

MULTIPLICITY AND STABILITY OF NORMALIZED SOLUTIONS TO NON-AUTONOMOUS SCHRÖDINGER EQUATION WITH MIXED NON-LINEARITIES

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Abstract This paper first studies the multiplicity of normalized solutions to the non-autonomous Schrödinger equation with mixed nonlinearities

$$\begin{cases} -\Delta u = \lambda u + h(\epsilon x)|u|^{q-2}u + \eta|u|^{p-2}u, & x \in \mathbb{R}^N, \\ \int_{\mathbb{R}^N} |u|^2 dx = a^2, \end{cases}$$

where $a, \epsilon, \eta > 0$, q is L^2 -subcritical, p is L^2 -supercritical, $\lambda \in \mathbb{R}$ is an unknown parameter that appears as a Lagrange multiplier and h is a positive and continuous function. It is proved that the numbers of normalized solutions are at least the numbers of global maximum points of h when ϵ is small enough. The solutions obtained are local minimizers and probably not ground state solutions for the lack of symmetry of the potential h . Secondly, the stability of several different sets consisting of the local minimizers is analysed. Compared with the results of the corresponding autonomous equation, the appearance of the potential h increases the number of the local minimizers and the number of the stable sets. In particular, our results cover the Sobolev critical case $p = 2N/(N - 2)$.

Keywords: normalized solutions; multiplicity; stability; non-autonomous Sobolev critical Schrödinger equation; variational methods

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1. Introduction and main results

In this paper, we study the multiplicity and stability of normalized solutions to the non-autonomous Schrödinger equation with mixed nonlinearities:

$$\begin{cases} -\Delta u = \lambda u + h(\epsilon x)|u|^{q-2}u + \eta|u|^{p-2}u, & x \in \mathbb{R}^N, \\ \int_{\mathbb{R}^N} |u|^2 dx = a^2, \end{cases} \quad (1.1)$$

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where $N \geq 1, a, \epsilon, \eta > 0, 2 < q < 2 + \frac{4}{N} < p$ $\begin{cases} < +\infty, & N = 1, 2, \\ \leq 2^* := \frac{2N}{N-2}, & N \geq 3, \end{cases}$ and $\lambda \in \mathbb{R}$ is an unknown parameter that appears as a Lagrange multiplier. The function h satisfies the following conditions:

- (h₁) $h \in C(\mathbb{R}^N, \mathbb{R})$ and $0 < h_0 = \inf_{x \in \mathbb{R}^N} h(x) \leq \max_{x \in \mathbb{R}^N} h(x) = h_{\max}$;
- (h₂) $h_\infty = \lim_{|x| \rightarrow +\infty} h(x) < h_{\max}$;
- (h₃) $h^{-1}(h_{\max}) = \{a_1, a_2, \dots, a_l\}$ with $a_1 = 0$ and $a_j \neq a_i$, if $i \neq j$.

A solution u to the problem (1.1) corresponds to a critical point of the functional:

$$E_\epsilon(u) := \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u|^2 dx - \frac{1}{q} \int_{\mathbb{R}^N} h(\epsilon x) |u|^q dx - \frac{\eta}{p} \int_{\mathbb{R}^N} |u|^p dx, \tag{1.2}$$

restricted to the sphere:

$$S(a) := \{u \in H^1(\mathbb{R}^N) : \int_{\mathbb{R}^N} |u|^2 dx = a^2\}.$$

It is well known that $E_\epsilon \in C^1(H^1(\mathbb{R}^N), \mathbb{R})$ and

$$E'_\epsilon(u)\varphi = \int_{\mathbb{R}^N} \nabla u \nabla \varphi dx - \int_{\mathbb{R}^N} h(\epsilon x) |u|^{q-2} u \varphi dx - \eta \int_{\mathbb{R}^N} |u|^{p-2} u \varphi dx,$$

for any $\varphi \in H^1(\mathbb{R}^N)$.

One motivation driving the search for normalized solutions to Equation (1.1) is the nonlinear Schrödinger equation:

$$i \frac{\partial \psi}{\partial t} + \Delta \psi + g(|\psi|^2)\psi = 0, \quad (t, x) \in \mathbb{R} \times \mathbb{R}^N. \tag{1.3}$$

Searching for standing wave solution $\psi(t, x) = e^{-i\lambda t} u(x)$ of Equation (1.3) leads to Equation (1.1) for u if $g(|s|^2)s = h(\epsilon x)|s|^{q-2}s + \eta|s|^{p-2}s$. Since the mass $\int_{\mathbb{R}^N} |\psi|^2 dx$ is preserved along the flow associated with (1.3), it is natural to consider the L^2 -norm of u as prescribed. Moreover, the variational characterization of normalized solutions is often a strong help to analyse their orbital stability, see [7, 10, 33, 34] and the references therein.

In the study of normalized solutions to the Schrödinger equation:

$$-\Delta u = \lambda u + |u|^{p-2}u, \quad x \in \mathbb{R}^N, \tag{1.4}$$

the number $\bar{p} := 2 + 4/N$, labelled L^2 -critical exponent, is a very important number, because in the study of Equation (1.4) using variational methods, the functional

$$J(u) := \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u|^2 dx - \frac{1}{p} \int_{\mathbb{R}^N} |u|^p dx, \quad u \in H^1(\mathbb{R}^N),$$

is bounded from below on $S(a)$ for the L^2 -subcritical problem, i.e., $2 < p < 2 + 4/N$. Thus, a solution of Equation (1.4) can be found as a global minimizer of $J|_{S(a)}$,

see [32, 36]. While for the L^2 -supercritical problem, i.e., $2 + 4/N < p < 2^*$, $J|_{S(a)}$ is unbounded from below (and from above). Related to this case, a seminal paper due to Jeanjean [17] exploited the mountain pass geometry to get a normalized solution, see [3, 4, 8, 14, 16, 20, 21] for more results about problems with unbounded functional. In the purely L^2 -critical case (i.e., $p = 2 + 4/N$), the result is delicate. Recently, Soave [33, 34] considered the Schrödinger equation with double power form nonlinearity:

$$-\Delta u = \lambda u + \mu|u|^{q-2}u + |u|^{p-2}u, \quad x \in \mathbb{R}^N. \tag{1.5}$$

Under different ranges of p and q , they investigated the geometric characteristics of the functional corresponding to Equation (1.5) and studied the existence, multiplicity, orbital stability and instability of the normalized solutions, see [2, 18, 19, 23, 35, 39] for more results. The multiplicity of normalized solutions to the autonomous Schrödinger equation or systems has also been considered extensively at the last years, see [2, 3, 5, 12, 14, 16, 19–21, 27, 28].

