and (3.29) and introducing the Lundquist number $S = 1/\eta$, we obtain the control condition

$$\frac{\Delta(g) - \Delta'_0}{S\Delta'_s} J_0 D_L(0, g) = G\Psi_{\Sigma}, \tag{3.30}$$

and, after using (3.24), we find

$$g\psi_L(0, g) = \frac{\Delta'_s \Psi_{\text{ext}}}{\tau_* \left(S - \frac{\Delta'_0}{\tau_*} \right)}. \tag{3.31}$$

Inverse transforming the previous equation and then integrating we get the final solution for the reconnected flux at the rational surface:

$$\psi(0, t) = \frac{\Delta'_s \Psi_{\text{ext}}}{\Delta'_0} e^{\frac{\Delta'_0 t}{\tau_*}} - \frac{\Delta'_s \Psi_{\text{ext}}}{\Delta'_0}. \tag{3.32}$$

From the previous equation it is clear that with $\psi(0, t)$ proportional to Ψ_{ext} the magnetic island can be suppressed or controlled by a suitable choice of J_0 .

It is important to observe that when a constant ψ island shrinks below a critical value, if the driven current has a scale length (absorption depth) comparable to this critical value, the perturbation can be driven into a non-constant ψ regime, where instability conditions can be reached for tearing unstable current sheets and secondary island structures. Indeed, in the visco-resistive regime, according to Comisso *et al.* (2015, 2016), a nonlinear instability condition should be reached when, under the ECCD effect, the island approaches from above (in a controlled fashion) the dimensionless critical width $w_{\text{crit}} = 4\sqrt{\Psi_{\text{crit}}}$, where

$$\Psi_{\text{crit}} = C \frac{k}{S\Delta'_s} \sqrt{1 + P}. \tag{3.33}$$

Here, C is a parameter related to the marginally stable current sheets aspect ratio. This critical condition for the development of the plasmoid instability can be transferred into a condition on the EC current beam size compared to the island width:

$$\Psi_{\text{ext}} = \Psi_{\Sigma} (1 - G) \geq \frac{\eta C k \sqrt{1 + P}}{\Delta'_s}. \tag{3.34}$$

Exploiting (3.30) this condition can be rewritten as:

$$J_0 D_L(0, g) \frac{\Delta(g) - \Delta'_0}{S G \Delta'_s} \geq \frac{\eta C k \sqrt{1 + P}}{\Delta'_s}. \tag{3.35}$$

If we assume a Gaussian behaviour of width δ_{CD} for the spatial distribution $D(\psi)$, we can rewrite the previous equation as

$$\frac{2J_0}{\delta_{\text{CD}}\sqrt{\pi}} \frac{\Delta(g) - \Delta'_0}{SG\Delta'_s} \geq \frac{\eta Ck\sqrt{1+P}}{\Delta'_s}, \quad (3.36)$$

where J_0 is the total injected current at the beginning of the control. This expression can be read as a condition for the deposition length of the control current respect of the peaking value as:

$$\frac{\delta_{\text{CD}}}{J_0} \leq \frac{\sqrt{\pi}(1-G)(\Delta(g) - \Delta'_0)}{2GCk\sqrt{1+P}}. \quad (3.37)$$

We note that given a deposition depth and a current drive the presence of the viscosity makes it harder to reach the plasmoids-like regime.

4. Numerical results

The theoretical results reported in the previous section highlight the effects of the amplitude J_0 and the width δ_{CD} of the ECCD on the control of a magnetic island sustained by a boundary forcing contribution. However this analysis is quite general and remains valid, at least qualitatively, also for spontaneous reconnection events, typical of the tokamak scenarios (White 1986). Recent numerical simulations (Lazzaro *et al.* 2018), in fact, pointed out the role of the ECCD beam width on the onset of plasmoid-like instabilities when the control is applied on a large, nonlinear magnetic island rising from a linearly unstable equilibrium configuration. In particular the simulations showed that the smaller the δ_{CD} , the more lively the dynamics of the plasmoids, according to the prediction of (3.37).

