



On the mean structure and unsteadiness of dual shock wave–turbulent boundary layer interactions

Nan Li^{1,2,3,†}, Wenfeng Li^{1,3}, Zhengyin Ye^{1,2,3} and Weiwei Zhang^{1,2,3}

¹School of Aeronautics, Northwestern Polytechnical University, Xi'an 710072, PR China

²International Joint Institute of Artificial Intelligence on Fluid Mechanics, Northwestern Polytechnical University, Xi'an 710072, PR China

³National Key Laboratory of Aircraft Configuration Design, Xi'an 710072, PR China

(Received 1 January 2024; revised 13 July 2024; accepted 14 August 2024)

Supersonic internal flows often exhibit multiple reflected shocks within a limited distance. These shocks can interact with each other in a complex manner due to the characteristics of the shock wave–turbulent boundary layer interaction (STBLI), including flow distortion and the relaxing boundary layer. This study aims to characterise this type of interaction and to clarify its fluid physics. A separated STBLI zone was established either upstream or downstream, and another weaker STBLI was established in the opposing position to serve as a perturbation. Time-resolved measurements were employed to characterise the mean separation and unsteadiness as the two regions approached each other, as well as their relationship. The experimental results indicated that the STBLI could affect the separation and reattachment of the other STBLI through either the decelerated or relaxing boundary layer. Despite a small deflection angle, the incident shock can amplify the low-frequency oscillations in the downstream STBLI region. Additionally, the interaction in the downstream region can be influenced by both low- and high-frequency oscillations associated with the upstream STBLI through a relaxing boundary layer. Despite the limited correlation observed between the low-frequency fluctuations in the downstream region and the boundary layer flow not far upstream, there still exists some degree of correlation between the low-frequency shock motions even when they are widely separated. Both the ‘upstream mechanism’ and ‘downstream mechanism’ have been observed, and the significance of low-frequency dynamics in the separated flow, relative to that of the upstream flow, is closely associated with interaction intensity.

Key words: supersonic flow, shock waves, boundary layer separation

† Email address for correspondence: linan2019@nwpu.edu.cn

1. Introduction

The shock wave–turbulent boundary layer interaction (STBLI) is commonly observed in both the internal and external flows of high-speed aircraft, and has significant effects on vehicle and component performance. This classic topic has been investigated extensively in recent decades (Dolling 2001). The STBLI typically adversely affects aerodynamic performance, leading to a thicker boundary layer or even flow separation. Consequently, the total pressure loss and flow distortion increase significantly. The flow unsteadiness caused by the STBLI often results in downstream oscillations that can be severe in certain cases, potentially damaging the airframe or engine. However, the STBLI does not necessarily lead to entirely negative consequences. For instance, using the enhanced fluctuation to improve the mixing of fuel and air within a scramjet combustor is feasible (Yang, Kubota & Zukoski 1993). With a comprehensive understanding of the physical processes, sophisticated and effective flow control techniques deeply rooted in the principles of fluid physics can be developed. These techniques can be employed directly in design, facilitating the creation of optimal designs for aerodynamic devices while circumventing undesired consequences or harnessing potential advantages. Scholars focus primarily on two aspects when studying the STBLI: the mean flow characteristics, such as the pressure increase within and scale of the separation, and the unsteadiness in the interaction, such as low-frequency oscillations.

The classic theory proposed by Chapman, Kuehn & Larson (1958) considers the effects of both the Reynolds number and the Mach number, enabling the prediction of the pressure increase within the separation bubble. Another important contribution of this theory is that it reveals the fundamental features of the STBLI, specifically, that the initial pressure increase and extent length caused by the interaction are related only to the local flow parameters and are independent of the shock intensity, whereas the shock intensity affects only the pressure increase downstream. The length scale of the separation region in the STBLI is of particular interest because of its significance in the geometric design of aircraft. Furthermore, this length is commonly used as a normalisation factor for the low-frequency oscillation of the STBLI. Souverein, Bakker & Dupont (2013) developed a separation length scaling method for the STBLI based on the mass conservation of flow in both the upstream and downstream STBLI regions. The derived relationship between the normalised interaction length of the STBLI region and the strength of the STBLI covers wide ranges of Mach numbers, Reynolds numbers and shock strengths, exhibiting only a moderate scatter of approximately 15 %.

Studies on the unsteadiness of the STBLI have broadly sustained the perspective of the STBLI as a forced dynamical system. In cases without separation, investigations have suggested a direct relationship between the movement of the shock and the turbulence that it encounters (Debieve & Lacharme 1986; Lee, Lele & Moin 1993). The occurrence of shock unsteadiness at frequencies significantly lower than those in unseparated cases has also been observed when the shock is sufficiently strong to induce separation in a general sense (Piponniau *et al.* 2009; Priebe *et al.* 2016). According to Dupont, Haddad & Debieve (2006), the interaction region can be divided into five main sections, each encompassing typical time scales that span two orders of magnitude. The analysis of the source of this low-frequency unsteadiness revealed two broad mechanisms that are responsible for driving the pulsations in the separation bubble. First is the ‘upstream mechanism’, in which the separation bubble is influenced by the incoming boundary layer. Studies have indicated connections between the variations in momentum, pressure and velocity within the turbulent boundary layer prior to separation and the movements of the separation shock (Andreopoulos & Muck 1987; Gramann & Dolling 1990; Erengil

& Dolling 1991*a,b*; Beresh, Clemens & Dolling 2002; Ganapathisubramani, Clemens & Dolling 2006). The ‘downstream mechanism’ is related to the separation bubble and the shear layer, which dominate the pulsation for large length scales. Previous studies have extensively highlighted the potential driving force behind the formation of the shear layer over the separation bubble, and the subsequent entrainment of fluid (Piponniau *et al.* 2009; Priebe & Martin 2012; Estruch-Samper & Chandola 2018). Feedback mechanisms within the separation bubble have also been considered as sources of low-frequency oscillations in many studies (Pirozzoli, Grasso & Gatski 2004; Wu & Martin 2008). Scholars have also argued that low-frequency unsteadiness does not arise exclusively from external forcing, whether it occurs upstream or downstream from the separation shock. Instead, this unsteadiness emerges as an inherent characteristic of the coupled system (Theofilis 2011; Toubert & Sandham 2011; Hildebrand *et al.* 2018; Hao *et al.* 2021). Thomas, Putnam & Chu (1994), Toubert & Sandham (2009) and Sidharth *et al.* (2018) identified an unstable mode resulting from the inherent global instability of the separation bubble. Hao *et al.* (2021) discovered a strong correlation between the emergence of secondary separation beneath the primary separation bubble and global instability. Cao *et al.* (2021) provided evidence of streamwise heat flux streaks even in the absence of any external disturbances.

To acquire essential insights, significant emphasis has been placed on conventional interaction involving a single interaction region. However, having only one STBLI region is considered the ideal case. Deviations from this case may occur in practical flight scenarios. For instance, in internal flows such as those related to high-speed inlets and isolators, the presence of multiple reflected shocks often results in boundary layer separation at adjacent locations (Leonard & Narayanaswamy 2021; Khobragade, Unnikrishnan & Kumar 2022). This highlights the question of whether adjacent STBLI regions interact with each other, particularly considering the inherent features of the STBLI. These include the dependence of the pressure increase at the separation point and extent length on the local flow parameters, as well as the decelerated or relaxing boundary layer downstream from the interaction region. In other words, the adverse pressure gradient may cause the separation of the STBLI region to occur earlier through the disturbed boundary layer. Previous studies have revealed the development and shedding of large vortex structures during these interactions, which result in elevated levels of turbulence far from the surface within the downstream boundary layer (Dupont *et al.* 2008; Graftieaux, Michard & Grosjean 2001). These structures remain present for several interaction lengths. Questioning the extent to which the unsteady features of the STBLI region affect other interaction regions is also important.

The objective of the present study was to examine the aforementioned issues by utilising time-resolved pressure measurements, high-speed schlieren visualisations and the particle image velocimetry (PIV) technique to investigate dual-STBLIs (incident and compression-ramp-induced STBLIs) under Mach 4.1 edge conditions. Strong STBLI zones with evident separation were sequentially set at the upstream and downstream positions, and another area was designated as a weak STBLI zone to study the influences from upstream and downstream. Six scenarios with various spacings between the two interaction regions were considered. The flow structure variations were first observed using schlieren imaging. Next, the effects of the additional STBLI on separation and reattachment were assessed. The application of PIV was utilized to characterise the state of the boundary layer following the interaction. The utilisation of time-resolved measurement techniques enabled us to analyse the dynamics of the interaction, encompassing the temporal evolution of the unsteadiness, shock behaviour, shear layer development and perturbation propagation.

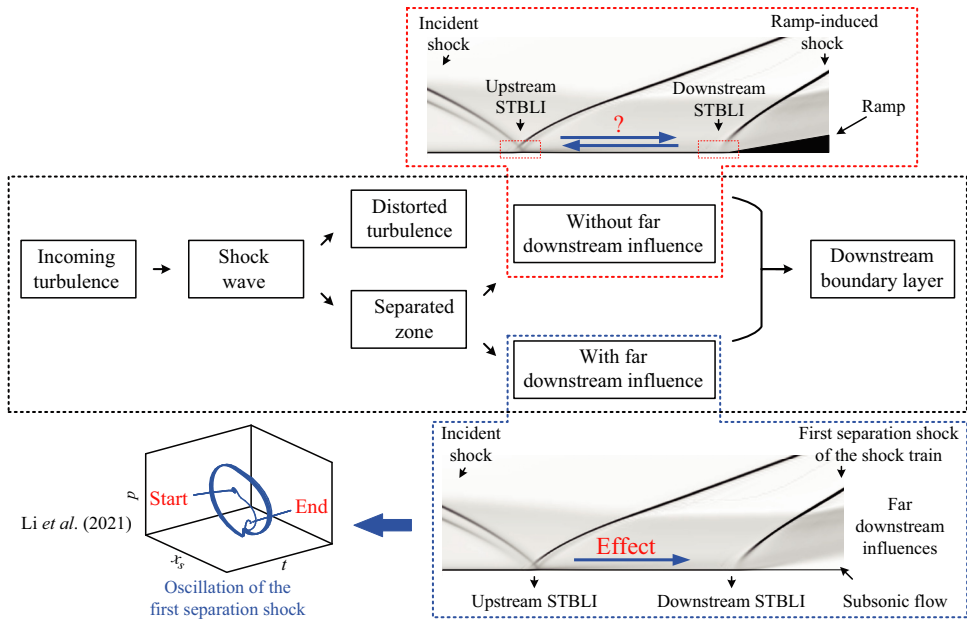


Figure 1. Schematic of the problem domain.

2. Problem statement

The existence of various distinct types of STBLI, characterised by their geometry and the occurrence of flow separation, suggests that these phenomena may lead to fundamentally different forms of unsteadiness. Dussauge & Piponniau (2008) and Dussauge (2009) proposed interpretations based on the diagram presented in the black dashed box in figure 1. The upper and lower branches depict flows that are not separated and are separated, respectively. In both scenarios, a shock wave acts as an interface between the upstream and downstream layers, dividing them. The positions and motions of the shock waves vary accordingly. By considering these different components, the motion of the shock wave can be analysed from both upstream and downstream perspectives.