As to the non-autonomous Schrödinger equation:

$$-\Delta u + V(x)u = \lambda u + f(u), \quad x \in \mathbb{R}^N, \tag{1.6}$$

under different assumptions on V and f , the existence of normalized solutions to (1.6) has been studied by many researchers. Ikoma and Miyamoto [15] and Zhong and Zou [43] considered Equation (1.6) with general L^2 -subcritical nonlinearities by applying the standard concentration compactness arguments, see also [24, 30, 37] for results to Equation (1.6) with special L^2 -subcritical nonlinearities $f(u) = |u|^{p-2}u$. See [25, 30] for results to Equation (1.6) with special L^2 -critical nonlinearities, [6, 29, 30, 37] for results to Equation (1.6) with special L^2 -supercritical nonlinearities, and [11] for results to Equation (1.6) with general L^2 -supercritical nonlinearities. In addition, the orbital stability of the set consisting of the normalized ground state solutions to Equation (1.6) was studied [6, 15]. There are relatively few studies about the mixed problem:

$$-\Delta u + V(x)u = \lambda u + \mu|u|^{q-2}u + |u|^{p-2}u, \quad x \in \mathbb{R}^N. \tag{1.7}$$

Li and Zhao [24] studied the existence and orbital stability of normalized ground state solutions to Equation (1.7) for q is L^2 -subcritical and p is L^2 -critical. When $p = \frac{2N}{N-2}$, Kang and Tang [22] studied the existence of normalized ground state solutions to Equation (1.7) in each of these cases $2 < p < 2 + \frac{4}{N}$, $p = 2 + \frac{4}{N}$ and $2 + \frac{4}{N} < p < \frac{2N}{N-2}$. Moreover, the strong instability of such solutions was also studied for the case $2 + \frac{4}{N} \leq p < \frac{2N}{N-2}$. As to the studies about the multiplicity of normalized solutions to the non-autonomous Schrödinger equation, Yang et al. [42] studied Equation (1.6) with f being L^2 -subcritical and satisfying Berestycki–Lions type conditions. Alves [1] considered the multiplicity of normalized solutions to

$$-\Delta u = \lambda u + h(\epsilon x)f(u), \quad x \in \mathbb{R}^N, \tag{1.8}$$

with f being L^2 -subcritical. As far as we know, there are no studies about multiplicity of normalized solutions to non-autonomous Schrödinger equation with mixed nonlinearities.

In this paper, motivated by [1], we study the multiplicity of normalized solutions to Equation (1.1).

To state the main results, let us first introduce some necessary notations. For $r \geq 1$, the L^r -norm of $u \in L^r(\mathbb{R}^N)$ is denoted by $\|u\|_r$. For every $N \geq 3$, there exists an optimal constant $S > 0$ depending only on N such that

$$S\|u\|_2^{2^*} \leq \|\nabla u\|_2^2, \quad \forall u \in D^{1,2}(\mathbb{R}^N), \quad (\text{Sobolev inequality}), \quad (1.9)$$

where $D^{1,2}(\mathbb{R}^N)$ denotes the completion of $C_c^\infty(\mathbb{R}^N)$ with respect to the norm $\|u\|_{D^{1,2}} := \|\nabla u\|_2$. Let

$$2 < t < \begin{cases} \infty, & N = 1, 2, \\ 2^*, & N \geq 3 \end{cases} \quad \text{and} \quad \gamma_t := \frac{N}{2} - \frac{N}{t}.$$

The Gagliardo–Nirenberg inequality (see [40]) says that there exists an optimal constant $C_{N,t} > 0$ depending on N and t such that

$$\|u\|_t \leq C_{N,t} \|u\|_2^{1-\gamma_t} \|\nabla u\|_2^{\gamma_t}, \quad \forall u \in H^1(\mathbb{R}^N). \quad (1.10)$$

Note that if we let $C_{N,2^*} := S^{-\frac{1}{2}}$, then (1.9) and (1.10) can be written in a unified form:

$$\|u\|_t \leq C_{N,t} \|u\|_2^{1-\gamma_t} \|\nabla u\|_2^{\gamma_t}, \quad 2 < t \begin{cases} < \infty, & N = 1, 2, \\ \leq 2^*, & N \geq 3. \end{cases} \quad (1.11)$$

Let p and q be as in Equation (1.1) and set

$$B := \frac{p\gamma_p - q\gamma_q}{2 - q\gamma_q} \left(\frac{2 - q\gamma_q}{p\gamma_p - 2} \right)^{\frac{p\gamma_p - 2}{p\gamma_p - q\gamma_q}} \left(\frac{C_{N,q}^q}{q} \right)^{\frac{p\gamma_p - 2}{p\gamma_p - q\gamma_q}} \left(\frac{C_{N,p}^p}{p} \right)^{\frac{2 - q\gamma_q}{p\gamma_p - q\gamma_q}}. \quad (1.12)$$

We make the following assumptions on h_{max} , η and a :

$$\left(h_{max} a^{q(1-\gamma_q)} \right)^{\frac{p\gamma_p - 2}{p\gamma_p - q\gamma_q}} \left(\eta a^{p(1-\gamma_p)} \right)^{\frac{2 - q\gamma_q}{p\gamma_p - q\gamma_q}} < \frac{1}{2B}, \quad (1.13)$$

and

$$\begin{aligned} & \left(h_{max} a^{q(1-\gamma_q)} \right)^{\frac{1}{p\gamma_p - q\gamma_q}} \eta^{\frac{N-2}{4} - \frac{1}{p\gamma_p - q\gamma_q}} \\ & \leq \left(\frac{(2 - q\gamma_q) C_{N,q}^q 2^* S^{\frac{2^*}{2}}}{q(p-2)} \right)^{\frac{-1}{p\gamma_p - q\gamma_q}} S^{\frac{N}{4}}. \end{aligned} \quad (1.14)$$

The multiplicity result of this paper is as follows.

Theorem 1.1. *Let $N, \epsilon, a, \eta, p, q, h$ be as in Equation (1.1), h_{max}, a and η satisfy condition (1.13). If $p = 2^*$, we further assume that Equation (1.14) holds. Then, there exists $\epsilon_0 > 0$ such that Equation (1.1) admits at least l couples $(u_j, \lambda_j) \in H^1(\mathbb{R}^N) \times \mathbb{R}$ of weak solutions for $\epsilon \in (0, \epsilon_0)$ with $\int_{\mathbb{R}^N} |u_j|^2 dx = a^2$, $\lambda_j < 0$ and $E_\epsilon(u_j) < 0$ for $j = 1, 2, \dots, l$.*

Remark 1.2. We make some notes on conditions (1.13) and (1.14):

(1) In studying the normalized solutions to the autonomous Schrödinger equation (1.5) with mixed nonlinearities $q < 2 + \frac{4}{N} < p$, the first step is to study the lower bound function of the functional to the problem (1.5) and then assume the maximum of the lower bound function is positive, see [18, 33, 34] for more details. In our non-autonomous problem (1.1), we also obtain a lower bound function $g_a(r)$ for the functional $E_\epsilon(u)$ and the condition (1.13) is added just to guarantee the maximum of $g_a(r)$ is positive (see §2) so that we can truncate the functional $E_\epsilon(u)$ and obtain the local minimizer of the functional with negative energy. So in some sense, the condition (1.13) is very weak.

(2) When $p = 2^*$, the condition (1.14) is added for technical reasons in order to obtain the PS condition for the truncated functional $E_{\epsilon,T}(u)$ (see Lemmas 4.4) and it can be weakened if we can give the explicit expression of R_0 (see Lemma 4.4).