The results reported in Lazzaro *et al.* (2018) have been obtained in a rather unstable, large Δ' , configuration, assuming a purely resistive plasma. In this section we want to generalize these results, first by considering less unstable regimes, that are close to the operation condition in tokamaks, and then by investigating the effects of the kinematic viscosity on the efficacy of the island control.

We adopt the same numerical approach described in Borgogno *et al.* (2014). The equations (2.3)–(2.4) are numerically solved in the presence of a static ‘Harris pinch’ equilibrium configuration with $\psi_{\text{eq}}(x) = -\log \cosh(x)$. We recall that this equilibrium is tearing mode unstable if the instability parameter $\Delta' = 2 \cdot (1/k_y - k_y) > 0$, where $k_y = 2\pi m/L_y$, with m the corresponding mode number and L_y the length of the domain along the y -direction. The profile of the control current density is assumed to be Gaussian

$$J_{\text{CD}}(x, y, t) = J_m(t) \exp\left(-\frac{(\psi(x, y, t) - \psi_O(t))^2}{\delta_{\text{CD}}^2}\right), \quad (4.1)$$

where ψ_O is the magnetic flux evaluated at the position of the magnetic island O -point at the beginning of the control stage. The peak amplitude J_0 has a step function time waveform

$$J_m(t) = \begin{cases} 0 & t < t_1 \vee t > t_2, \\ J_0 & t_1 < t < t_2, \end{cases} \quad (4.2)$$

where t_1 and t_2 are the switching on and switching off time of the current control, respectively. The amplitude J_0 is a constant proportional to the difference between the

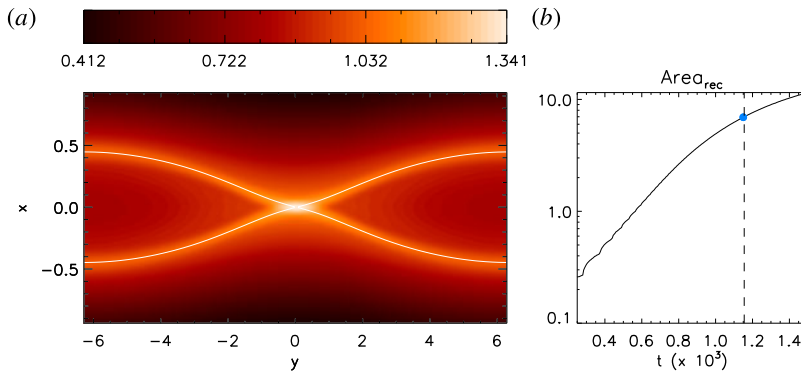


FIGURE 1. (a) Contour plot of the current density at the beginning of the ECCD injection in the regime $\Delta' = 3$. The superimposed white lines identify the borders of the corresponding reconnected region. (b) Time evolution of the area of the reconnected region in the absence of rf control. The dashed line identifies the starting injection time t_1 , and the blue dot shows the time when the current is plotted.

current density values at the X - and O -points of the magnetic island at $t = t_1$, i.e. $J_0 = a \cdot (J_X(t_1) - J_O(t_1))$. Finally, the EC beam width in ψ space, δ_{CD} , is taken proportional to the difference between the magnetic flux at the X - and the O -point of the magnetic island when $t = t_1$, i.e. $\delta_{CD} = b \cdot (\psi_X(t_1) - \psi_O(t_1))$.

Here we apply the ECCD to an $m = 1$ island associated with a weakly unstable perturbation, with $\Delta' = 3$, while in Lazzaro *et al.* (2018) the linear instability parameter was $\Delta' = 7.5$. The plasma resistivity is the same in both cases, $\eta = 5 \times 10^{-4}$.