In a previous study (Li & Chang 2021), an intriguing observation was made: as the shock train induced by the backpressure approached the upstream STBLI region in an isolator, broadband and gradually intensifying oscillations occurred. Under constant inflow and outflow conditions, violent limit cycle oscillation of the separation shock occurred around the interaction region owing to a positive feedback mechanism within the shock train resulting from the disturbed distributions of the flow parameters caused by the STBLI (Li *et al.* 2021). The shock train can be considered an STBLI with far-downstream influences that are characterised by the coupling between the downstream flow and the separation shock, which extends over distances much larger than the characteristic length scale of the incoming flow (Hadjadj & Dussauge 2009). The STBLI at the leading edge of the shock train is essentially identical to the incident STBLI and compression-ramp-induced STBLI, both of which exhibit forced motion and intrinsic instability (Bruce & Babinsky 2008; Li *et al.* 2021). The downstream STBLI has been confirmed to be influenced by the upstream one in shock train cases. However, the characteristics of the upstream STBLI have been obscured by violent oscillations of the shock train. The interference between the two canonical interactions remains unknown, and the previous studies on shock trains motivate further investigation into their mutual interaction. The presence of

Structure and unsteadiness of dual STBLIs

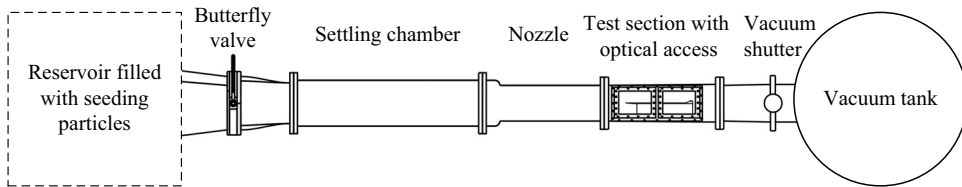


Figure 2. Diagram of the supersonic facility at NPU.

unsteadiness, distortion of flow parameters, relaxation process downstream of the STBLI, and low-frequency mechanism give rise to several questions regarding these aspects.

- (1) Will a sudden change in separation occur as two interaction regions approach one another?
- (2) How does the unsteadiness progress as the two interaction regions approach one another?
- (3) Does any relationship exist between the two interactions?

The current study was focused on the effects of downstream and upstream STBLIs on other interaction regions. Previous studies (Li & Chang 2021; Li *et al.* 2021), the themes of which are shown in the blue dashed box at the bottom of figure 1, suggest that the effects are not negligible. For better implementation and less additional interference, the upstream and downstream interactions were designed as impinging shock and compression corner interactions, respectively. To avoid transition effects, the boundary layer upstream from the incident shock was set to be fully turbulent. In corner regions, three-dimensional shock wave patterns exist. According to Li *et al.* (2021) and Wang *et al.* (2015), the dominance of two-dimensional flow characteristics increased in the central region with a higher aspect ratio of the channel (width to height) and a smaller proportion of corner flow. Thus to minimise the three-dimensional effect of the STBLI, the minimum aspect ratio for channels composed of wedges, flat plates and sidewalls was set at 2.5. We also verified the two-dimensional flow features by the planar laser scattering method and three-dimensional numerical simulations. The flow basically maintained the two-dimensional characteristics within a range of approximately 120 mm spread out near the centreline, while the three-dimensional flow area in corners remained small. Additionally, the three-dimensional dynamic mode decomposition results indicated that the shock remained predominantly two-dimensional and uniform in the spanwise direction during low-frequency motion (Priebe *et al.* 2016). Therefore, we focused solely on analysing the low-frequency dynamics in two dimensions.

3. Experimental set-up

3.1. Wind tunnel

All tests were performed in an air-breathing supersonic wind tunnel of the National Key Laboratory of Science and Technology on Aerodynamic Design and Research at Northwestern Polytechnical University (NPU). The nominal free-stream Mach number was 4.2 at the exit of the nozzle. The facility comprised a stagnation chamber with damping screens, an interchangeable rectangular supersonic nozzle, a test section, a diffuser, and a 200 m³ vacuum tank, as shown in figure 2. Four vacuum pumps could pump the vacuum tank to a pressure of less than 0.1 Pa in 1 h. These settings enabled sustained runs of approximately 10 s.

M_∞	M_1	U_1 (m s ⁻¹)	T_0 (K)	P_0 (kPa)	Re^* (m ⁻¹)
4.2 ± 0.02	4.1 ± 0.02	675.8 ± 3	295 ± 2	100 ± 0.5	4.3×10^6

Table 1. Summary of flow conditions.

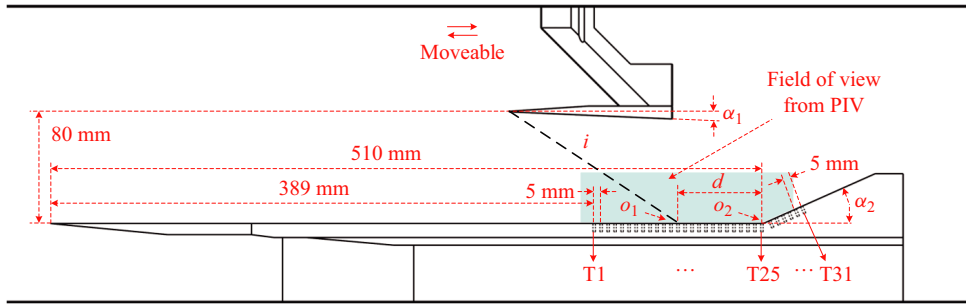


Figure 3. Diagram of the test section, with plate model, wedge and the distribution of pressure transducers.

The entrance of the test section measured 200 mm × 200 mm (width × height). The divergence of the upper and lower walls in the test section was adjusted by ±0.5° relative to the centreline, considering the development of the boundary layer along these walls. The test section contained removable modules on all four sides to mount the models and provide optical access. Two pieces of optical glass of dimensions 260 mm × 180 mm were mounted on each sidewall for schlieren imaging.

The flow conditions used in this study are listed in table 1. Here, M_∞ , T_0 and P_0 correspond to the nominal Mach number, stagnation temperature and stagnation pressure of the supersonic flow at the exit of the nozzle, and U_1 denotes the edge velocity on the flat plate upstream from the STBLI region. The Mach number at the flat plate, denoted as M_1 , is 4.1 ± 0.02 , slightly lower than the free-stream Mach number 4.2, resulting in a unit Reynolds number $Re^* = 4.3 \times 10^6$ m⁻¹. This discrepancy can be attributed to the deceleration caused by a shock generated by the forced transition device positioned at the leading edge of the flat plate.

3.2. Test model

Figure 3 provides a schematic representation of the model. A full-span, 610 mm long steel plate with a 5° lead was employed to generate the boundary layer for all tests. The plate was connected to the bottom wall at height 60 mm by using a rib plate. The rib plate was specifically designed to offset the divergence angle of the lower wall. Therefore, the full-span plate was parallel to the free-stream flow. The forced transition method was also employed to facilitate the boundary layer transition and to ensure a turbulent boundary layer upstream from the STBLI zone. The downstream STBLI was produced by using a compression corner with deflection angle 24° at the end of the plate. The upstream STBLI was generated by employing a two-dimensional wedge suspended from the upper wall. Different angles were designed to achieve disparate shock intensities. The vertical distance between the tip of the wedge and the plate surface was 80 mm. This wedge could be moved streamwise in 10 mm intervals, resulting in different distances between the two STBLI regions.

Case	Angle of the upstream wedge α_1 (deg.)	Angle of the downstream ramp α_2 (deg.)	d (mm)
A	3	24	52, 41, 30, 19, 10, 0
B	10	24	56, 45, 36, 25, 16, 6

Table 2. Geometric parameters of test model.

As shown in figure 3, the incident shock i intersects the centreline of the plate surface at point o_1 under inviscid conditions. The distance between o_1 and o_2 (the origin of the ramp at the end of the plate) is defined as d . The configurations of the two cases are presented in table 2, with the upstream deflection angles of the wedge being 3° and 10° . The shock generator was adjusted with a spacing of approximately 10 mm along the flow direction during the test to obtain six distances between the impingement point of the incident shock and the origin of the compression corner. The values of d obtained from schlieren imaging are also listed in table 2.

3.3. Test programme

Different diagnostic methods were used throughout the tests. The tests aimed to determine the flow structure of the interference between the two interaction regions and to provide a physical interpretation. High-frequency pressure measurements were used to investigate the unsteadiness and communication between the two interaction regions. Although commonly utilised for qualitative analysis, the schlieren imaging technique directly correlates the light intensity of the schlieren image with the density gradients in the flow, thereby providing valuable information. The evaluation of the flow oscillation frequencies can be facilitated by utilising time-resolved flow field information. High-speed schlieren imaging is a superior method of acquiring extensive datasets. The PIV measurements were also utilized to quantitatively characterise the state of the boundary layer through its interactions with shock waves.

3.3.1. Time-resolved pressure measurements

Up to 31 fast-response pressure transducers were set in the centreline of the plate and flushed onto the plate surface, each having natural frequency 200 kHz, as shown schematically in figure 3. Transducers labelled T1–T25 were spaced 5.0 mm apart in the streamwise direction, starting 389.0 mm from the leading edge, with sensor T25 exactly 1.0 mm upstream from the origin of the ramp. The other six transducers, labelled T26–T31, started 5.0 mm from the origin of the ramp. Two different transducer models, namely, Kulite XCS-062-15A and XCQ-062-30A, were utilised in the study. These transducers were rated at 103.4 kPa and 206.8 kPa absolute, respectively. The transducers were connected to two 16-bit A/D converters (NI PCI-6338 Multifunction DAQ) and then recorded simultaneously at 500 kS s^{-1} (with a custom NI LabVIEW Virtual Instrument) for each channel. A 200 kHz low-pass filter was used to remove aliasing effects. The auxiliary amplifier was used to achieve a high-level pressure signal, but it imposed a constraint on the response at approximately 40 kHz. The fast-response transducers were calibrated by obtaining readings at 11 different pressure points ranging from 0.5 kPa to 100 kPa, using a Wika Mensor pressure controller (CPC6000). The linear fitting method was employed to establish a correlation between the recorded pressure and mean voltage. The deviation of each data point from the calibration line was found to be within 0.5%.

Subsequently, a linear regression model was utilised to convert the voltage readings of the transducer into corresponding pressure values.

