

# ANOTHER PROOF OF THE THEOREMS ON THE EIGENVALUES OF A SQUARE QUATERNION MATRIX

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**1. Introduction.** The nature of the eigenvalues of a square quaternion matrix had been considered by Lee [1] and Brenner [2]. In this paper the author gives another elementary proof of the theorems on the eigenvalues of a square quaternion matrix by considering the equation  $Gy = \mu\bar{y}$ , where  $G$  is an  $n \times n$  complex matrix,  $y$  is a non-zero vector in  $C^n$ ,  $\mu$  is a complex number, and  $\bar{y}$  is the conjugate of  $y$ . The author wishes to thank Professor Y. C. Wong for his supervision during the preparation of this paper.

**2. Notations.** Let  $R$  and  $C$  be the field of real numbers and the field of complex numbers respectively, and  $Q$  be the algebra of real quaternions. Then  $Q$  has a base composed of four elements  $e_0, e_1, e_2, e_3$  whose multiplication table is given by the following formulae:

$$e_0 e_\alpha = e_\alpha e_0 = e_\alpha, \quad e_0^2 = e_0, \\ e_\alpha^2 = -e_0, \quad e_\alpha e_\beta = -e_\beta e_\alpha = e_\gamma,$$

where  $1 \leq \alpha, \beta, \gamma \leq 3$ , and  $(\alpha, \beta, \gamma)$  is a cyclic permutation of  $(1, 2, 3)$ . If  $q \in Q$ , then

$$q = a_0 e_0 + a_1 e_1 + a_2 e_2 + a_3 e_3,$$

where  $a_i \in R$  ( $i = 0, 1, 2, 3$ ). We shall identify  $e_0$  and  $e_1$  with 1 and  $i (= \sqrt{-1})$  respectively, so that we can write  $q = a_0 + ia_1 + e_2(a_2 - ia_3) = \lambda + e_2\mu$ , where  $\lambda, \mu \in C$  (see Chevalley [3, pp. 16–17]). We define the norm of  $q$  as the real number  $\sum_{i=0}^3 a_i^2$ , and the trace of  $q$  as  $a_0$ .

We regard  $R^n$  and  $C^n$  as vector spaces over  $R$  and  $C$ , respectively, and  $Q^n$  as a right vector space over  $Q$ .

### 3. The nature of the eigenvalues of a square quaternion matrix.

**THEOREM 1.** Let  $F = G_1 + e_2 G_2$  be an  $n \times n$  quaternion matrix, where  $G_1$  and  $G_2$  are complex matrices, and let

$$G(\lambda) \equiv \begin{pmatrix} \bar{G}_2 & G_1 - \lambda I_n \\ -\bar{G}_1 + \lambda I_n & G_2 \end{pmatrix}, \quad g(\lambda) \equiv |G(\lambda)|,$$

where the bar denotes the complex conjugate,  $|G(\lambda)|$  the determinant of the matrix  $G(\lambda)$ ,  $I_n$  the  $n \times n$  identity matrix, and  $\lambda$  a complex variable.

(a) If  $\alpha + i\beta + e_2(\gamma + i\delta)$  is any eigenvalue of  $F$ , then  $\alpha + ik$ , where  $k^2 = \beta^2 + \gamma^2 + \delta^2$ , is a zero point of  $g(\lambda)$ .

(b) Conversely, if  $\alpha + ik$  is any zero point of  $g(\lambda)$ , then  $\alpha + i\beta + e_2(\gamma + i\delta)$ , for any real numbers,  $\beta, \gamma$  and  $\delta$  such that  $\beta^2 + \gamma^2 + \delta^2 = k^2$ , is an eigenvalue of  $F$ .

*Proof.* As a first step in the proof of Theorem 1, we consider the following equation

$$Fx = xq, \tag{1}$$

where  $x = x_1 + e_2x_2 \neq 0$  with  $x_1, x_2 \in C^n$  and  $q = \lambda + e_2\mu$  with  $\lambda, \mu \in C$ . Since

$$\begin{aligned} Fx &= G_1x_1 - \bar{G}_2x_2 + e_2(G_2x_1 + \bar{G}_1x_2), \\ xq &= x_1\lambda - \bar{x}_2\mu + e_2(x_2\lambda + \bar{x}_1\mu), \end{aligned}$$

equation (1) is equivalent to

$$\begin{cases} G_1x_1 - \bar{G}_2x_2 = x_1\lambda - \bar{x}_2\mu, \\ G_2x_1 + \bar{G}_1x_2 = x_2\lambda + \bar{x}_1\mu, \end{cases} \tag{2}$$

which we can write as

$$\begin{pmatrix} G_1 - \lambda I_n & -\bar{G}_2 \\ G_2 & \bar{G}_1 - \lambda I_n \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \mu \begin{pmatrix} -\bar{x}_2 \\ \bar{x}_1 \end{pmatrix}. \tag{3}$$