Figure 1(a) shows the current density distribution and the corresponding magnetic island at the beginning of the ECCD injection. The time t_1 corresponds to a nonlinear stage of the magnetic island evolution (figure 1b), in the so-called Rutherford phase (Rutherford 1973), where the magnetic island width is of the order of the equilibrium shear length. The choice of this time is consistent with the request that the growth rates in the regimes $\Delta' = 3$ and $\Delta' = 7.5$, normalized to the corresponding linear growth rates, are the same when the ECCD is turned on. As a consequence the magnetic island width in the most unstable regime is approximately twice the width in the less unstable case.

According to Lazzaro *et al.* (2018) we adopt different widths of the ECCD beam deposition, while the initially injected total ECCD current, $\int J_{CD}(x, y, t_1) dx dy$, is the same. As far as the parameter b is relatively large the control current efficacy is low in both regimes. Figure 2 refers to the $b = 2$ case for $\Delta' = 3$. The magnetic island shrinks monotonically until the system reaches a new equilibrium on a time scale $1/\gamma_{in}$, where $\gamma_{in} \approx 0.01$ is the linear growth rate of the non-controlled reconnecting mode. We note that the saturated island area has the same order of magnitude of the area at $t = t_1$, resulting in a completely ineffective control. The topology of the magnetic island remains the same during the control process, while in the more unstable regime the saturation phase is dominated by the mode $m = 2$. This behaviour reflects the linear properties of the system in the two regimes (Militello, Grasso & Borgogno 2014). While in $\Delta' = 7.5$ the two unstable modes $m = 1$ and $m = 2$ grow with comparable rates, for $\Delta' = 3$ just the $m = 1$ perturbation is linearly unstable.

Major differences appear when the ECCD beam is smaller than the magnetic island width at $t = t_1$. We consider first the case $b = 1$, shown in figure 3. After

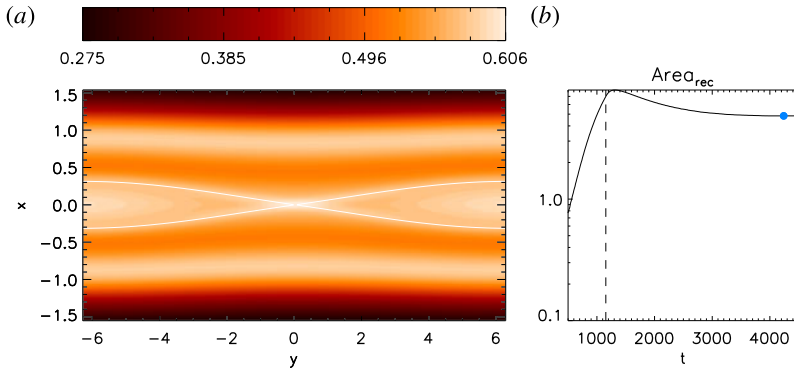


FIGURE 2. (a) Contour plot of the current density in the presence of an ECCD beam of width $\delta_{CD} = b(\psi_X - \psi_O)$ with $b = 2$ in the regime $\Delta' = 3$. The superimposed white lines identify the borders of the corresponding reconnected region. (b) Time evolution of the area of the reconnected region. The dashed line identifies the starting injection time t_1 , while the blue dot shows the time when the current is plotted.