The power spectral density (PSD), cross-correlation and coherence function were estimated over a duration 8.0 s. The dataset was divided into 487 blocks with a 50 % overlap. Each block consisted of 2^{14} samples, resulting in frequency resolution $\Delta f = 30.5$ Hz. To calculate the PSD, the Welch method was employed along with a Hanning window. The correlation coefficient between two points (denoted x and y) is defined as $\rho_{xy}(\tau) = R_{xy}(\tau) / \sqrt{(R_{xx}(0) R_{yy}(0))}$, where $R_{xy}(\tau)$ is the cross-correlation function between the two signals, τ is the lag time, and $R_{xx}(0)$ and $R_{yy}(0)$ are the autocorrelation functions for zero lag time, with the function normalised to the range ± 1 . The magnitude-squared coherence estimate is a frequency-dependent function that ranges from 0 to 1. These values indicate the level of correspondence between signal x and signal y at different frequencies. This coherence is defined as $C_{xy}(f) = |P_{xy}(f)|^2 / \sqrt{(P_{xy}(f) P_{xy}(f))}$, where $P_{xy}(f)$ represents the cross-PSD between the two signals, and $P_{xx}(f)$ and $P_{yy}(f)$ are their respective auto-spectral densities.

3.3.2. High-speed schlieren visualisations

A conventional Z-type schlieren system was used to visualise the flow structures with different density gradients. Two concave mirrors, each with diameter 200 mm and focal length 2000 mm, were utilised to collimate the light passing through the test section and refocus it on the opposite side. A xenon lamp was directed towards an aperture in the form of a narrow opening positioned at the focus point of the concave mirror. On the opposite side of the test section, another concave mirror collected the light rays, and a knife edge was placed at the focus to visualise the density gradients of interest. A horizontal knife edge was employed to identify vertical gradient changes, thereby capturing the flapping behaviour of the shear layer. Schlieren visualisations were recorded using a Phantom 340L high-speed camera at 4×10^4 fps. For all runs, the image resolution was 512 pixels in the horizontal direction, and 100 pixels in the vertical direction. A duration of 2 μ s was chosen as the exposure time, ensuring effective freezing of the shock structures in each image.

Time-resolved image sequences can provide transient information in the flow field, assuming a linear relationship between the density gradient and light intensity in the schlieren image. Therefore, the intensity is closely related to the motion of vortex structures, shear layers or shock waves. The light intensity of each pixel in the image sequence is denoted as $I(i, j, n)$, where I represents the intensity, and i and j represent the horizontal and vertical positions in the image. The snapshot number n ranges from 1 to 3.2×10^5 . The time series that describes the evolution of light intensity at a specific pixel (i, j) can be represented as $I_{i,j}(n)$, which also indicates the change in the density gradient at that location during the selected time interval. Statistical information such as the standard deviation of the flow field captured by schlieren imaging can be derived from these data. The standard deviation map clearly highlights the presence of significant intensity fluctuations in the region in which the shock wave and edge of the boundary layer are influenced by the breathing of the separation bubble.

The spatial and temporal correlation between flow structures, such as shock waves and vortices, allows for the extraction of large-scale coherent patterns from the time series. The methodology known as spectral proper orthogonal decomposition (SPOD) offers a collection of orthogonal modes that exhibit distinct frequencies and effectively

capture the organised evolution of flow structures across both time and space domains (Towne, Schmidt & Colonius 2018). In the present study, we utilised SPOD analysis with Hanning window function and 155 blocks with 50 % overlap of 2^{12} images to reveal the characteristic of flow structures with low-, medium- and high-frequency oscillations in the STBLI.

3.3.3. The PIV measurements

We employed PIV to obtain quantitative measurements of the flow field structure and boundary layer conditions. The flow was illuminated by a double-pulsed Litron Nano200-15 Nd:Yag laser with wavelength 532 nm. The repetition rate of the laser was 15 Hz, the typical pulse energy was approximately 200 mJ, and the pulse duration was 6 ns. The laser sheet was emitted vertically onto the centreline of the flat-plate wall in the test section through an optical glass window installed on the roof.

The flow was seeded with aerosol oil particles, which had average diameter approximately $1.0\ \mu\text{m}$. These seeding particles were supplied to the tunnel through a reservoir consisting of a thin-walled pallet-sized ($4 \times 4 \times 4\ \text{m}^3$) plastic bag, similar to the one developed by Tichenor, Humble & Bowersox (2012). The reservoir was positioned upstream of the tunnel and connected directly to the inlet of the stagnation chamber. Initially, particles were injected into the reservoir, followed by even mixing using an air pump to inflate the bag to the required volume for a run. Particle concentration in the reservoir was regulated by adjusting the operating time for particle atomisation during injection. The reservoir concentration was determined based on experience to ensure a high particle concentration in the image captured. Rings attached to the reservoir were tethered with ropes to control bag deformation as its contents are emptied (similarly to a bellows). Upon opening of the butterfly valve, downstream vacuum facilitates suctioning of particles into the test section along with main flow. The Stokes number of the particle was approximately 1.1 (Stokes number = τ_p/τ_f , with $\tau_p \approx 18.9\ \mu\text{s}$ representing the time scale of the particle). Based on the findings by Brooks *et al.* (2018), it has been demonstrated that particle lag acts as a low-pass filter on fluctuating velocity PSD, thereby limiting measurable energy content. The flatter spectrum observed in wall-normal fluctuating velocity appears to render this component more susceptible to such effects compared to the streamwise component. Consequently, in this study, we employed quantitative measurements of streamwise velocity to characterise the state of the boundary layer.

To minimise the presence of high-intensity pixel regions near the wall, the steel wall surface within the field of view (FOV) was meticulously polished to restrict scattered light, and the cameras were positioned at a height comparable to that of the wall. Particle images were captured using an Impex CXP-C5341 CMOS camera with spatial resolution 5312×3040 pixels. The time offset between the double images was set at 440 ns. The FOV of the entire dual-STBLI regions measured $156\ \text{mm} \times 90\ \text{mm}$ in both streamwise and normal wall directions, respectively, with spatial resolution $34.1\ \text{pixel}\ \text{mm}^{-1}$. The PIV images were processed using PIVlab (Thielicke & Sonntag 2021) with standard iterative multi-step interrogation areas of 32×32 pixels, and a 50 % overlap in both horizontal and vertical directions. For measurements of the undisturbed turbulent boundary layer and local interactions, the FOV was set at $48.6\ \text{mm} \times 27.9\ \text{mm}$, with scaling $109.3\ \text{pixel}\ \text{mm}^{-1}$. The initial and final window sizes corresponded to 128×128 pixels and 48×48 pixels, respectively, with a 50 % overlap. Furthermore, to allow convergence of conditional mean quantities, approximately 1500 statistically independent velocity fields were acquired.

3.4. Upstream turbulent boundary layer

The flow parameters of the undisturbed boundary layer were determined by utilising measurements from PIV. The measurements were conducted 380 mm from the leading edge of the plate. The mean velocity profile is presented in [figure 4\(a\)](#). The incompressible theory is extended to include compressible flows by modifying the dimensional analysis to account for changes in density using the van Driest effective velocity (van Driest 1951). Subsequently, this velocity is combined with the Walz equation (Walz 1969) and the perfect gas law, assuming a constant pressure throughout the boundary layer. This integration yields a closed-form equation

$$u^* = \frac{u_e}{b} \sin^{-1} \left(\frac{2b^2(u/u_e) - a}{\sqrt{a^2 + 4b^2}} \right), \quad (3.1)$$

where

$$a = \left(1 + r \frac{\gamma - 1}{2} M_e^2 \right) \frac{T_e}{T_w} - 1, \quad (3.2)$$

$$b^2 = r \frac{\gamma - 1}{2} M_e^2 \left(\frac{T_e}{T_w} \right), \quad (3.3)$$

and $r = Pr^{1/3} = 0.89$ represents the recovery factor. For the case of an adiabatic zero-pressure-gradient flat-plate compressible turbulent boundary layer, when the recovery temperature is equal to the wall temperature, we have $a = 0$. And the velocity profile in the log layer is defined as

$$u_{vd}^+ = \frac{u^*}{u_\tau} = \frac{1}{\kappa} \log \left(\frac{u_\tau y}{\nu} \right) + C, \quad (3.4)$$

where $\kappa = 0.41$ and $C = 5.2$. Coles (1956) extended the log law into the outer scaling region by adding a wake function to describe the departure from the log layer. The derived law of the wake,

$$u_{vd}^+ = \frac{1}{\kappa} \log \left(\frac{u_\tau y}{\nu_w} \right) + C + \frac{2\Pi}{\kappa} \sin^2 \left(\frac{\pi}{2} \frac{y}{\delta_1} \right), \quad (3.5)$$

remains applicable throughout the logarithmic layer to the outer region, encompassing the intermediate overlap.

The statistical uncertainty associated with the mean velocity, due to limited realisations, is less than 1% U_1 . The transformed velocity profile matches well with the standard log law, and a distinct wake component characteristic of turbulent boundary layers can be identified clearly, which aligns with Coles' law of the wake (Coles 1956). The friction velocity was obtained by making a least squares fit to the law of the wake of the measured velocity profile. According to the PIV data, the boundary layer thickness δ_1 measured 8.8 mm (99% U_1), while the displacement thickness δ_1^* was found to be 3.6 mm. The momentum thickness θ was determined as 0.4 mm, and the shape factor H was calculated as 8.2. Additionally, the Reynolds number Re_θ based on momentum thickness was estimated at 1.9×10^3 . These flow conditions are summarised in [table 3](#). The reference flow is further documented by presenting a sample PSD graph in [figure 4\(b\)](#), which illustrates the wall pressure within the undisturbed boundary layer. The fluctuation energy remains broad and consistent across the low-frequency range, which is in accordance with

δ_1 (mm)	δ_1^* (mm)	θ (mm)	H	Re_θ
8.8	3.6	0.4	8.2	1.9×10^3

Table 3. Summary of flow conditions.

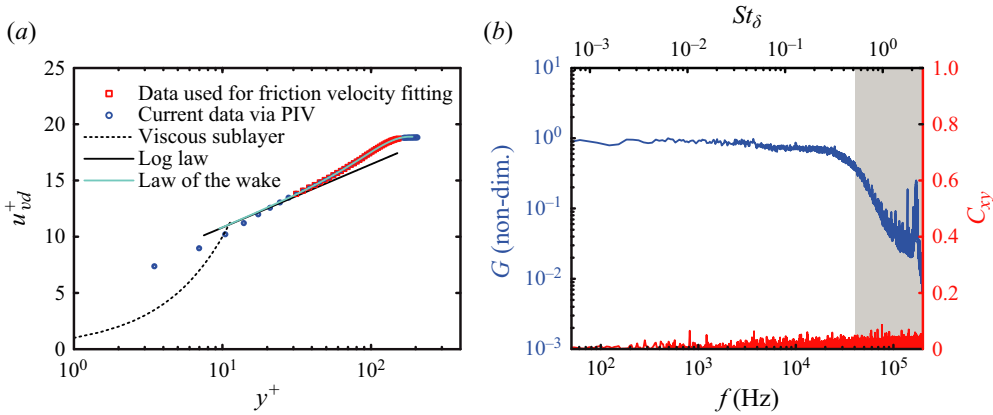


Figure 4. Turbulent boundary layer conditions. (a) Velocity profile of the upstream turbulent boundary layer obtained by PIV and Pitot tube. (b) The PSD based on wall pressure (blue) and the coherence C_{xy} (red) between the wall pressure within the upstream boundary layer and separation. The grey shaded area indicates the region outside sensor frequency response (>40 kHz).

the results of high-speed flow experiments conducted by Beresh *et al.* (2011). Furthermore, we examined the potential correlation between the pressure fluctuations in the incoming flow and those in the recirculation region. Figure 4(b) illustrates the coherence between the wall pressure measurements within the incoming boundary layer and at the separation shock foot. This coherence suggests that a minimal correlation exists between the pressure fluctuations in the upstream boundary layer and low-frequency unsteadiness near the separation.