But

$$\begin{aligned} \begin{pmatrix} G_1 - \lambda I_n & -\bar{G}_2 \\ G_2 & \bar{G}_1 - \lambda I_n \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} &= \begin{pmatrix} G_1 - \lambda I_n & -\bar{G}_2 \\ G_2 & \bar{G}_1 - \lambda I_n \end{pmatrix} \begin{pmatrix} O & I_n \\ -I_n & O \end{pmatrix} \begin{pmatrix} -x_2 \\ x_1 \end{pmatrix} \\ &= \begin{pmatrix} \bar{G}_2 & G_1 - \lambda I_n \\ -\bar{G}_1 + \lambda I_n & G_2 \end{pmatrix} \begin{pmatrix} -x_2 \\ x_1 \end{pmatrix}. \end{aligned}$$

Therefore, equation (1) is equivalent to

$$G(\lambda)y = \mu\bar{y}, \tag{4}$$

where  $G(\lambda) = \begin{pmatrix} \bar{G}_2 & G_1 - \lambda I_n \\ -\bar{G}_1 + \lambda I_n & G_2 \end{pmatrix}, y = \begin{pmatrix} -x_2 \\ x_1 \end{pmatrix} \in C^{2n}.$

Several lemmas are required to complete the proof of Theorem 1.

LEMMA 1. *Let  $U, V, W$  be  $n \times n$  complex matrices and  $\mu$  be a complex number; then*

$$\begin{vmatrix} \mu I_n & U \\ V & W \end{vmatrix} = | \mu W - VU |.$$

*Proof.* If  $\mu = 0$ , the result follows from Laplace’s expansion.

If  $\mu \neq 0$ , then

$$\begin{vmatrix} \mu I_n & U \\ V & W \end{vmatrix} = \begin{vmatrix} I_n & O \\ -\frac{1}{\mu}V & I_n \end{vmatrix} \begin{vmatrix} \mu I_n & U \\ V & W \end{vmatrix} = \begin{vmatrix} \mu I_n & U \\ O & W - \frac{1}{\mu}VU \end{vmatrix},$$

and again Laplace’s expansion yields the result.

LEMMA 2. *Let  $G = H_1 + iH_2$ , where  $H_1$  and  $H_2$  are  $n \times n$  real matrices, and let*

$$h(\gamma, \delta) \equiv \begin{vmatrix} H_1 - \gamma I_n & -H_2 - \delta I_n \\ H_2 - \delta I_n & H_1 + \gamma I_n \end{vmatrix}, \quad p(t) \equiv | G\bar{G} - tI_n |,$$

where  $\gamma, \delta$  and  $t$  are real variables; then  $(\gamma_1, \delta_1)$  is a zero point of  $h(\gamma, \delta)$  if and only if  $\gamma_1^2 + \delta_1^2$  is a zero point of  $p(t)$ .

*Proof.*

$$h(\gamma, \delta) = (-1)^n \begin{vmatrix} iI_n & I_n \\ O & I_n \end{vmatrix} \begin{vmatrix} H_1 - \gamma I_n & -H_2 - \delta I_n \\ H_2 - \delta I_n & H_1 + \gamma I_n \end{vmatrix} \begin{vmatrix} iI_n & O \\ I_n & I_n \end{vmatrix} \\ = (-1)^n \begin{vmatrix} 2\bar{\mu}I_n & \bar{G} + \bar{\mu}I_n \\ G + \bar{\mu}I_n & H_1 + \gamma I_n \end{vmatrix},$$

where  $\mu = \gamma + i\delta$ . By Lemma 1, we have

$$h(\gamma, \delta) = (-1)^n | 2\bar{\mu}(H_1 + \gamma I_n) - (G + \bar{\mu}I_n)(\bar{G} + \bar{\mu}I_n) | \\ = (-1)^n | 2\bar{\mu}H_1 + 2\bar{\mu}\gamma I_n - G\bar{G} - 2\bar{\mu}H_1 - \bar{\mu}^2 I_n | \\ = (-1)^n | \bar{\mu}(2\gamma - \bar{\mu})I_n - G\bar{G} | \\ = (-1)^n | (\gamma^2 + \delta^2)I_n - G\bar{G} | \\ = (-1)^{2n} | G\bar{G} - (\gamma^2 + \delta^2)I_n | \\ = p(\gamma^2 + \delta^2).$$

Thus Lemma 2 is proved.