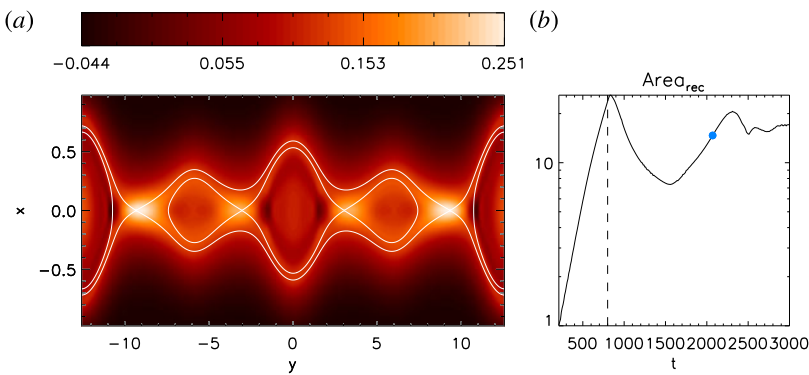


FIGURE 3. (a) Contour plot of the current density in the presence of an ECCD beam of width $\delta_{CD} = b(\psi_X - \psi_O)$ with $b = 1$ in the regime $\Delta' = 7.5$. The superimposed white lines identify the borders of the corresponding reconnected region. (b) Time evolution of the area of the reconnected region. The dashed line identifies the starting injection time t_1 , while the blue dot shows the time when the current is plotted.

an initial decreasing phase, the higher Δ' regime is characterized by the onset of a plasmoid-like instability. As shown in figure 4, by the contour plot and the profile at $x = 0$ of the rf current density at the same time as figure 3, in this phase, the magnetic flux function exhibits a uniform distribution around the reconnection region and, according to (4.1), the same is true for the control current. This condition makes almost negligible the ECCD contribution in reducing the island area. In fact it strongly differs from the ideal control configuration, represented at the injection initial time t_1 in figure 5, where it is clear that J_{CD} is peaked at the O -point of the magnetic island. On the other hand, we have verified that, when $\Delta' = 3$, plasmoids are completely absent and the ECCD control is optimal, leading to the rapid annihilation of the magnetic island (see figure 6). Note that the island suppression does not proceed monotonically in time, but it exhibits a strong discontinuity at $t \approx 2250$. At this time the area of the island bounces back with a growth rate equal to the

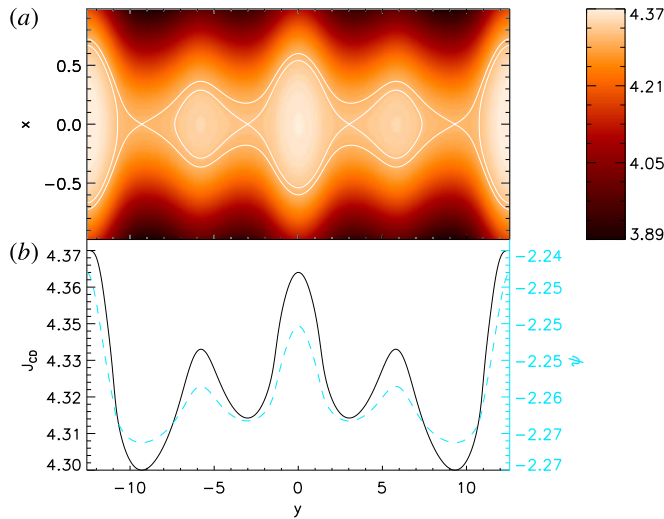


FIGURE 4. (a) Contour plot of the rf current density at the same time as the contour plot shown in figure 3. The superimposed white lines identify the borders of the corresponding reconnected region. (b) Profile of the rf current density at $x=0$ for the same time. The dashed line corresponds to the ψ profile.

previous rate of quench. This is the consequence of the so called flip instability (Monticello *et al.* 1978; Lazzaro & Coelho 2002), that has already been observed in numerical experiments of early control activity (Borgogno *et al.* 2014; Fevrier *et al.* 2016). At the onset of the instability the value of the reconnected flux $\psi_X - \psi_O$ changes sign, which is equivalent to a shift of $L_y/2$ of the equilibrium position of the elliptic O -point of the tearing perturbation (figure 6*a,b*). Due to this island shift the X -point happens to be now under the influence of the rf driven current that drives the growth of the magnetic island. However, if the deposition of the rf driven current is broad enough the magnetic island may grow to intercept the stabilizing current at its O -point and decreases again.