To prove Theorem 1.1, we follow the arguments of [1] (see also [9]). In [1], multiple solutions to the problem (1.8) are perturbed from the global minimizer of the functional $\tilde{J}|_{S(a)}$ corresponding to the limit problem:

$$-\Delta u = \lambda u + \mu f(u), \quad x \in \mathbb{R}^N. \tag{1.15}$$

There the arguments depend on the existence of a global minimizer and the relative compactness of any minimizing sequence of the functional $\tilde{J}|_{S(a)}$. While in our problem (1.1), the appearance of the L^2 -supercritical term $\eta|u|^{p-2}u$ implies that the functional to the limit problem:

$$-\Delta u = \lambda u + \mu|u|^{q-2}u + \eta|u|^{p-2}u, \quad x \in \mathbb{R}^N, \tag{1.16}$$

with $q < 2 + 4/N < p$ is unbounded from below (and from above). In view of the studies of [18, 33], we know that the functional in this case has a local minimizer. So we try to perturb multiple solutions to Equation (1.1) from the local minimizer of the limit problem (1.16). If we restrict the limit functional to a bounded region to obtain the local minimizer as did in articles [18, 33], we cannot obtain the connection of the functional to Equation (1.1) and the limit functional to Equation (1.16) for the appearance of the potential. To avoid this difficulty, we employ the truncated skill used in [2, 31], and then we can isolate the local minimizer and finally obtain the multiplicity of normalized solutions to the problem (1.1). The application of truncated functions and the appearance of the Sobolev critical exponent $p = 2^*$ make the analysis challenging. In [2], the authors studied the multiplicity of normalized solutions to the autonomous Schrödinger equation (1.16) with $q < 2 + 4/N < p = 2^*$ in the radially symmetric space $H_{rad}^1(\mathbb{R}^N)$ by using truncated skill and genus theory. Note that our problem (1.1) is non-autonomous and not radially symmetric, so their method does not work in our problem.

We also consider the stability of the solutions obtained in Theorem 1.1. For this aim, we give the definition of stability.

Definition 1.3. A set $\Omega \subset H^1(\mathbb{R}^N)$ is stable under the flow associated with the problem:

$$\begin{cases} i\frac{\partial\psi}{\partial t} + \Delta\psi + h(\epsilon x)|\psi|^{q-2}\psi + \eta|\psi|^{p-2}\psi = 0, & t > 0, x \in \mathbb{R}^N, \\ \psi(0, x) = u_0(x) \end{cases} \tag{1.17}$$

if for any $\theta > 0$ there exists $\gamma > 0$ such that for any $u_0 \in H^1(\mathbb{R}^N)$ satisfying

$$\text{dist}_{H^1(\mathbb{R}^N)}(u_0, \Omega) < \gamma,$$

the solution $\psi(t, \cdot)$ of problem (1.17) with $\psi(0, x) = u_0$ satisfies

$$\sup_{t \in \mathbb{R}^+} \text{dist}_{H^1(\mathbb{R}^N)}(\psi(t, \cdot), \Omega) < \theta.$$

Theorem 1.4. Let N, a, η, q, h and ϵ_0 be as in Theorem 1.1, $p < 2^*$, $\epsilon \in (0, \epsilon_0)$, (1.13) hold. Then, $\Omega_i (i = 1, \dots, l)$ is stable under the flow associated with the problem (1.17), where Ω_i is defined in Equation (5.1). Since the definition of Ω_i needs many notations used in the proof of Theorem 1.1 in § 2–4, so we do not give it here.

Theorem 1.5. Let N, a, η, q, h and ϵ_0 be as in Theorem 1.1, $p = 2^*$, $\epsilon \in (0, \epsilon_0)$, (1.13) and (1.14) hold. Further assume that $h(x) \in C^1(\mathbb{R}^N)$ and $h'(x) \in L^\infty(\mathbb{R}^N)$. Then, $\Omega_i (i = 1, \dots, l)$ is stable under the flow associated with the problem (1.17).

Remark 1.6. (1) The definition of the sets $\Omega_i (i = 1, \dots, l)$ seems so natural. They act like potential wells to attract solutions that start around them and guarantee the stability, see the proof of Theorem 1.4 in § 5 which is very interesting.

(2) In this paper, the solutions obtained in Theorem 1.1 are local minimizers and they are probably not ground state solutions, since the potential h does not have symmetry and thus these l different solutions probably have different energies. So in some sense, we obtain the stability of local minimizer set Ω_i , which is different from most of the existing results concerning the stability of ground state solutions set (see [18, 26, 33]). Moreover, by the definition of Ω_i , we know $\Omega_i \cap \Omega_j = \emptyset$ for $i \neq j$. So we obtain the stability of l different sets $\Omega_i (i = 1, \dots, l)$, which is very different from the existing results about the stability of the only one set of ground state solutions.

(3) For the limit problem (1.16) with $q < 2 + 4/N < p$, authors [18, 33] obtained a normalized local minimizer to (1.16) with negative energy which is also a ground state solution and the ground state solutions set is stable. In view of the results of this paper, it seems that the appearance of the potential h increases the numbers of the local minimizers and the numbers of the stable sets.

This paper is organized as follows. In § 2, we define the truncated functional used in the study. In § 3, we study the properties of the truncated autonomous functional. In § 4, we study the truncated non-autonomous problem and give the proof of Theorem 1.1. In § 5, we prove the stability results Theorem 1.4.

Notation: The usual norm of $u \in H^1(\mathbb{R}^N)$ is denoted by $\|u\|$. C, C_1, C_2, \dots denotes any positive constant, whose value is not relevant and maybe change from line to line. $o_n(1)$ denotes a real sequence with $o_n(1) \rightarrow 0$ as $n \rightarrow +\infty$. ‘ \rightarrow ’ denotes strong convergence and ‘ \rightharpoonup ’ denotes weak convergence. $B_r(x_0) := \{x \in \mathbb{R}^N : |x - x_0| < r\}$.

2. Truncated functionals

In the proof of Theorem 1.1, we will adapt for our case a truncated function found in Peral Alonso ([31], Chapter 2, Theorem 2.4.6).