4. Mean flow organisation

4.1. Expanded separation: the role of a retarded boundary layer

Time-averaged schlieren images were used to investigate the overall separation trends of the interactions. The interference between weak interacting flows originating from different upstream shock impact locations and a strong STBLI is illustrated in figure 5. Furthermore, the mean wall pressure normalised by the free-stream pressure and the relative standard deviation σ_p/p_w along the centreline for each case are also presented. The incident shock i , as shown in figure 5(a), impacts approximately 52 mm upstream from the origin of the compression corner ($x = 0$ mm). For ease of comparison in the subsequent cases, we define the impinging location as the intersection between the incident shock extension line and the wall surface in the inviscid flow; however, because of the upstream bending of the incident shock beneath the boundary layer, the actual shock foot is positioned 5 mm upstream from this impinging location. Reflected shock ii is relatively weak because of the small deflection angle of the wedge. The nominal Mach number downstream from the first STBLI region was 3.89, and the compression-ramp-induced

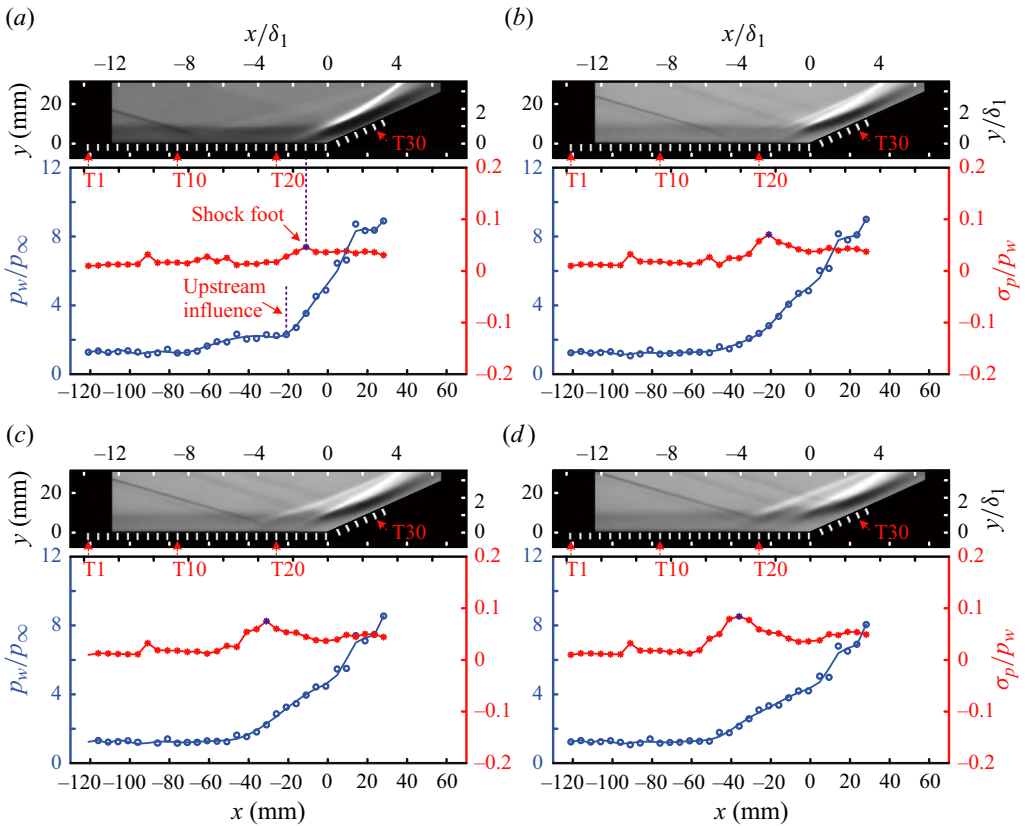


Figure 5. Distributions of wall pressure and relative standard deviation for case A with different spacings between the two interaction regions, along with the mean flow structures: (a) $d = 52$ mm, (b) $d = 30$ mm, (c) $d = 19$ mm, (d) $d = 10$ mm.

STBLI led to a separated boundary layer. The wall pressure distribution reveals the presence of two pressure increases: one caused by the incident shock, and the other induced by the shock at the compression corner. The separation point captured by the schlieren image is approximately 6 mm upstream from the corner. The local maxima for σ_p/p_w can be employed to identify the shock foot. The peak observed at T7 may have been caused by a spanwise shock wave that occurred because of the gap between the test section and either the nozzle or the window. The interaction extent L_{ext} , which is defined as the distance between the origin of the interaction and the location of the separation point of the compression-ramp-induced STBLI identified by wall pressure measurements, is approximately 15 mm.

When the incident shock shifts 10 mm downstream ($d = 41$ mm), besides the displacement of the incident shock and slight expansion of the separation region, no significant changes are observed in the flow field depicted in figure 5(a); therefore, detailed flow information is not provided here. Notably, even though the upstream STBLI is relatively weak, the turbulence in the incoming boundary layer is distorted by its passage across the shock wave, then is convected downstream and contributes to the formation of a new boundary layer. In addition, the adverse pressure gradient caused by the incident shock cannot be ignored. The STBLI at the compression corner encounters a progressively incomplete boundary layer as the incident shock moves downstream.

The presence of such a disturbed boundary layer (retarded boundary layer) is thought to affect the flow parameters at the downstream separation, such as shear stress. According to the free-interaction theory, these flow parameter variations can affect both the initial pressure increase and the length of the region associated with the separation. However, owing to either the limitations in the transducer distribution or a relatively weak STBLI, no significant effect is observed, and L_{ext} remains unchanged in these two scenarios.

The incident shock in [figure 5\(b\)](#) shifts further downstream with $d = 30$ mm, and the downstream STBLI also undergoes a significant change in this scenario. Notably, although the displacement of the shock foot remains consistent with the previous observations (d changes from 52 mm to 41 mm and then to 30 mm, corresponding to a variation of 5 mm in the shock foot position towards upstream), a sudden and substantial increase in L_{ext} occurs, where L_{ext} reaches 40 mm. This length is more than twice the previous length. Additional shock waves for which the origin location (time-averaged) is consistent with the upstream influence (UI) are more perceptible in this scenario. The intensity and shock angle at the UI are greater for the downstream interaction than for the upstream one, indicating that flow deflection exceeds that caused by the upstream shock. The gradual rise in pressure towards the separation point can be attributed to both the combination of the incident shocks and the UI resulting from the downstream STBLI.

The incident shock in [figure 5\(c\)](#) undergoes a displacement of an additional 10 mm. In the absence of interference between the two interaction regions, the impingement point of the upstream incident shock should ideally align with the starting point of the UI as shown in [figure 5\(a\)](#). However, the time-averaged schlieren image reveals a significant change in the origin of the compression wave as it crosses the impinging point of the upstream incident shock. Despite this difference, no shift in the location of the separation point identified by the schlieren image compared with that depicted in [figure 5\(b\)](#) is apparent. The peak position of σ_p/p_w also exhibits a notable displacement, which is consistent with the alterations observed in the schlieren image depicting the compression wave. The significant reduction in the skin friction coefficient within the interaction region is a crucial characteristic of the STBLI, and based on the free-interaction theory, the interaction extent L_{ext} is inversely proportional to the skin friction coefficient. From this phenomenon, we can infer that the upstream STBLI region overlaps with the initial portion of the downstream STBLI region. The sudden change in L_{ext} results from drastic changes in the local flow conditions at the separation point of the downstream STBLI. An evident extension of the separation is observed in [figure 5\(d\)](#), whereas the length L_{ext} appears to be consistent with that in [figure 5\(a\)](#). In this scenario, the shock foot has already passed the impingement point of the upstream incident shock; thus the incident shock no longer affects the flow parameters at separation.

Even with a small deflection angle, the impact of the incident shock is evident. [Figure 6](#) illustrates the variation in the shock foot position at the compression corner in case A. Initially, the shock foot position changes linearly with d , which aligns with the gradual variations in the flow parameters within the boundary layer downstream from the first STBLI region. However, when d reaches 19 mm, a shift in the shock foot position occurs. According to the free-interaction theory, the local flow parameters affect the extent of the interaction, resulting in changes in the UI; however, the local flow does not affect the separation. The superposition of pressure gradients also plays a crucial role in this situation. A greater length is required for the development of the separation shear layer (flow acceleration) to achieve a larger pressure increase. In addition, the separation can be facilitated by the presence of a retarded boundary layer following the interaction region.

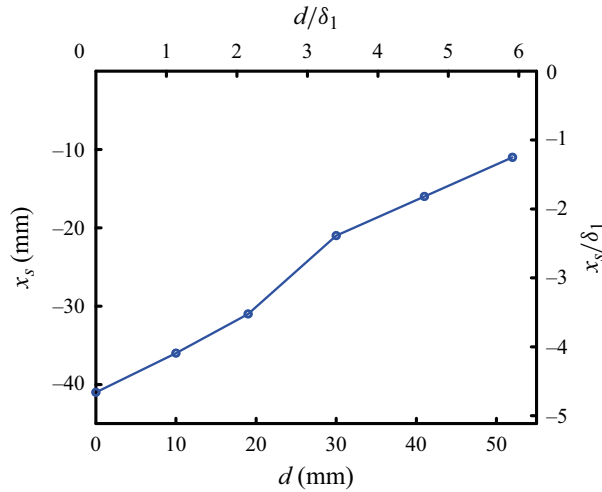


Figure 6. Variation of the shock foot position in case A. These locations were determined according to the peak of the relative standard deviation.

The mean flow behaviour is also described by the average streamwise velocity field in [figure 7\(a\)](#). The contour lines are densely distributed around dimensionless velocity 1.0, making the incident shock visible despite its relatively weak intensity. The distorted boundary layer downstream from the first STBLI region seems to exhibit a gradual increase in thickness at a relatively modest rate. The profiles of the streamwise velocity in the wall-normal direction at $x = 25$ mm are shown in [figure 7\(b\)](#). When the first STBLI is at a distant location, such as $d = 52$ and 30 mm, no significant change occurs in the boundary layer state upstream from the interaction region at the compression corner. However, when the incident shock continues to move downstream ($d = 19$ mm), a notable deficit is observed in the streamwise velocity. This deficit caused by an adverse pressure gradient could be due to either the upstream incident shock or forward propagation of the adverse pressure gradient from the downstream interaction region. The comparison of the first two scenarios reveals that even in the latter case, the deficit in the velocity profile is ultimately attributed to the alteration of the local boundary layer state caused by the upstream incident shock wave.