**LEMMA 3.** Let  $G = H_1 + iH_2$ , where  $H_1$  and  $H_2$  are  $n \times n$  real matrices, and let  $h(\gamma, \delta)$  and  $p(t)$  be defined as in Lemma 2. Then the equation

$$Gy = \mu\bar{y}, \tag{5}$$

where  $y = y_1 + iy_2 \neq 0$  with  $y_1, y_2 \in R^n$  and  $\mu = \gamma + i\delta$  with  $\gamma, \delta \in R$ , is consistent if and only if  $p(\gamma^2 + \delta^2) = 0$ .

*Proof.* Since

$$Gy = H_1y_1 - H_2y_2 + i(H_2y_1 + H_1y_2), \\ \mu\bar{y} = \gamma y_1 + \delta y_2 + i(\delta y_1 - \gamma y_2),$$

equation (5) is equivalent to

$$\left. \begin{aligned} (H_1 - \gamma I_n)y_1 + (-H_2 - \delta I_n)y_2 &= O \\ (H_2 - \delta I_n)y_1 + (H_1 + \gamma I_n)y_2 &= O \end{aligned} \right\} \tag{6}$$

where  $y_1, y_2$  are not both zero. It follows from our definition of  $h(\gamma, \delta)$  that equations (6) are consistent if and only if  $(\gamma, \delta)$  is a zero point of  $h(\gamma, \delta)$ . Therefore, by Lemma 2, equations (6), and hence also equation (5), are consistent if and only if  $p(\gamma^2 + \delta^2) = 0$ . Thus Lemma 3 is proved.

**LEMMA 4.** Let  $G(\lambda)$  be defined as in Theorem 1 and let  $p(\lambda, t) = | G(\lambda)\overline{G(\lambda)} - tI_{2n} |$ , where  $t$  is a real variable. Then

(a) Equation (4), and hence also equation (1), and  $\lambda = \alpha + i\beta, \mu = \gamma + i\delta$  are consistent if and only if  $p(\alpha + i\beta, \gamma^2 + \delta^2) = 0$ .

(b)  $p(\alpha + i\beta, \gamma^2 + \delta^2) = p(\alpha + i\beta_1, \gamma_1^2 + \delta_1^2)$  for all real numbers  $\beta_1, \gamma_1$  and  $\delta_1$  such that  $\beta_1^2 + \gamma_1^2 + \delta_1^2 = \beta^2 + \gamma^2 + \delta^2$ .

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*Proof.* (a) follows directly from Lemma 3. To prove (b), we note that for all real  $\alpha, \beta, \gamma$  and  $\delta$ ,

$$\begin{aligned}
 p(\alpha + i\beta, \gamma^2 + \delta^2) &= |G(\alpha + i\beta)\overline{G(\alpha + i\beta)} - (\gamma^2 + \delta^2)I_{2n}| \\
 &= \begin{vmatrix} \overline{G_2}G_2 - G_1G_1 + 2\alpha G_1 - (a^2 + \beta^2)I_n & \overline{G_2}G_1 + G_1\overline{G_2} - 2\alpha\overline{G_2} \\ -(\gamma^2 + \delta^2)I_n & \\ -\overline{G_1}G_2 - G_2G_1 + 2\alpha G_2 & -\overline{G_1}G_1 + G_2\overline{G_2} + 2\alpha\overline{G_1} - (\alpha^2 + \beta^2)I_n \\ & -(\gamma^2 + \delta^2)I_n \end{vmatrix} \\
 &= \begin{vmatrix} \overline{G_2}G_2 - G_1G_1 + 2\alpha G_1 - \alpha^2 I_n & \overline{G_2}G_1 + G_1\overline{G_2} - 2\alpha\overline{G_2} \\ -(\beta^2 + \gamma^2 + \delta^2)I_n & \\ -\overline{G_1}G_2 - G_2G_1 + 2\alpha G_2 & -\overline{G_1}G_1 + G_2\overline{G_2} + 2\alpha\overline{G_1} - \alpha^2 I_n \\ & -(\beta^2 + \gamma^2 + \delta^2)I_n \end{vmatrix} \\
 &= |G(\alpha)\overline{G(\alpha)} - (\beta^2 + \gamma^2 + \delta^2)I_{2n}| = p(\alpha, \beta^2 + \gamma^2 + \delta^2).
 \end{aligned}$$

From this it follows that

$$p(\alpha + i\beta, \gamma^2 + \delta^2) = p(\alpha + i\beta_1, \gamma_1^2 + \delta_1^2) \tag{7}$$

for all real  $\beta_1, \gamma_1$  and  $\delta_1$  such that  $\beta_1^2 + \gamma_1^2 + \delta_1^2 = \beta^2 + \gamma^2 + \delta^2$ .