In what follows, we will consider the functional E_ϵ given by Equation (1.2) restricted to $S(a)$. By the Sobolev inequality and the Gagliardo–Nirenberg inequality (1.11), we have

$$\begin{aligned} E_\epsilon(u) &\geq \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u|^2 \, dx - \frac{1}{q} h_{\max} \int_{\mathbb{R}^N} |u|^q \, dx - \frac{\eta}{p} \int_{\mathbb{R}^N} |u|^p \, dx \\ &\geq \frac{1}{2} \|\nabla u\|_2^2 - \frac{1}{q} h_{\max} C_{N,q}^q a^{q(1-\gamma q)} \|\nabla u\|_2^{q\gamma q} - \frac{\eta}{p} C_{N,p}^p a^{p(1-\gamma p)} \|\nabla u\|_2^{p\gamma p} \\ &= g_a(\|\nabla u\|_2), \end{aligned} \tag{2.1}$$

for any $u \in S(a)$, where

$$g_a(r) := \frac{1}{2} r^2 - \frac{1}{q} h_{\max} C_{N,q}^q a^{q(1-\gamma q)} r^{q\gamma q} - \frac{\eta}{p} C_{N,p}^p a^{p(1-\gamma p)} r^{p\gamma p}, \quad r > 0.$$

Set $g_a(r) = r^2 w_a(r)$ with

$$w_a(r) := \frac{1}{2} - \frac{1}{q} h_{\max} C_{N,q}^q a^{q(1-\gamma q)} r^{q\gamma q - 2} - \frac{\eta}{p} C_{N,p}^p a^{p(1-\gamma p)} r^{p\gamma p - 2}, \quad r > 0.$$

Now we study the properties of $w_a(r)$. Note that

$$t\gamma_t \begin{cases} < 2, & 2 < t < 2 + 4/N, \\ = 2, & t = 2 + 4/N, \\ > 2, & 2 + 4/N < t \leq 2^* \end{cases} \quad \text{and} \quad \gamma_{2^*} = 1.$$

It is obvious that $\lim_{r \rightarrow 0^+} w_a(r) = -\infty$ and $\lim_{r \rightarrow +\infty} w_a(r) = -\infty$. By direct calculations, we obtain that

$$w'_a(r) = -\frac{1}{q} h_{\max} C_{N,q}^q a^{q(1-\gamma q)} (q\gamma_q - 2) r^{q\gamma_q - 3} - \frac{\eta}{p} C_{N,p}^p a^{p(1-\gamma p)} (p\gamma_p - 2) r^{p\gamma_p - 3}.$$

Then, the equation $w'_a(r) = 0$ has a unique solution:

$$r_0 = \left(\frac{(2 - q\gamma_q) \frac{1}{q} h_{\max} C_{N,q}^q a^{q(1-\gamma q)}}{(p\gamma_p - 2) \frac{\eta}{p} C_{N,p}^p a^{p(1-\gamma p)}} \right)^{\frac{1}{p\gamma_p - q\gamma_q}}, \tag{2.2}$$

and the maximum of $w_a(r)$ is

$$w_a(r_0) = \frac{1}{2} - B \left(h_{\max} a^{q(1-\gamma q)} \right)^{\frac{p\gamma p - 2}{p\gamma p - q\gamma q}} \left(\eta a^{p(1-\gamma p)} \right)^{\frac{2 - q\gamma q}{p\gamma p - q\gamma q}},$$

where B is defined in Equation (1.12). Thus under the assumption (1.13), the maximum of $w_a(r)$ is positive and $w_a(r)$ has exactly two zeros $0 < R_0 < R_1 < \infty$, which are also the zeros of $g_a(r)$. It is obvious that $g_a(r)$ has the following properties:

$$\begin{cases} g_a(0) = g_a(R_0) = g_a(R_1) = 0; & g_a(r) < 0 \text{ for } r > 0 \text{ small;} \\ \lim_{r \rightarrow +\infty} g_a(r) = -\infty; & g_a(r) \text{ has exactly two critical points;} \\ r_1 \in (0, R_0) \text{ and } r_2 \in (R_0, R_1) & \text{with } g_a(r_1) < 0 \text{ and } g_a(r_2) > 0. \end{cases} \tag{2.3}$$

Now fix $\tau : (0, +\infty) \rightarrow [0, 1]$ as being a non-increasing and C^∞ function that satisfies:

$$\tau(x) = \begin{cases} 1, & \text{if } x \leq R_0 \\ 0, & \text{if } x \geq R_1 \end{cases}, \tag{2.4}$$

and consider the truncated functional:

$$E_{\epsilon, T}(u) := \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u|^2 \, dx - \frac{1}{q} \int_{\mathbb{R}^N} h(\epsilon x) |u|^q \, dx - \frac{\eta}{p} \tau(\|\nabla u\|_2) \int_{\mathbb{R}^N} |u|^p \, dx. \tag{2.5}$$

Thus,

$$\begin{aligned} E_{\epsilon, T}(u) &\geq \frac{1}{2} \|\nabla u\|_2^2 - \frac{1}{q} h_{\max} C_{N, q}^q a^{q(1-\gamma q)} \|\nabla u\|_2^{q\gamma q} \\ &\quad - \frac{\eta}{p} \tau(\|\nabla u\|_2) C_{N, p}^p a^{p(1-\gamma p)} \|\nabla u\|_2^{p\gamma p} \\ &= \bar{g}_a(\|\nabla u\|_2), \end{aligned} \tag{2.6}$$

for any $u \in S(a)$, where

$$\bar{g}_a(r) := \frac{1}{2} r^2 - \frac{1}{q} h_{\max} C_{N, q}^q a^{q(1-\gamma q)} r^{q\gamma q} - \frac{\eta}{p} \tau(r) C_{N, p}^p a^{p(1-\gamma p)} r^{p\gamma p}.$$

It is easy to see that $\bar{g}_a(r)$ has the following properties:

$$\begin{cases} \bar{g}_a(r) \equiv g_a(r) \text{ for all } r \in [0, R_0]; \\ \bar{g}_a(r) \text{ is positive and strictly increasing in } (R_0, +\infty). \end{cases} \tag{2.7}$$

Correspondingly, for any $\mu \in (0, h_{\max}]$, we denote by $J_\mu, J_{\mu,T} : H^1(\mathbb{R}^N) \rightarrow \mathbb{R}$ the following functionals:

$$J_\mu(u) := \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u|^2 \, dx - \frac{\mu}{q} \int_{\mathbb{R}^N} |u|^q \, dx - \frac{\eta}{p} \int_{\mathbb{R}^N} |u|^p \, dx \tag{2.8}$$

and

$$J_{\mu,T}(u) := \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u|^2 \, dx - \frac{\mu}{q} \int_{\mathbb{R}^N} |u|^q \, dx - \frac{\eta}{p} \tau(\|\nabla u\|_2) \int_{\mathbb{R}^N} |u|^p \, dx. \tag{2.9}$$

The properties of $J_{\mu,T}$ and $E_{\epsilon,T}$ will be studied in § 3 and 4, respectively.

3. The truncated autonomous functional

In this section, we study the properties of the functional $J_{\mu,T}$ defined in Equation (2.9) restricted to $S(a_1)$, where $\mu \in (0, h_{\max}]$ and $a_1 \in (0, a]$.