In the scenario in which $d = 19$ mm, small-field-of-view PIV measurements were conducted in the region between $x = -40$ mm and $x = 0$ mm. The root mean square (r.m.s.) of the streamwise velocity fluctuations is shown in [figure 8](#), together with the locally magnified schlieren image. A region of high-energy fluctuations, starting at approximately $x = -15$ mm, is observed in the r.m.s. contour, indicating the initiation of the shear layer within the separation. Furthermore, fluctuations with a specific level extend upstream to the vicinity of $x = -30$ mm, which corresponds to both the peak position of the pressure fluctuation and the area encompassed by the compression waves. These compression waves exhibit a remarkable unsteady behaviour, which will be analysed in the subsequent section on shock unsteadiness.

4.2. Expanded separation: the role of a relaxing boundary layer

This situation differs when the relative positions of the two interaction regions change. In this case, the interaction with the separation occurs upstream. The incident shock

Structure and unsteadiness of dual STBLIs

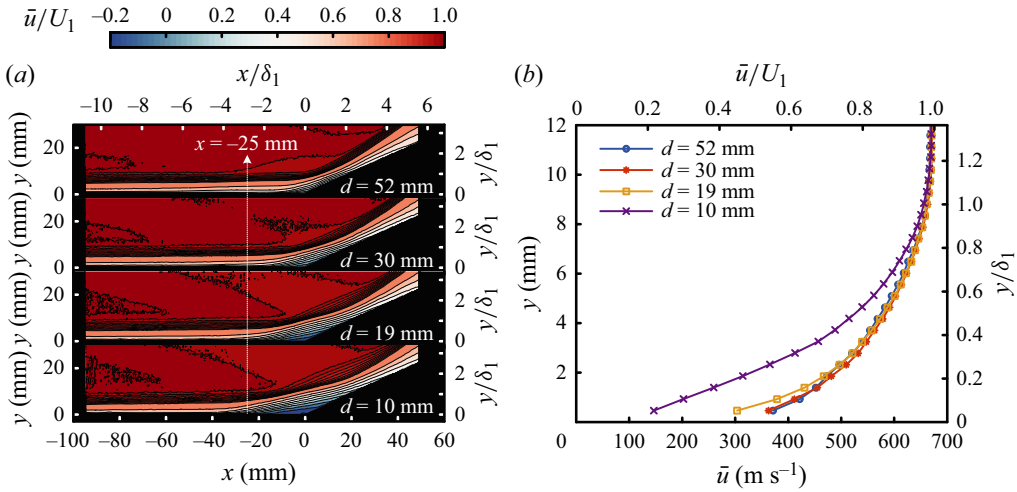


Figure 7. Mean streamwise velocity distribution \bar{u}/U_1 in case A. (a) Streamwise velocity contours from -0.2 to 0.9 in increments of 0.1 , and from 0.9 to 1.0 in increments of 0.01 . (b) Streamwise velocity profiles with various d at $x = -25$ mm.

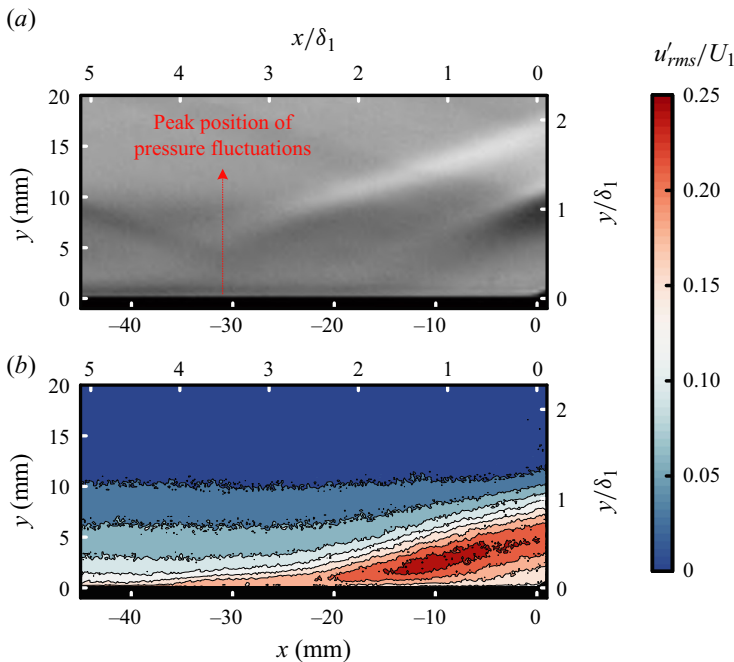


Figure 8. Comparison of (a) time-averaged schlieren image and (b) r.m.s. streamwise velocity fluctuations in the magnified field of the interaction region with $d = 19$ mm.

impacts a location approximately 56 mm upstream from the origin of the compression corner, as shown in figure 9(a). Owing to the relatively large deflection angle of the wedge, the incident shock is sufficiently strong to induce a separate boundary layer in the first STBLI region. The nominal Mach number downstream from this region is 2.85. The compression-ramp-induced STBLI leads to a boundary layer without any apparent separation, even at deflection angle 24° . A potential explanation is that the upstream

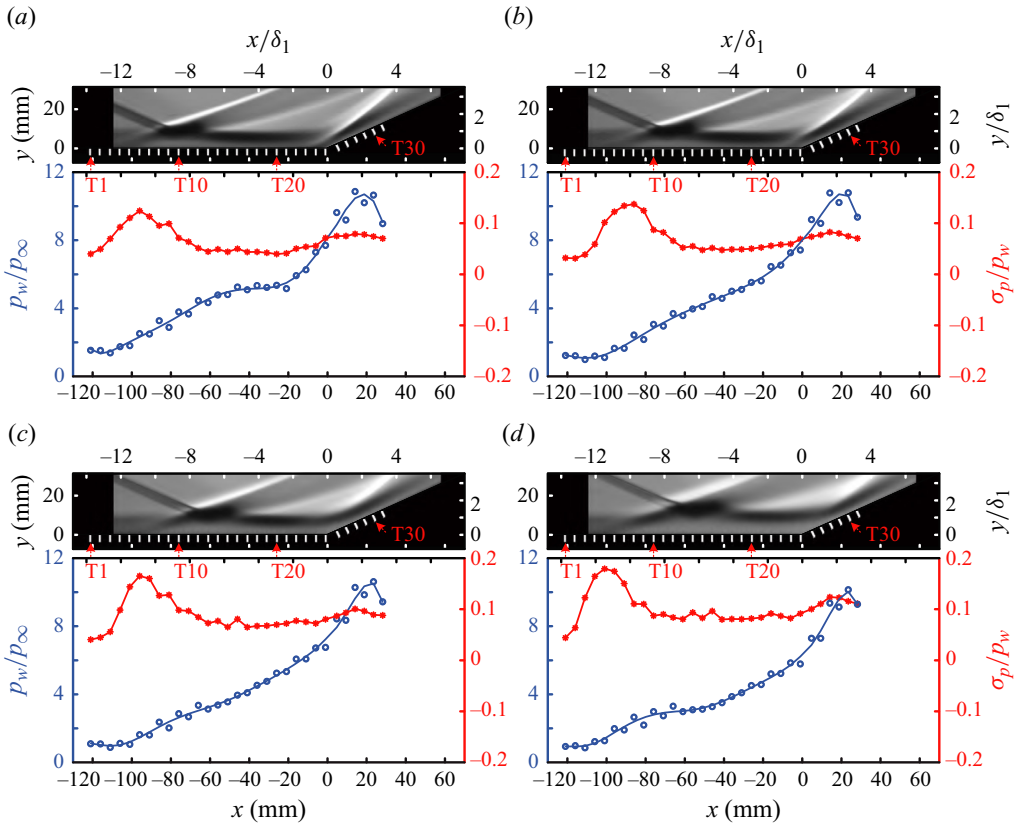


Figure 9. Distributions of wall pressure and relative standard deviation for case B with different spacings between the two interaction regions, along with the mean flow structures: (a) $d = 56$ mm, (b) $d = 45$ mm, (c) $d = 36$ mm, (d) $d = 25$ mm.

expansion waves induced by the shock generator exert a beneficial influence on the downstream STBLI region. The shock foot, identified using the relative standard deviation, is located near transducer T6. This location aligns with the results of the schlieren image analysis. The absence of a pressure plateau in the pressure distribution can be attributed to the relatively weak incident shock at this Mach number, despite inducing separation. According to Xue *et al.* (2023), under the current flow conditions, the critical flow deflection angle is 24.8° , beyond which further increases in pressure may cease and the pressure may exhibit non-monotonic changes, potentially approaching a plateau.

When the incident shock shifts 10 mm downstream, as shown in figure 9(b), the separated STBLI region approaches the downstream region while simultaneously experiencing a similar displacement of the shock foot position. Wall pressure continuously increases from the UI to the compression surface. Furthermore, with the emergence of compression waves, the sonic line gradually moves away from the wall as the flow develops. This observation suggests a change in the subsonic region beneath the boundary layer between these two regions. However, subsequent analysis of the shear layer evolution indicated that a complete connection was not established. As shown in figure 9(c), the incident shock shifts further downstream, making the connection between the two interaction regions more evident. A distinctly separated boundary layer between the two

regions can be observed in the schlieren image. The extension of the shock waves towards the lower part of the boundary layer ceases to occur at the compression corner.

In [figure 9\(d\)](#), the incident shock undergoes a downstream shift of an additional 10 mm, resulting in an enlarged merged separation region compared with that in the previous scenario. Simultaneously, a pressure plateau is observed in the wall pressure distribution, which is equal to the value estimated using free-interaction theory. However, the pressure plateau does not extend to the compression corner; instead, it terminates at the location of vortex shedding and is followed by a gradual increase in pressure until it reaches the compression surface because of the compression waves upstream from the reattachment shock. The shock foot moves upstream once again towards transducer T5. In the scenarios with $d = 16$ and 6 mm, the separation shock gradually moves upstream as the incident shock progresses downstream, and the size of the separation region continuously expands. The presence of pressure plateaus also become more prominent, coinciding with the increasing platform area.

The average streamwise velocity fields for case B are displayed in [figure 10\(a\)](#). For the scenario in which $d = 56$ mm, the velocity profiles at different streamwise locations downstream from the first STBLI region are presented in [figure 10\(b\)](#). When the two interaction regions are far apart, the downstream boundary layer develops with a relatively low rate of recovery until it reaches the compression corner. When the incident shock moves downstream, it fails to reach the UI of the downstream interaction region starting at approximately $x = -11$ mm. The adverse pressure gradient initially affects the relaxing boundary layer from downstream, causing a gradual displacement of the sonic line within this boundary layer away from the wall, and resulting in a sequence of compression waves in the second STBLI region. As the interaction regions approach each other ($d = 36$ mm), the PIV results reveal a clear connection between the low-energy fluids in the two regions. Furthermore, the schlieren images demonstrate the fusion of the two separation zones, as illustrated in [figure 9\(c\)](#). From this spacing, a reverse movement is observed for the separation shock of the first STBLI. At this point, the adverse pressure gradient induced by the compression corner influences the upstream region through a separated boundary layer. The combined influence of these factors results in the expansion of the separation zone and transition of the reattachment position.