When $b=0.5$ plasmoids appear also in the less unstable regime, leading to a very poor ECCD efficiency (see figure 7). However, the plasmoid dynamics in this regime is much less lively than in the analogous case for the configuration with linear stability parameter $\Delta' = 7.5$, shown in figure 8. In fact the y -spectrum of the magnetic flux function is richer and the plasmoid formation is faster in the large Δ' regime. This reflects in the evolution of the island area for the two cases. The fast growth of the island observed in the case $\Delta' = 7.5$, after the initial effective shrinking phase, is due to the rapid growth and recombination of the plasmoids, leading to a continuous change in the magnetic topology which removes the J_{CD} effect. By contrast, when $\Delta' = 3$, the initial transient of the island reduction is followed by a much smoother area increase, corresponding to magnetic topology variations on much slower time scales.

In order to study the effects of the kinematic viscosity on the magnetic island control, we solved numerically the equation set (2.3)–(2.4) with a Prandtl number $P = 10$. This value has been chosen on the basis of the formula $P = \sqrt{(m_i/m_e)}\beta$ (e.g. Park, Monticello & White (1984)) for a deuterium plasma and for a typical high-performance tokamak $\beta = 0.03$. As in the purely resistive case, we considered

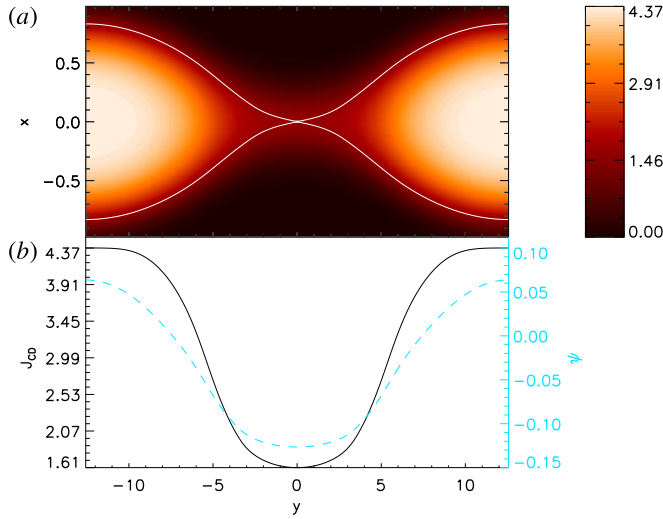


FIGURE 5. (a) Contour plot of the rf current density at $t = t_1$ corresponding to the case represented in figure 3. The superimposed white lines identify the borders of the corresponding reconnected region. (b) Profile of the rf current density at $x = 0$ for the same time. The dashed line corresponds to the ψ profile.

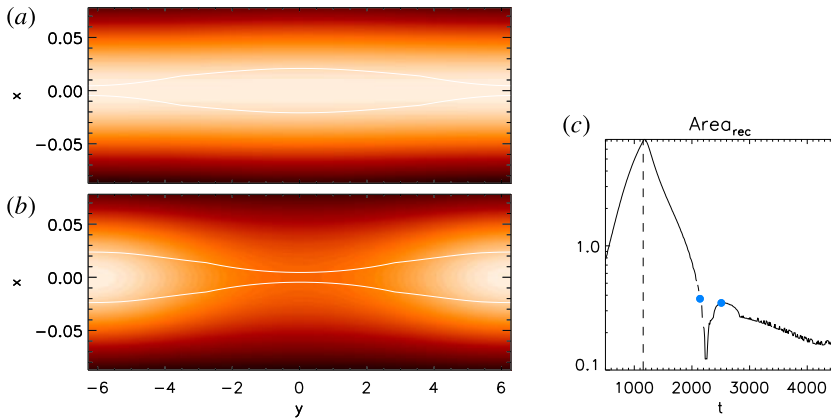


FIGURE 6. (a,b) Contour plots of the current density in the presence of an ECCD beam of width $\delta_{CD} = b(\psi_x - \psi_O)$ with $b = 1$ in the regime $\Delta' = 3$ at two different time steps, before (b) and after (a) the flip instability. The superimposed white lines identify the borders of the corresponding reconnected region. Note that the plotting range along the x -direction for these plots is an order of magnitude smaller than in the other figures. (c) Time evolution of the area of the reconnected region. The dashed line identifies the starting injection time t_1 , while the blue dots show the time steps when the currents are plotted.