Lemma 3.1. *Let N, a, η, p and q be as in Equations (1.1) and (1.13) hold, $\mu \in (0, h_{\max}]$, $0 < a_1 \leq a$. Then the functional $J_{\mu,T}$ is bounded from below on $S(a_1)$.*

Proof. By Equations (2.6) and (2.7), for any $u \in S(a_1)$,

$$\begin{aligned} J_{\mu,T}(u) &\geq J_{\max,T}(u) \\ &\geq \frac{1}{2} \|\nabla u\|_2^2 - \frac{1}{q} h_{\max} C_{N,q}^q a_1^{q(1-\gamma q)} \|\nabla u\|_2^{q\gamma q} \\ &\quad - \frac{\eta}{p} \tau(\|\nabla u\|_2) C_{N,p}^p a_1^{p(1-\gamma p)} \|\nabla u\|_2^{p\gamma p} \\ &\geq \bar{g}_a(\|\nabla u\|_2) \geq \inf_{r \geq 0} \bar{g}_a(r) > -\infty. \end{aligned}$$

The proof is complete. □

Lemma 3.2. *Let N, a, η, p, q be as in Equations (1.1) and (1.13) hold, $\mu \in (0, h_{\max}]$, $0 < a_1 \leq a$. $\Upsilon_{\mu,T,a_1} := \inf_{u \in S(a_1)} J_{\mu,T}(u) < 0$.*

Proof. Fix $u \in S(a_1)$. For $t > 0$, we define $u_t(x) = t^{\frac{N}{2}} u(tx)$. Then, $u_t \in S(a_1)$ for all $t > 0$. By $\tau \geq 0$ and $q\gamma q < 2$, we obtain that

$$\begin{aligned} J_{\mu,T}(u_t) &\leq \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u_t|^2 \, dx - \frac{\mu}{q} \int_{\mathbb{R}^N} |u_t|^q \, dx \\ &= \frac{1}{2} t^2 \int_{\mathbb{R}^N} |\nabla u|^2 \, dx - \frac{\mu}{q} t^{q\gamma q} \int_{\mathbb{R}^N} |u|^q \, dx, \\ &< 0 \end{aligned}$$

for $t > 0$ small enough. Thus, $\Upsilon_{\mu,T,a_1} < 0$. The proof is complete. □

Lemma 3.3. *Let N, a, η, p and q be as in Equations (1.1) and (1.13) hold, $\mu \in (0, h_{max}]$. Then*

- (1) $J_{\mu, T} \in C^1(H^1(\mathbb{R}^N), \mathbb{R})$;
- (2) *Let $a_1 \in (0, a]$. If $u \in S(a_1)$ such that $J_{\mu, T}(u) < 0$, then $\|\nabla u\|_2 < R_0$ and $J_{\mu, T}(v) = J_\mu(v)$ for all v satisfying $\|v\|_2 \leq a$ and being in a small neighborhood of u in $H^1(\mathbb{R}^N)$.*

Proof. (1) is trivial. Now we prove (2). It follows from $J_{\mu, T}(u) < 0$ and

$$J_{\mu, T}(u) \geq \bar{g}_{a_1}(\|\nabla u\|_2) \geq \bar{g}_a(\|\nabla u\|_2),$$

that $\bar{g}_a(\|\nabla u\|_2) < 0$, which implies that $\|\nabla u\|_2 < R_0$ by (2.7). By (1) and $J_{\mu, T}(u) < 0$, we obtain that $J_{\mu, T}(v) < 0$ for all v in a small neighborhood of u in $H^1(\mathbb{R}^N)$, which combined with $\|v\|_2 \leq a$ gives that $\|\nabla v\|_2 < R_0$ and thus $J_{\mu, T}(v) = J_\mu(v)$. The proof is complete. □

For any $a_1 \in (0, a]$, we define

$$m_\mu(a_1) := \inf_{u \in V(a_1)} J_\mu(u), \quad V(a_1) := \{u \in S(a_1) : \|\nabla u\|_2 < R_0\}.$$

Since $J_{\mu, T}(u) \geq \bar{g}_{a_1}(\|\nabla u\|_2) \geq \bar{g}_a(\|\nabla u\|_2)$ for any $u \in S(a_1)$, by Lemma 3.1, we obtain that

$$\Upsilon_{\mu, T, a_1} = \inf_{u \in S(a_1)} J_{\mu, T}(u) = m_\mu(a_1). \tag{3.1}$$

In ([18], Lemma 2.6 and Theorem 1.2), the authors obtained that

Lemma 3.4. *Let N, a, η, p and q be as in Equations (1.1) and (1.13) hold, $\mu \in (0, h_{max}]$. Then*

- (1) $a_1 \in (0, a] \mapsto m_\mu(a_1)$ is continuous;
- (2) *Let $0 < a_1 < a_2 \leq a$, then $\frac{a_1^2}{a_2} m_\mu(a_2) < m_\mu(a_1) < 0$.*

Consequently, by Equation (3.1) and Lemma 3.4, we obtain that

Lemma 3.5. *Let N, a, η, p and q be as in Equations (1.1) and (1.13) hold, $\mu \in (0, h_{max}]$. Then*

- (1) $a_1 \in (0, a] \mapsto \Upsilon_{\mu, T, a_1}$ is continuous;
- (2) *Let $0 < a_1 < a_2 \leq a$, then $\frac{a_1^2}{a_2} \Upsilon_{\mu, T, a_2} < \Upsilon_{\mu, T, a_1} < 0$.*

The next compactness lemma is useful in the study of the autonomous problem as well as in the non-autonomous problem.

Lemma 3.6. *Let N, a, η, p and q be as in Equations (1.1) and (1.13) hold, $\mu \in (0, h_{max}]$, $a_1 \in (0, a]$. $\{u_n\} \subset S(a_1)$ be a minimizing sequence with respect to Υ_{μ, T, a_1} . Then, for some subsequence, either*

(i) $\{u_n\}$ is strongly convergent,

or

(ii) There exists $\{y_n\} \subset \mathbb{R}^N$ with $|y_n| \rightarrow \infty$ such that the sequence $v_n(x) = u_n(x + y_n)$ is strongly convergent to a function $v \in S(a_1)$ with $J_{\mu,T}(v) = \Upsilon_{\mu,T,a_1}$.

Proof. Noting that $\|\nabla u_n\|_2 < R_0$ for n large enough, there exists $u \in H^1(\mathbb{R}^N)$ such that $u_n \rightharpoonup u$ in $H^1(\mathbb{R}^N)$ up to a subsequence. Now we consider the following three possibilities.

(1) If $u \neq 0$ and $\|u\|_2 = b \neq a_1$, we must have $b \in (0, a_1)$. Setting $v_n = u_n - u$, $d_n = \|v_n\|_2$, and by using

$$\|u_n\|_2^2 = \|v_n\|_2^2 + \|u\|_2^2 + o_n(1),$$

we obtain that $\|v_n\|_2 \rightarrow d$, where $a_1^2 = d^2 + b^2$. Noting that $d_n \in (0, a_1)$ for n large enough, and using the Brézis–Lieb Lemma (see [41]), Lemma 3.5, $\|\nabla u_n\|_2^2 = \|\nabla u\|_2^2 + \|\nabla v_n\|_2^2 + o_n(1)$, $\|\nabla u\|_2^2 \leq \liminf_{n \rightarrow +\infty} \|\nabla u_n\|_2^2$, τ is continuous and non-increasing, we obtain that

$$\begin{aligned} \Upsilon_{\mu,T,a_1} + o_n(1) &= J_{\mu,T}(u_n) = \frac{1}{2} \|\nabla v_n\|_2^2 - \frac{\mu}{q} \|v_n\|_q^q - \frac{\eta}{p} \tau(\|\nabla u_n\|_2) \|v_n\|_p^p \\ &\quad + \frac{1}{2} \|\nabla u\|_2^2 - \frac{\mu}{q} \|u\|_q^q - \frac{\eta}{p} \tau(\|\nabla u_n\|_2) \|u\|_p^p + o_n(1) \\ &\geq J_{\mu,T}(v_n) + J_{\mu,T}(u) + o_n(1) \\ &\geq \Upsilon_{\mu,T,d_n} + \Upsilon_{\mu,T,b} + o_n(1) \\ &\geq \frac{d^2}{a_1^2} \Upsilon_{\mu,T,a_1} + \Upsilon_{\mu,T,b} + o_n(1). \end{aligned}$$