Overall, the boundary layer between the two STBLI regions plays an important role in the separation expansion. Even with a small deflection angle, the incident shock decelerates the boundary layer, leading to significant changes in the UI and peak position of pressure fluctuations. Downstream from the separated STBLI, the relaxing boundary layer develops with a relatively low rate of recovery and is easier to separate when subjected to adverse pressure gradients. The adverse pressure gradient is more likely to propagate upstream through these perturbed boundary layers when the two interaction regions approach each other, rather than through fully developed turbulent boundary layers.

5. Unsteadiness in the interactions

5.1. Streamwise evolution of the PSD

At each transducer, the pressure was normalised with respect to p_∞ , and the PSD of the wall pressure was computed over each run to characterise the streamwise variations of the wall pressure dynamics. [Figure 11](#) presents maps of the frequency-premultiplied PSD ($f G(f)$) of the pressure fluctuations for case A. The spectra are normalised by the variance of the local wall pressure below 40.0 kHz. To enable interpretation with reference to the

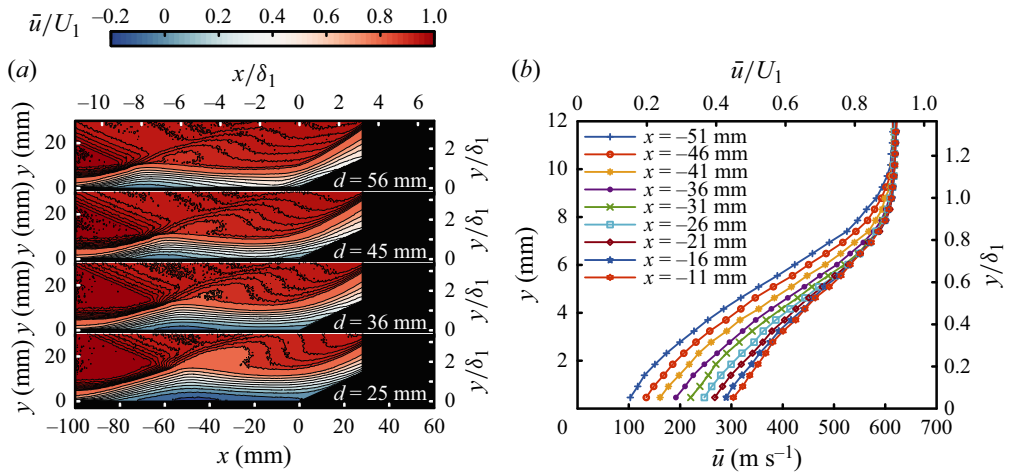


Figure 10. Mean streamwise velocity distribution \bar{u}/U_1 in case B. (a) Streamwise velocity contours from -0.2 to 0.9 in increments of 0.1 , and from 0.9 to 1.0 in increments of 0.01 . (b) Evolution of streamwise velocity profiles at various positions with $d = 56$ mm.

boundary layer time scales, the right-hand axis in the spectra is shown in terms of $St_\delta = f\delta_1/U_1$. We also give the non-dimensional frequency based on the interaction length L_{int} in the subsequent analysis. In all cases, the peak energy should be located at the convection frequency ($U_1/\delta_1 = 89.51$ kHz); however, these peaks fall near 40 kHz, which is the cutoff frequency of the transducer.

The presence of a weak low-frequency component can be observed at a fixed position between $x = -100$ mm and $x = -80$ mm in figure 11(a), which is consistent with the occurrence of the peak in the distribution of σ_p/p_w in figure 5. This unexpected disturbance can be attributed to the spanwise developing shock caused by the gap between the optical window and the sidewall. Downstream from this region, oscillations induced by the incident shock can be observed within the frequency range from 1.0 kHz to 5.0 kHz. At the mean location of the shock foot ($x \approx -20$ mm), the low-frequency content caused by the STBLI at the compression corner is also detected, and downstream from this interaction region, the broadband peak shifts towards higher frequencies. As the incident shock moves downstream, as illustrated in figures 11(b,c), no significant change is evident in the high-frequency component of the interaction. However, a gradual extension of the upstream low-frequency component is observed. In figure 11(b), the dynamic characteristics of the two interaction regions can still be distinguished. As depicted in figures 11(c,d), when the upstream incident shock enters the downstream interaction region, the range of low-frequency oscillations exhibited by the separation shock expands. The location of the energy peak in the low-frequency component is also in accordance with that indicated in figure 5(c).

The connection between the two interaction regions is more evident in case B, as depicted in figure 12. Within the upstream STBLI region, low-frequency dominance with a local maximum at 719.0 Hz ($St_\delta = 0.008$, $St_{L_{int}} = 0.04$) can be observed at the shock foot in both figures 12(a) and 12(b). Subsequently, high-frequency fluctuations emerge at approximately 37.0 kHz ($St_\delta = 0.41$, $St_{L_{int}} = 2.2$), indicating the incipient instability of the separated shear layer. In the relaxation region between the two interaction regions, the flow exhibits only high-frequency fluctuations.

Structure and unsteadiness of dual STBLIs

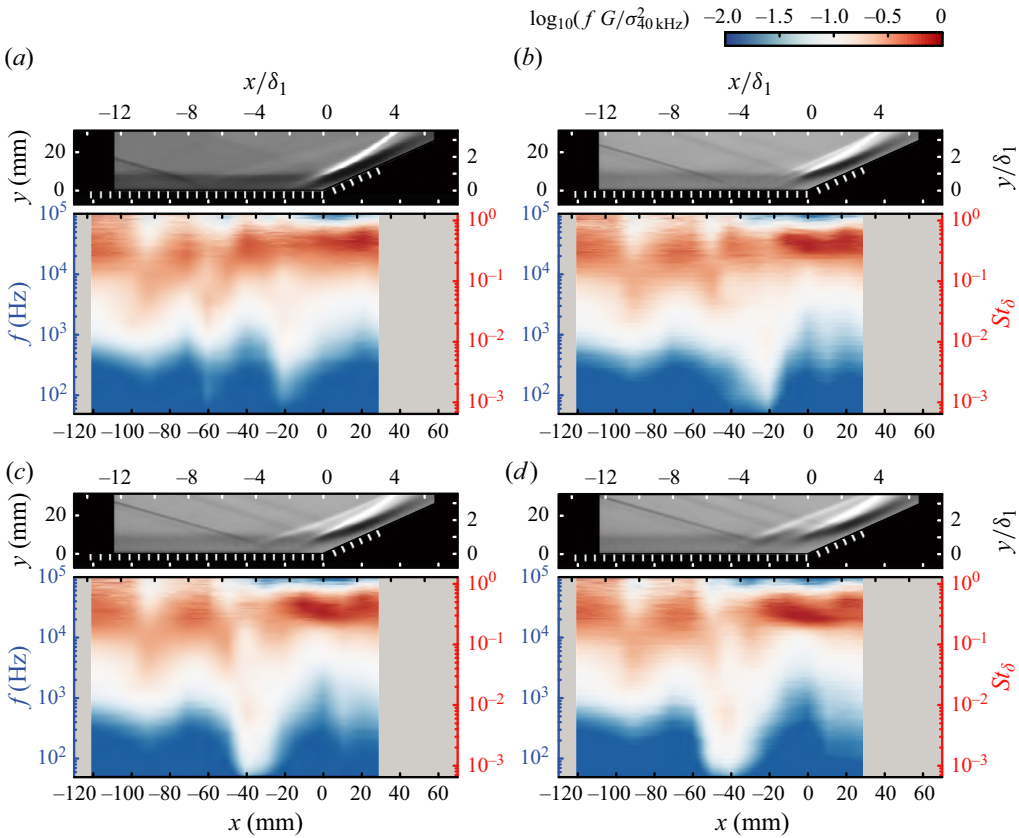


Figure 11. Streamwise evolution of frequency-premultiplied pressure fluctuation PSD for case A with (a) $d = 52$ mm, (b) $d = 30$ mm, (c) $d = 19$ mm, (d) $d = 0$ mm. All plots have the same spatial coordinates (x - y plane) scaled by the boundary layer thickness and contour levels.

The spectral evolution over the two STBLI regions with smaller spacings is illustrated in figures 12(c) and 12(d), where distinct low-frequency oscillations are observed between the two regions. An increase in energy content is observed at frequencies of approximately 183.0 Hz ($St_\delta = 0.002$, $St_{L_{int}} = 0.02$) near the shock foot, whereas a dominant instability of 18.4 kHz ($St_\delta = 0.21$, $St_{L_{int}} = 2.04$) subsequently emerges downstream from the separation shock. This unsteadiness signifies the initial stage of shear layer development. The subsequent shedding of the shear layer is observed to transition to lower frequencies as it progresses along the recirculation length, reaching 15.2 kHz ($St_\delta = 0.17$, $St_{L_{int}} = 1.68$) near the expansion fan at $x = x_0 + 0.5L_{int}$, where x_0 is the shock foot location. After vortex shedding, this frequency remains nearly constant up to the compression corner. When the separation extends to the corner, forming a large separation, the low-frequency spectrum with substantial power moves upstream along with the separation shock. The low-frequency component persists in the recirculation region, albeit with diminishing power. With an increase in the separation scale, the shear layer becomes longer, leading to a decrease in the vortex shedding frequency downstream.

The range of low-frequency bands can serve as an additional indicator for determining the range of the shock motion, which is observed to be 20 mm in figure 12(b).

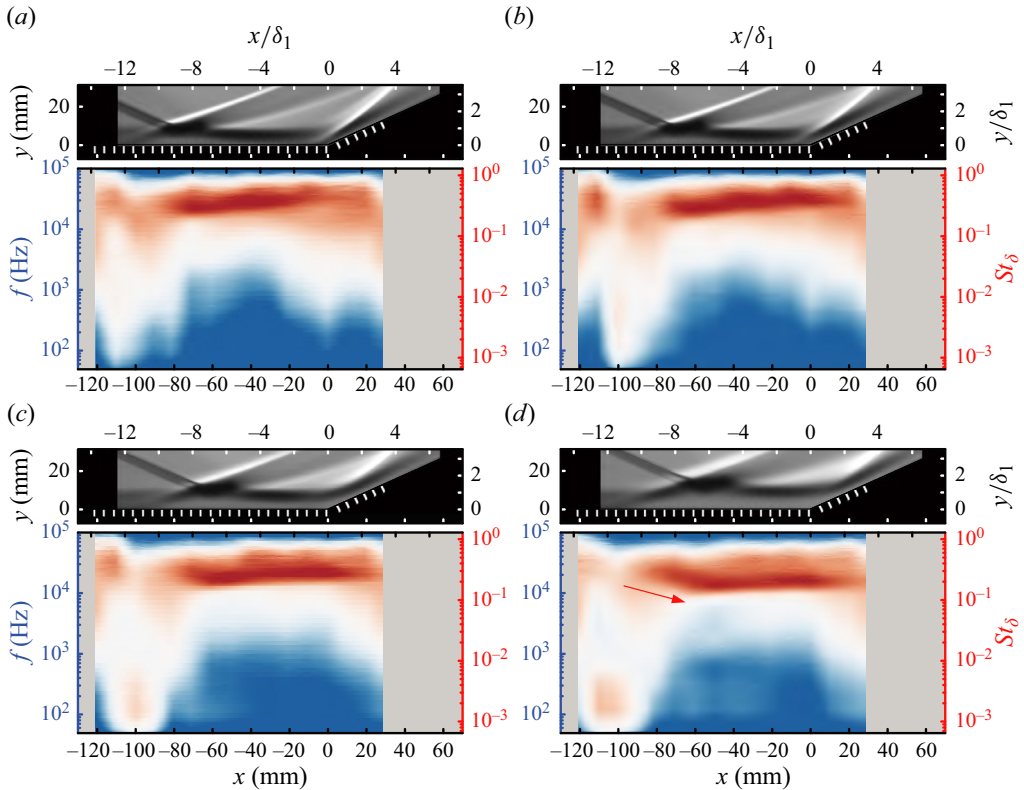


Figure 12. Streamwise evolution of frequency-premultiplied pressure fluctuation PSD for case B with (a) $d = 56$ mm, (b) $d = 45$ mm, (c) $d = 36$ mm, (d) $d = 25$ mm. All plots use the same contour set and spatial coordinates as those in figure 11.