Thus assertion (b) of Lemma 4 is proved.

The proof of Theorem 1 is now immediate. It follows from the definition that

$$g(\lambda)\overline{g(\lambda)} = |G(\lambda)\overline{G(\lambda)}| = p(\lambda, 0).$$

Therefore we have, by Lemma 4,

$$g(\alpha + ik)\overline{g(\alpha + ik)} = p(\alpha + ik, 0) = p(\alpha + i\beta, \gamma^2 + \delta^2), \tag{8}$$

where  $\beta, \gamma$  and  $\delta$  are any real numbers such that  $k^2 = \beta^2 + \gamma^2 + \delta^2$ . If  $q = \alpha + i\beta + e_2(\gamma + i\delta)$  is any eigenvalue of  $F$ , then, by Lemma 4,  $p(\alpha + i\beta, \gamma^2 + \delta^2) = 0$ . Therefore it follows from (8) that  $\alpha + ik$  is a zero point of  $g(\lambda)$ . Thus assertion (a) of Theorem 1 is proved. Conversely, if  $\alpha + ik$  is any zero point of  $g(\lambda)$ , then it follows from (8) that  $p(\alpha + i\beta, \gamma^2 + \delta^2) = 0$  for any real  $\beta, \gamma$  and  $\delta$  such that  $\beta^2 + \gamma^2 + \delta^2 = k^2$ . Therefore, by Lemma 4,  $\alpha + i\beta + e_2(\gamma + i\delta)$  is an eigenvalue of  $F$ . Thus assertion (b) of Theorem 1 is proved.

**COROLLARY 1.** *If  $\tau$  is an eigenvalue of  $F$  and  $q$  is a quaternion such that  $\tau$  and  $q$  have equal norms and traces, then  $q$  is an eigenvalue of  $F$ .*

*Proof.* This is an immediate consequence of Theorem 1.

**COROLLARY 2.** *If  $q_1$  and  $q_2$  are two quaternions having equal norms and traces, then there exists a quaternion  $\sigma \neq 0$  such that  $q_2 = \sigma^{-1}q_1\sigma$ .*

*Proof.* Take  $F = q_1$ ; then, since  $q_1 1 = 1q_1$ , Corollary 2 follows from Corollary 1.

**THEOREM 2.** *Let  $F$  and  $g(\lambda)$  be defined as in Theorem 1; then a complex number  $\lambda$  is an eigenvalue of  $F$  if and only if  $\lambda$  is a zero point of  $g(\lambda)$ . And if  $\tau$  is an eigenvalue of  $F$ , then  $\sigma^{-1}\tau\sigma$  is also an eigenvalue of  $F$  for all  $\sigma \neq 0$  in  $Q$ . The class  $\sigma^{-1}\tau\sigma$  contains just two complex numbers ( $\lambda$  and  $\bar{\lambda}$ ).*

*Proof.* Since  $\tau$  and  $\sigma^{-1}\tau\sigma$  have equal norms and traces, by Theorem 1, Corollaries 1 and 2, Theorem 2 follows.

**4. Remark.** The polynomial  $g(\lambda)$  defined in Theorem 1 has real coefficients. In fact, we have

$$\begin{aligned}
 g(\lambda) &= \begin{vmatrix} \bar{G}_2 & G_1 - \lambda I_n \\ -\bar{G}_1 + \lambda I_n & G_2 \end{vmatrix} = \begin{vmatrix} O & I_n \\ -I_n & O \end{vmatrix} \begin{vmatrix} \bar{G}_2 & G_1 - \lambda I_n \\ -\bar{G}_1 + \lambda I_n & G_2 \end{vmatrix} \begin{vmatrix} O & -I_n \\ I_n & O \end{vmatrix} \\
 &= \begin{vmatrix} G_2 & \bar{G}_1 - \lambda I_n \\ -G_1 + \lambda I_n & \bar{G}_2 \end{vmatrix} = \bar{g}(\lambda).
 \end{aligned}$$

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