Letting $n \rightarrow +\infty$, we find that

$$\begin{aligned} \Upsilon_{\mu,T,a_1} &\geq \frac{d^2}{a_1^2} \Upsilon_{\mu,T,a_1} + \Upsilon_{\mu,T,b} \\ &> \frac{d^2}{a_1^2} \Upsilon_{\mu,T,a_1} + \frac{b^2}{a_1^2} \Upsilon_{\mu,T,a_1} = \Upsilon_{\mu,T,a_1}, \end{aligned}$$

which is a contradiction. So this possibility can not exist.

(2) If $\|u\|_2 = a_1$, then $u_n \rightarrow u$ in $L^2(\mathbb{R}^N)$ and thus $u_n \rightarrow u$ in $L^t(\mathbb{R}^N)$ for all $t \in (2, 2^*)$.

Case $p < 2^*$, then

$$\begin{aligned} \Upsilon_{\mu,T,a_1} &= \lim_{n \rightarrow +\infty} J_{\mu,T}(u_n) \\ &= \lim_{n \rightarrow +\infty} \left(\frac{1}{2} \|\nabla u_n\|_2^2 - \frac{\mu}{q} \|u_n\|_q^q - \frac{\eta}{p} \tau(\|\nabla u_n\|_2) \|u_n\|_p^p \right) \\ &\geq J_{\mu,T}(u). \end{aligned}$$

As $u \in S(a_1)$, we infer that $J_{\mu,T}(u) = \Upsilon_{\mu,T,a_1}$, then $\|\nabla u_n\|_2 \rightarrow \|\nabla u\|_2$ and thus $u_n \rightarrow u$ in $H^1(\mathbb{R}^N)$, which implies that (i) occurs.

Case $p = 2^*$, noting that $\|\nabla v_n\|_2 \leq \|\nabla u_n\|_2 < R_0$ for n large enough, and using the Sobolev inequality, we have

$$\begin{aligned}
 J_{\mu,T}(v_n) = J_\mu(v_n) &= \frac{1}{2} \int_{\mathbb{R}^N} |\nabla v_n|^2 \, dx - \frac{\mu}{q} \int_{\mathbb{R}^N} |v_n|^q \, dx - \frac{\eta}{p} \int_{\mathbb{R}^N} |v_n|^p \, dx \\
 &\geq \frac{1}{2} \|\nabla v_n\|_2^2 - \frac{\eta}{2^*} \frac{1}{S^{\frac{2^*}{2}}} \|\nabla v_n\|_2^{2^*} + o_n(1) \\
 &= \|\nabla v_n\|_2^2 \left(\frac{1}{2} - \frac{\eta}{2^*} \frac{1}{S^{\frac{2^*}{2}}} \|\nabla v_n\|_2^{2^*-2} \right) + o_n(1) \tag{3.2} \\
 &\geq \|\nabla v_n\|_2^2 \left(\frac{1}{2} - \frac{\eta}{2^*} \frac{1}{S^{\frac{2^*}{2}}} R_0^{2^*-2} \right) + o_n(1) \\
 &= \|\nabla v_n\|_2^2 \frac{1}{q} h_{\max} C_{N,q}^q a^{q(1-\gamma q)} R_0^{q\gamma q-2} + o_n(1),
 \end{aligned}$$

because $w_a(R_0) = \frac{1}{2} - \frac{\eta}{2^*} \frac{1}{S^{\frac{2^*}{2}}} R_0^{2^*-2} - \frac{1}{q} h_{\max} C_{N,q}^q a^{q(1-\gamma q)} R_0^{q\gamma q-2} = 0$. Now we remember that

$$\Upsilon_{\mu,T,a_1} \leftarrow J_{\mu,T}(u_n) \geq J_{\mu,T}(v_n) + J_{\mu,T}(u) + o_n(1). \tag{3.3}$$

Since $u \in S(a_1)$, we have $J_{\mu,T}(u) \geq \Upsilon_{\mu,T,a_1}$, which combined with Equations (3.2) and (3.3) gives that $\|\nabla v_n\|_2^2 \rightarrow 0$ and then $u_n \rightarrow u$ in $H^1(\mathbb{R}^N)$. This implies that (i) occurs.

(3) If $u \equiv 0$, that is, $u_n \rightarrow 0$ in $H^1(\mathbb{R}^N)$. We claim that there exist $R, \beta > 0$ and $\{y_n\} \subset \mathbb{R}^N$ such that

$$\int_{B_R(y_n)} |u_n|^2 \, dx \geq \beta, \quad \text{for all } n. \tag{3.4}$$

Indeed, otherwise we must have $u_n \rightarrow 0$ in $L^t(\mathbb{R}^N)$ for all $t \in (2, 2^*)$. Thus, for $p < 2^*$, $J_{\mu,T}(u_n) \geq \frac{1}{2} \|\nabla u_n\|_2^2 + o_n(1)$, which contradicts $J_{\mu,T}(u_n) \rightarrow \Upsilon_{\mu,T,a_1} < 0$. For $p = 2^*$, similarly to (3.2), we obtain that

$$J_{\mu,T}(u_n) \geq \|\nabla u_n\|_2^2 \frac{1}{q} h_{\max} C_{N,q}^q a^{q(1-\gamma q)} R_0^{q\gamma q-2} + o_n(1).$$

We also get a contradiction in this case. Hence, in all cases, Equation (3.4) holds and $|y_n| \rightarrow +\infty$ obviously. From this, considering $\bar{u}_n(x) = u_n(x + y_n)$, clearly $\{\bar{u}_n\} \subset S(a_1)$ and it is also a minimizing sequence with respect to Υ_{μ,T,a_1} . Moreover, there exists $\bar{u} \in H^1(\mathbb{R}^N) \setminus \{0\}$ such that $\bar{u}_n \rightarrow \bar{u}$ in $H^1(\mathbb{R}^N)$. Following as in the first two possibilities of the proof, we derive that $\bar{u}_n \rightarrow \bar{u}$ in $H^1(\mathbb{R}^N)$, which implies that (ii) occurs. \square

Lemma 3.7. *Let N, a, η, p, q be as in Equation (1.1), $\mu \in (0, h_{max}]$, $a_1 \in (0, a]$, (1.13) hold. Then, Υ_{μ, T, a_1} is attained.*

Proof. By Lemma 3.1, there exists a bounded minimizing sequence $\{u_n\} \subset S(a_1)$ satisfying $J_{\mu, T}(u_n) \rightarrow \Upsilon_{\mu, T, a_1}$ as $n \rightarrow +\infty$. Now, applying Lemma 3.6, there exists $u \in S(a_1)$ such that $J_{\mu, T}(u) = \Upsilon_{\mu, T, a_1}$. The proof is complete. \square

An immediate consequence of Lemma 3.7 is the following corollary.