For peak frequency 427.2 Hz, the shock velocity is estimated to be 8.5 m s^{-1} or approximately 1.2% of the free-stream velocity, closely matching the typical literature value of 2.0%. Furthermore, the observed trend in the separation shock velocity with increasing separation scale is consistent with the findings of Estruch-Samper & Chandola (2018). The essential components in STBLI, namely, the shock system, shear layer and separation bubble, play crucial roles in determining the unsteady characteristics (Wu & Martin 2008). This section provides a comprehensive overview of the unsteady features exhibited by dual-STBLIs along the flow direction. A detailed analysis is presented for each individual aspect.

5.2. Shock wave unsteadiness

Even if the incident shock is relatively weak, the boundary layer downstream from the STBLI region is disturbed, rendering it more susceptible to thickening or separation in the presence of adverse pressure gradients. This decelerated boundary layer can significantly influence the subsequent STBLI when the two interaction regions are closely positioned, as observed in the current case. The wall pressure begins to increase upstream from the nominal separation or interaction point in the STBLI region owing to the pressure gradient. With a less fully developed boundary layer, this effect extends further upstream, as does the low-frequency oscillation of the waves induced by UI.

Structure and unsteadiness of dual STBLIs

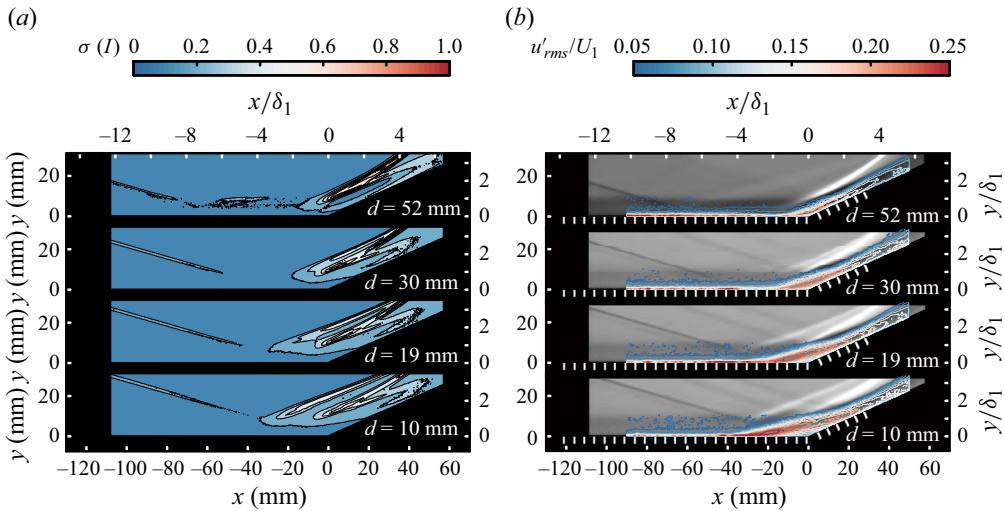


Figure 13. Fluctuations in the flow field with various spacings between the two STBLI regions in case A. (a) Standard deviation (temporal) intensity maps of the dual-STBLIs obtained from schlieren image sequences. Levels of contour are spaced by 0.2. (b) The r.m.s. streamwise velocity fluctuations normalised by the mean streamwise velocity upstream of the STBLI superimposed with the time-averaged schlieren images. Levels of contour are spaced by 0.02.

This process can be observed effectively using high-frame-rate schlieren imaging and PIV. The standard deviation of the image intensity obtained from a temporal sequence of 3.2×10^5 schlieren images is illustrated in figure 13, along with the superimposed r.m.s. streamwise velocity fluctuation on the time-averaged schlieren image for case A. Due to the different visual principles on which schlieren imaging and PIV are based, they complement each other in revealing the unsteady features in the interaction region. Schlieren imaging can capture structural changes in flow fields with large density gradients, including shock waves and shear layers. The standard deviation map reveals fluctuations in both the incident shock and boundary layer. However, the magnitudes of these fluctuations are significantly lower than those of the shock oscillation at the compression corner. Within the boundary layer and the interaction region, the PIV enables the quantitative measurement of the flow field, facilitating an accurate assessment of the boundary layer state.

When the spacing between the two STBLI regions is relatively large, as depicted in figure 13(a) with $d = 52$ and 30 mm, the separation shock becomes distinctly discernible in the standard deviation map. The separation shock manifests as a distinct region characterised by significant intensity fluctuations, indicating the unsteady nature of the STBLI. The downstream boundary layer also exhibits a certain level of turbulence. Shock motions typically arise from specific causes, as evidenced by the PIV results in figure 13(b), indicating a higher level of velocity fluctuation beneath the separation shock within the interaction region. These fluctuations encompass diverse frequencies, including the breathing of the separation bubble and shear layer development. The downstream movement of the incident shock, as illustrated in figure 13 with $d = 30$ and 19 mm, has a negligible effect on the position of the separation shock at the compression corner. The interaction region at the compression corner is expected to experience an expansion of high-level fluctuations. However, noticeable oscillations of additional waves induced by the UI can be observed distinctly not far upstream in the standard deviation map.

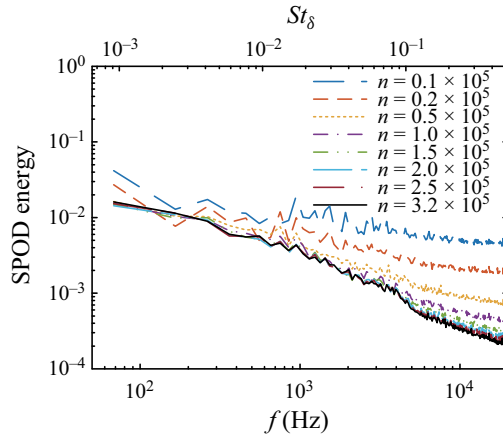


Figure 14. Dependence of the SPOD energy convergence on the number of samples.

The downstream movement of the incident shock leads to a gradual upstream movement of the additional waves generated at the UI, intensifying the oscillations. An analysis of the standard deviation map reveals that variations in the incident shock do not affect the position of the original separation shock at the compression corner. However, violent oscillations are observed in the waves generated at the UI.

The standard deviation map and PIV results enable the observation of amplified oscillations in the upstream influence waves and separation region; however, they do not provide insights into the frequency components present in the interaction regions. To overcome this limitation, we analysed and summarised the SPOD modes across all frequencies. Before further discussions, we would like to emphasise that the number of data samples utilised in this analysis is sufficient. The leading SPOD modal energies obtained with different snapshots of instantaneous fields are shown in figure 14. When the number of snapshots exceeds 1.0×10^5 , the difference in energy for low frequencies is minimal, whereas when the number of snapshots exceeds 2.0×10^5 , the differences in high frequencies gradually decrease. Considering the very tiny discrepancy between the distributions obtained with $n = 2.5 \times 10^5$ and $n = 3.2 \times 10^5$, convergence of the SPOD energy is regarded as sufficient. In addition, the SPOD result exhibits a broadband and energetic low-frequency component associated with the separation shock unsteadiness, which is consistent with the wall pressure measurements.

Three primary shapes emerge, which can be seen in both cases: first, low-frequency oscillations are predominantly influenced by the separation shock; second, medium-frequency oscillations are associated with the oscillation of the separated shear layer; and third, relatively high-frequency oscillations are characterised by small-scale coherent structures originating from vortex shedding. When the two interaction regions are sufficiently far apart, as illustrated in figure 15(a), the typical characteristics of the STBLI can be observed at the compression corner. From the inspection of the leading SPOD mode, we can conclude that the low-frequency oscillations, such as those at $St_\delta = 0.007$, are dominated by the separation shock motion at the compression corner. This observation is consistent with the fundamental understanding of STBLI, in that separation bubble breathing and large-scale separation shock motion occur predominantly at lower frequencies. The separated shear layer exhibits significant coherent fluctuations, such as

Structure and unsteadiness of dual STBLIs

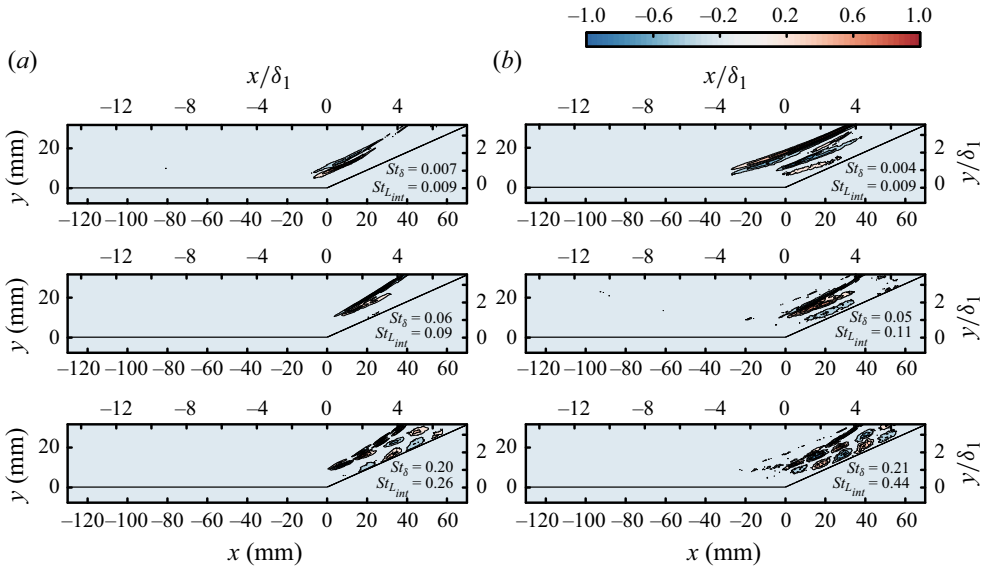


Figure 15. First SPOD composed of flow fluctuations obtained from schlieren image sequences in case A with (a) $d = 52$ mm, (b) $d = 19$ mm. The plots illustrate low-, medium- and high-frequency oscillations in the flow, arranged from top to bottom. The contours represent the real part of the first SPOD mode, with the levels spaced at intervals of 0.1.

flapping of the mixed layer and structural shedding, predominantly at low and medium frequencies ($St_\delta = 0.007$ and 0.06).