the ECCD dynamics for different values of the beam width parameter $b = 2, 1, 0.5$ in the regimes $\Delta' = 7.5$ and $\Delta' = 3$. In each regime, the amplitude of the magnetic island at the beginning of the control current injection in the visco-resistive and in the resistive simulations is the same. The initial total control current is kept constant for all the values of b . Figure 9 shows the evolution of the magnetic island area

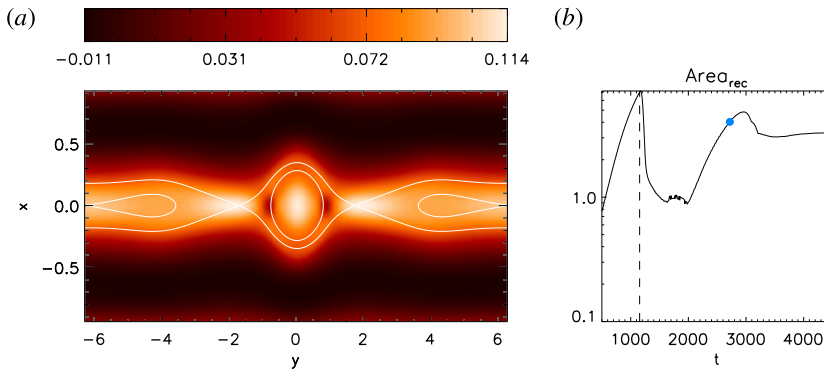


FIGURE 7. (a) Contour plot of the current density in the presence of an ECCD beam of width $\delta_{CD} = b(\psi_x - \psi_o)$ with $b = 0.5$ in the regime $\Delta' = 3$. The superimposed white lines identify the borders of the corresponding reconnected region. (b) Time evolution of the area of the reconnected region. The dashed line identifies the starting injection time t_1 , while the blue dot shows the time when the current is plotted.

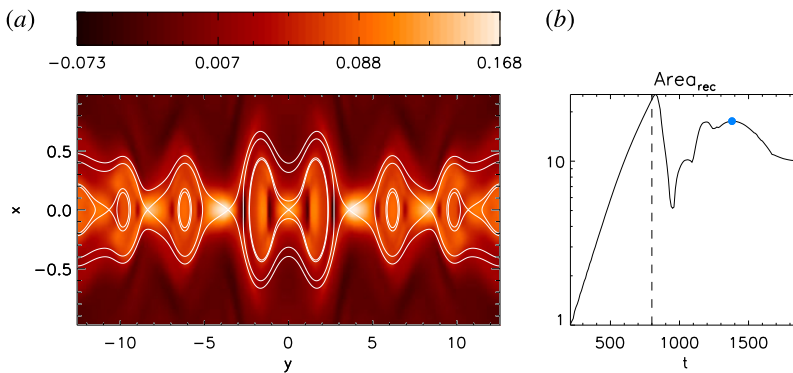


FIGURE 8. (a) Contour plot of the current density in the presence of an ECCD beam of width $\delta_{CD} = b(\psi_x - \psi_o)$ with $b = 0.5$ in the regime $\Delta' = 7.5$. The superimposed white lines identify the borders of the corresponding reconnected region. (b) Time evolution of the area of the reconnected region. The dashed line identifies the starting injection time t_1 , while the blue dot shows the time when the current is plotted.

for the various beam width at $\Delta' = 7.5$. As in the purely resistive case, plasmoids appear when $b \leq 1$ also in the presence of viscosity, which tends to slow down the dynamics of the small scale structures. However, the viscosity does not affect the long term behaviour of the controlled magnetic island whatever the width of the ECCD beam. As shown in figure 9, in fact, the area of the reconnected region in the final equilibrium stage is comparable both with and without viscosity for each value of b .