Corollary 3.8. *Let N, a, η, p and q be as in Equations (1.1) and (1.13) hold. Fix $a_1 \in (0, a]$ and let $0 < \mu_1 < \mu_2 \leq h_{max}$. Then, $\Upsilon_{\mu_2, T, a_1} < \Upsilon_{\mu_1, T, a_1}$.*

Proof. Let $u \in S(a_1)$ satisfy $J_{\mu_1, T}(u) = \Upsilon_{\mu_1, T, a_1}$. Then, $\Upsilon_{\mu_2, T, a_1} \leq J_{\mu_2, T}(u) < J_{\mu_1, T}(u) = \Upsilon_{\mu_1, T, a_1}$. \square

4. Proof of Theorem 1.1

In this section, we first prove some properties of the functional $E_{\epsilon, T}$ defined in Equation (2.5) restricted to the sphere $S(a)$, and then give the proof of Theorem 1.1.

Denote

$$J_{max, T} := J_{h_{max}, T}, \quad \Upsilon_{max, T, a} := \Upsilon_{h_{max}, T, a},$$

and

$$J_{\infty, T} := J_{h_{\infty}, T}, \quad \Upsilon_{\infty, T, a} := \Upsilon_{h_{\infty}, T, a}.$$

It is obvious that $J_{\infty, T}(u) \geq J_{max, T}(u)$ and $E_{\epsilon, T}(u) \geq J_{max, T}(u)$ for any $u \in S(a)$. By Lemma 3.1, the definition:

$$\Gamma_{\epsilon, T, a} := \inf_{u \in S(a)} E_{\epsilon, T}(u),$$

is well defined and $\Gamma_{\epsilon, T, a} \geq \Upsilon_{max, T, a}$.

The next lemma establishes some crucial relations involving the levels $\Gamma_{\epsilon, T, a}$, $\Upsilon_{\infty, T, a}$ and $\Upsilon_{max, T, a}$.

Lemma 4.1. *Let N, a, η, p, q, h and ϵ be as in Equations (1.1) and (1.13) hold. Then*

$$\limsup_{\epsilon \rightarrow 0^+} \Gamma_{\epsilon, T, a} \leq \Upsilon_{max, T, a} < \Upsilon_{\infty, T, a} < 0.$$

Proof. By Lemma 3.7, choose $u \in S(a)$ such that $J_{max, T}(u) = \Upsilon_{max, T, a}$. Then,

$$\begin{aligned} \Gamma_{\epsilon, T, a} \leq E_{\epsilon, T}(u) &= \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u|^2 \, dx - \frac{1}{q} \int_{\mathbb{R}^N} h(\epsilon x) |u|^q \, dx \\ &\quad - \frac{\eta}{p} \tau(\|\nabla u\|_2) \int_{\mathbb{R}^N} |u|^p \, dx. \end{aligned}$$

Letting $\epsilon \rightarrow 0^+$, by the Lebesgue dominated convergence theorem, we deduce that

$$\limsup_{\epsilon \rightarrow 0^+} \Gamma_{\epsilon,T,a} \leq \limsup_{\epsilon \rightarrow 0^+} E_{\epsilon,T}(u) = J_{h(0),T}(u) = J_{\max,T}(u) = \Upsilon_{\max,T,a},$$

which combined with Lemma 3.2 and Corollary 3.8 completes the proof. □

By Lemma 4.1, there exists $\epsilon_1 > 0$ such that $\Gamma_{\epsilon,T,a} < \Upsilon_{\infty,T,a}$ for all $\epsilon \in (0, \epsilon_1)$. In the following, we always assume that $\epsilon \in (0, \epsilon_1)$. Similarly to the proof of Lemma 3.3, we have the following result, whose proof is omitted.

Lemma 4.2. *Let $N, a, \eta, p, q, h, \epsilon$ be as in (1.1), $\epsilon \in (0, \epsilon_1)$, (1.13) hold. Then*

- (1) $E_{\epsilon,T} \in C^1(H^1(\mathbb{R}^N), \mathbb{R})$;
- (2) *If $u \in S(a)$ such that $E_{\epsilon,T}(u) < 0$, then $\|\nabla u\|_2 < R_0$ and $E_{\epsilon,T}(v) = E_\epsilon(v)$ for all v satisfying $\|v\|_2 \leq a$ and being in a small neighborhood of u in $H^1(\mathbb{R}^N)$.*

The next two lemmas will be used to prove the PS condition for $E_{\epsilon,T}$ restricted to $S(a)$ at some levels.

Lemma 4.3. *Let N, a, η, p, q, h be as in (1.1), $\epsilon \in (0, \epsilon_1)$, (1.13) hold. Assume $\{u_n\} \subset S(a)$ such that $E_{\epsilon,T}(u_n) \rightarrow c$ as $n \rightarrow +\infty$ with $c < \Upsilon_{\infty,T,a}$. If $u_n \rightharpoonup u$ in $H^1(\mathbb{R}^N)$, then $u \not\equiv 0$.*

Proof. Assume by contradiction that $u \equiv 0$. Then,

$$c + o_n(1) = E_{\epsilon,T}(u_n) = J_{\infty,T}(u_n) + \frac{1}{q} \int_{\mathbb{R}^N} (h_\infty - h(\epsilon x)) |u_n|^q dx.$$

By (h_2) , for any given $\delta > 0$, there exists $R > 0$ such that $h_\infty \geq h(x) - \delta$ for all $|x| \geq R$. Hence,

$$\begin{aligned} c + o_n(1) = E_{\epsilon,T}(u_n) &\geq J_{\infty,T}(u_n) + \frac{1}{q} \int_{B_{R/\epsilon}(0)} (h_\infty - h(\epsilon x)) |u_n|^q dx \\ &\quad - \frac{\delta}{q} \int_{B_{R/\epsilon}^c(0)} |u_n|^q dx. \end{aligned}$$

Recalling that $\{u_n\}$ is bounded in $H^1(\mathbb{R}^N)$ and $u_n \rightarrow 0$ in $L^t(B_{R/\epsilon}(0))$ for all $t \in [1, 2^*)$, it follows that

$$c + o_n(1) = E_{\epsilon,T}(u_n) \geq J_{\infty,T}(u_n) - \delta C + o_n(1),$$

for some $C > 0$. Since $\delta > 0$ is arbitrary, we deduce that $c \geq \Upsilon_{\infty,T,a}$, which is a contradiction. Thus, $u \not\equiv 0$. □