When the two interaction regions are in close proximity, as shown in figure 15(b), an additional shock wave with low-frequency oscillations originates from the UI, and the most energetic fluctuations are in this shock. However, this shock does not exhibit medium- or high-frequency unsteadiness. The shear layer provides energetic contributions at both low and medium frequencies. Similar findings were obtained in a study on the STBLI induced by a compression ramp (Grilli *et al.* 2012). The authors employed dynamic mode decomposition to analyse the presence of a low-frequency mode associated with the pulsation of the separation bubble. In another investigation on transonic STBLI (Sartor *et al.* 2015), Fourier-mode decomposition was utilised to examine the effects of low-frequency perturbations on both the shock wave and the top of the recirculation bubble. At medium frequencies, noticeable elongated coherent structures are present on the compression surface, as depicted in figure 15(b), suggesting intermittent movement of the shear layer in the direction normal to the wall. At a relatively high frequency ($St_\delta = 0.21$), streamwise periodic structures with small scales appear within the mixing layer in both figures 15(a) and 15(b).

Interestingly, only low-frequency oscillations are observed in the shock waves originating from the UI, which could be due to the existence of the retarded flow in the region upstream from the separation. Murphree *et al.* (2021) reported a similar phenomenon, wherein the planar laser scattering and pressure PSD revealed a retarded or weakly separated flow upstream from the region in which the separation was induced by a cylinder. The study conducted by Humble, Scarano & van Oudheusden (2009) revealed that vortex structures exhibit lifting behaviour even in the absence of a significantly reversed flow region. These vortex structures respond to the highly retarded flow within the inner layer, as illustrated in figure 8, similar to their response to a large-scale

recirculating bubble. Consequently, when no substantial deficit exists in the inner layer velocity, no lifting of vortex structures is observed. This finding is particularly important in the present interaction because the upstream STBLI strongly favours the occurrence of retarded flow. Even without a large-scale reversed-flow region, this retarded flow can instantaneously exhibit many features that are typically associated with large-scale separated interactions. In this case, the free-interaction theory provides a mathematical framework for establishing the connection between local conditions and the UI, whereas the presence of retarded flow offers a tangible physical basis.

5.3. Shear layer evolution

The shear layer plays a crucial role in the STBLI. The extent of the separation is determined by the ability of the shear layer originating from the separation point to overcome the pressure increase at the reattachment point. This ability is influenced by the initial momentum available during the process of reattachment. According to the free-interaction theory, it can be observed that the pressure rise leading up to separation is independent of the downstream conditions. Consequently, a higher overall pressure increase applied to the boundary layer or an escalation in shock intensity necessitates a greater pressure increase during reattachment. This increase can be accomplished only by increasing the velocity attained on the dividing streamline; thus extending the length of the shear layer is essential for facilitating more substantial momentum transfer from the outer flow. Additionally, Piponniau *et al.* (2009) proposed a hypothesis regarding the instability of the STBLI. They suggested that the unsteadiness of the separation bubble could be caused by a process of entrainment and recharge driven by the shear layer. The low-momentum fluid inside the separation bubble can be drawn in by the shedding mechanism through the action of the shear layer. Hereafter, the analysis focuses exclusively on unsteady effects within the separation region.

In case A, the most notable phenomenon is the change in the shock foot. In case B, the oscillation of the separation shock at the upstream position exhibits the expected behaviour, whereas the variation in the shear layer is worth noting. As the two interaction regions gradually approach each other, as depicted in [figure 9](#), reattachment in the upstream region no longer appears, and the shock wave at the compression surface gradually moves downstream with the fusion of the two interaction regions. When focusing on the area between these two regions, many compression waves appear upstream as the spacing decreases.

The standard deviation of the image intensity, along with the superimposed r.m.s. streamwise velocity fluctuation on the time-averaged schlieren image for case B, is depicted in [figure 16](#). When the two interaction regions are far apart, as shown in [figure 16\(a\)](#) with $d = 56$ and 45 mm, fluctuations with certain intensities can be observed in the separation and reattachment shocks of the upstream STBLI and the shock wave at the downstream compression ramp. The presence of fluctuations at the edge of the mixing layer originating from vortex shedding, and at the top of the recirculation bubble, should also be considered in the standard deviation map. Similar to case A, regions exhibiting high-level velocity fluctuations are observed within the interaction regions and are situated beneath the separation shocks, as shown in [figure 16\(b\)](#). When the spacing between the two regions decreases, large-range fluctuations caused by compression waves occur between these regions. Simultaneously, the oscillations in the mixing layer between these two regions are enhanced to a certain extent. With an increasing separation scale, the shear layer progressively moves away from the wall. The intriguing aspect lies in the gradual expansion of velocity fluctuation as the two interaction zones approach each other,

Structure and unsteadiness of dual STBLIs

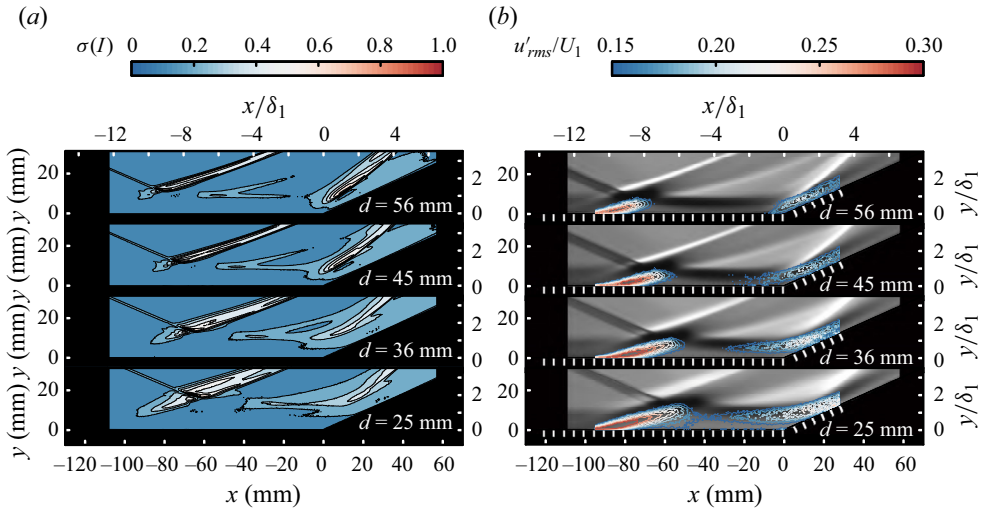


Figure 16. Fluctuations in the flow field with various spacings between the two STBLI regions in case B. (a) Standard deviation (temporal) intensity maps of the dual-STBLIs obtained from schlieren image sequences. Levels of contour are spaced by 0.2. (b) The r.m.s. streamwise velocity fluctuations normalised by the mean streamwise velocity upstream of the STBLI superimposed with the time-averaged schlieren image. Levels of contour are spaced by 0.02.

extending upstream through a separated shear layer. However, the frequency composition of these oscillations remains unknown.

Figure 17 shows the leading SPOD modes of the light intensity fluctuations obtained from the schlieren system. The low-frequency oscillations in all scenarios are governed primarily by the separation shock in the upstream STBLI region, accompanied by the motion of the shear layer normal to the wall, similar to what is depicted in figure 15. Streamwise periodic structures with small scales appear within the mixing layer at high frequencies. When the two interaction regions are widely separated, as depicted in figure 17(a), the range of low- and medium-frequency oscillations in the downstream mixing layer of the first STBLI region is limited, with the perturbation diminishing to a low level at a short distance downstream, whereas high-frequency periodic structures persist until they reach the compression surface. The shock wave at the compression corner is influenced by the mixing layer and vortex structures induced upstream, and these effects can be observed at low, medium and high frequencies. As the two regions approach each other, as shown in figure 17(b), coupled with the observations in figure 9(d), the separation of the mixing layer downstream from the first STBLI region results in more pronounced oscillations that extend to the compression surface, thereby influencing the compression waves above it. The elongated structures within the mixing layer extend continuously to the compression surface, indicating vertical amplitude oscillations of the entire mixing layer. When the scale of separation increases further, the elongated structures move away from the wall with the mixing layer. Notably, both the mixing layer fluctuations and the small-scale eddies originate downstream from the expansion fan or vortex shedding.

The source of low-frequency oscillations in the STBLI has been summarised in Clemens & Narayanaswamy (2009) and Souverein *et al.* (2010). The findings reported in those works indicate the presence of both upstream and downstream effects, with their significance varying depending on the degree of separation and the interaction strength. In cases in which the boundary layer is fully separated, the ‘downstream mechanism’

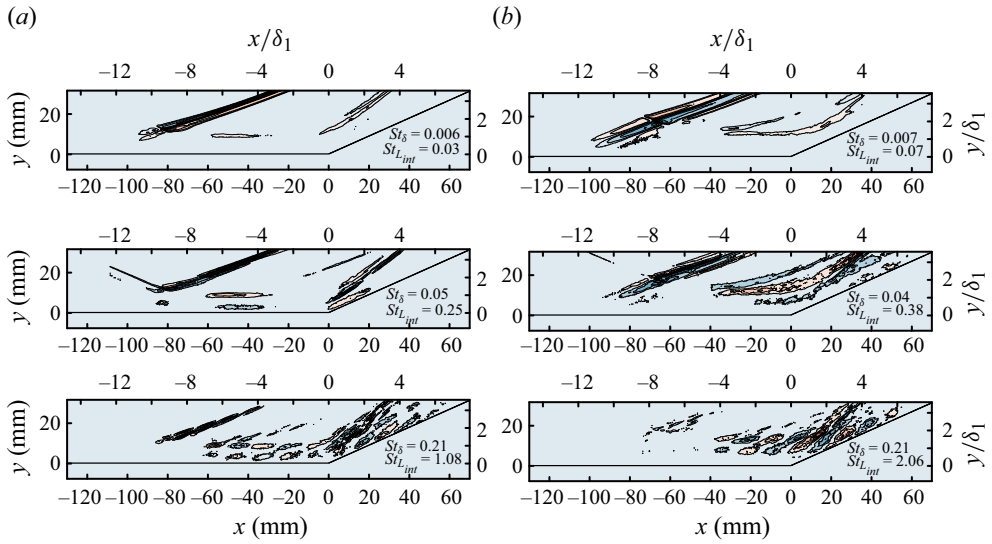


Figure 17. First SPOD mode of flow fluctuations obtained from schlieren image sequences in case B with (a) $d = 56$ mm, (b) $d = 25$ mm. The plots illustrate low-, medium- and high-frequency oscillations in the flow, arranged from top to bottom. All plots use the same contour set and spatial coordinates as those in