Figure 10 refers to the less unstable regime $\Delta' = 3$. It is clearly visible that the viscosity, reducing the threshold value of δ_{CD} for triggering the plasmoid instability, in agreement with the theoretical prediction of (3.37), plays a dominant role in this less unstable regime. In particular, for $b = 0.5$, contrary to the analogous purely resistive simulation, the suppression of plasmoids makes it possible that the continuous injection of the current control leads to the annihilation of the magnetic island. Note

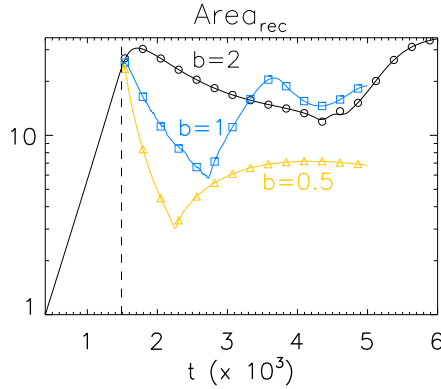


FIGURE 9. Time evolution of the area of the reconnected region for different ECCD beam widths $\delta_{CD} = b(\psi_X - \psi_O)$ with $b = 0.5$ (triangles), 1 (squares), 2 (circles) in the regime $\Delta' = 7.5$ with $P = 10$. The dashed line identifies the starting injection time t_1 .

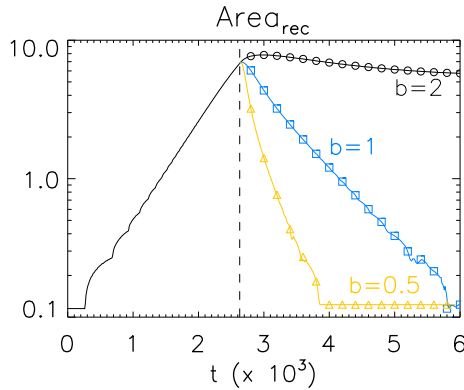


FIGURE 10. Time evolution of the area of the reconnected region for different ECCD beam widths $\delta_{CD} = b(\psi_X - \psi_O)$ with $b = 0.5$ (triangles), 1 (squares), 2 (circles) in the regime $\Delta' = 3$ with $P = 10$. The dashed line identifies the starting injection time t_1 .

that the presence of viscosity prevents the onset of flip instabilities. Finally we remark that, according to our simulations, in the visco-resistive, small Δ' regime highly focused ECCD beams increase the control current efficiency, as already found in Maraschek (2012), Koleman *et al.* (2014).

5. Conclusions

In this paper we have studied an aspect of the problem of island control by highly localized ECCD injection, in the conditions where it is theoretically possible that very fast reconnection processes modifying the island topology may be excited. The arguments are developed in the simplified conceptual framework of a two-dimensional visco-resistive MHD model. This simple model allows for an analytic treatment adopting the point of view of the converse of a Taylor problem. Using this approach we have shown that the reconnection process under the injection of a highly localized rf driven current may evolve into a regime of unstable current sheets and plasmoid formation, which hinder the desired detection and suppression of magnetic islands.

We have derived an expression, valid in the visco-resistive regime, for the threshold value of the ratio of the peaked current density over its deposition width above which a plasmoid-like instability occurs. Numerical simulations, for different values of the Prandtl number, supporting this theory have been also presented. In particular we have shown how reducing the deposition width may result in an uncontrolled system, the opposite to what was intended with the ECCD injection. However in a practical tokamak situation an excessively sharp focussing of the ECCD is unlikely and should not be sought. The influence of the linear stability parameter Δ' and the mitigation effect of the viscosity at the onset of the secondary instability have been highlighted.

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