Lemma 4.4. *Let N, a, η, p, q and h be as in Equation (1.1), $\epsilon \in (0, \epsilon_1)$, Equation (1.13) hold. If $p = 2^*$, we further assume that Equation (1.14) holds. Let $\{u_n\}$ be a $(PS)_c$ sequence of $E_{\epsilon,T}$ restricted to $S(a)$ with $c < \Upsilon_{\infty,T,a}$ and let $u_n \rightharpoonup u_\epsilon$ in $H^1(\mathbb{R}^N)$. If u_n*

does not converge to u_ϵ strongly in $H^1(\mathbb{R}^N)$, there exists $\beta > 0$ independent of $\epsilon \in (0, \epsilon_1)$ such that

$$\limsup_{n \rightarrow +\infty} \|u_n - u_\epsilon\|_2 \geq \beta.$$

Proof. By Lemma 4.2, we must have $\|\nabla u_n\|_2 < R_0$ for n large enough, and so, $\{u_n\}$ is also a $(PS)_c$ sequence of E_ϵ restricted to $S(a)$. Hence,

$$E_\epsilon(u_n) \rightarrow c \quad \text{and} \quad \|E'_\epsilon|_{S(a)}(u_n)\| \rightarrow 0 \quad \text{as } n \rightarrow +\infty.$$

Setting the functional $\Psi : H^1(\mathbb{R}^N) \rightarrow \mathbb{R}$ given by:

$$\Psi(u) = \frac{1}{2} \int_{\mathbb{R}^N} |u|^2 \, dx,$$

it follows that $S(a) = \Psi^{-1}(a^2/2)$. Then, by Willem ([41], Proposition 5.12), there exists $\{\lambda_n\} \subset \mathbb{R}$ such that

$$\|E'_\epsilon(u_n) - \lambda_n \Psi'(u_n)\|_{H^{-1}(\mathbb{R}^N)} \rightarrow 0, \quad \text{as } n \rightarrow +\infty. \tag{4.1}$$

By the boundedness of $\{u_n\}$ in $H^1(\mathbb{R}^N)$, we know $\{\lambda_n\}$ is bounded and thus, up to a subsequence, there exists λ_ϵ such that $\lambda_n \rightarrow \lambda_\epsilon$ as $n \rightarrow +\infty$. This together with Equation (4.1) leads to

$$E'_\epsilon(u_\epsilon) - \lambda_\epsilon \Psi'(u_\epsilon) = 0, \quad \text{in } H^{-1}(\mathbb{R}^N), \tag{4.2}$$

and then

$$\|E'_\epsilon(v_n) - \lambda_\epsilon \Psi'(v_n)\|_{H^{-1}(\mathbb{R}^N)} \rightarrow 0, \quad \text{as } n \rightarrow +\infty, \tag{4.3}$$

where $v_n := u_n - u_\epsilon$. By direct calculations, we get that

$$\begin{aligned} \Upsilon_{\infty, T, a} &> \lim_{n \rightarrow +\infty} E_\epsilon(u_n) \\ &= \lim_{n \rightarrow +\infty} \left(E_\epsilon(u_n) - \frac{1}{2} E'_\epsilon(u_n) u_n + \frac{1}{2} \lambda_n \|u_n\|_2^2 + o_n(1) \right) \\ &= \lim_{n \rightarrow +\infty} \left[\left(\frac{1}{2} - \frac{1}{q} \right) \int_{\mathbb{R}^N} h(\epsilon x) |u_n|^q \, dx \right. \\ &\quad \left. + \left(\frac{1}{2} - \frac{1}{p} \right) \eta \int_{\mathbb{R}^N} |u_n|^p \, dx + \frac{1}{2} \lambda_n a^2 + o_n(1) \right] \\ &\geq \frac{1}{2} \lambda_\epsilon a^2, \end{aligned}$$

which implies that

$$\lambda_\epsilon \leq \frac{2\Upsilon_{\infty, T, a}}{a^2} < 0, \quad \text{for all } \epsilon \in (0, \epsilon_1). \tag{4.4}$$

By Equation (4.3), we know

$$\int_{\mathbb{R}^N} |\nabla v_n|^2 dx - \lambda_\epsilon \int_{\mathbb{R}^N} |v_n|^2 dx - \int_{\mathbb{R}^N} h(\epsilon x) |v_n|^q dx - \eta \int_{\mathbb{R}^N} |v_n|^p dx = o_n(1), \tag{4.5}$$

which combined with Equation (4.4) gives that

$$\begin{aligned} \int_{\mathbb{R}^N} |\nabla v_n|^2 dx - \frac{2\Upsilon_{\infty,T,a}}{a^2} \int_{\mathbb{R}^N} |v_n|^2 dx \\ \leq h_{\max} \int_{\mathbb{R}^N} |v_n|^q dx + \eta \int_{\mathbb{R}^N} |v_n|^p dx + o_n(1). \end{aligned} \tag{4.6}$$

If u_n does not converge to u_ϵ strongly in $H^1(\mathbb{R}^N)$, that is, v_n does not converge to 0 strongly in $H^1(\mathbb{R}^N)$, by (4.6) and the Sobolev inequality, we deduce that

$$\begin{aligned} \int_{\mathbb{R}^N} |\nabla v_n|^2 dx - \frac{2\Upsilon_{\infty,T,a}}{a^2} \int_{\mathbb{R}^N} |v_n|^2 dx \\ \leq h_{\max} C_{N,q}^q \|v_n\|^q + \eta C_{N,p}^p \|v_n\|^p + o_n(1). \end{aligned}$$

So there exists $C > 0$ independent of ϵ such that $\|v_n\| \geq C$ and then by Equation (4.6):

$$\limsup_{n \rightarrow +\infty} \left(h_{\max} \int_{\mathbb{R}^N} |v_n|^q dx + \eta \int_{\mathbb{R}^N} |v_n|^p dx \right) \geq C. \tag{4.7}$$

Case $p < 2^*$, by (4.7) and the Gagliardo–Nirenberg inequality (1.11), there exists $\beta > 0$ independent of $\epsilon \in (0, \epsilon_1)$ such that

$$\limsup_{n \rightarrow +\infty} \|v_n\|_2 \geq \beta. \tag{4.8}$$

Case $p = 2^*$, if

$$\limsup_{n \rightarrow +\infty} \int_{\mathbb{R}^N} |v_n|^q dx \geq C,$$

for some $C > 0$ independent of ϵ , we obtain (4.8) as well. If

$$\liminf_{\epsilon \rightarrow 0^+} \limsup_{n \rightarrow +\infty} \int_{\mathbb{R}^N} |v_n|^q dx = 0 \quad \text{and} \quad \liminf_{\epsilon \rightarrow 0^+} \limsup_{n \rightarrow +\infty} \|v_n\|_2 = 0,$$

by Equation (4.7) we have

$$\liminf_{\epsilon \rightarrow 0^+} \limsup_{n \rightarrow +\infty} \int_{\mathbb{R}^N} |v_n|^p dx \geq C,$$

and by Equation (4.5) we have

$$\liminf_{\epsilon \rightarrow 0^+} \limsup_{n \rightarrow +\infty} \int_{\mathbb{R}^N} |\nabla v_n|^2 dx = \liminf_{\epsilon \rightarrow 0^+} \limsup_{n \rightarrow +\infty} \eta \int_{\mathbb{R}^N} |v_n|^p dx.$$

Applying the Sobolev inequality to the above equality, we obtain that

$$\liminf_{\epsilon \rightarrow 0^+} \limsup_{n \rightarrow +\infty} \|\nabla v_n\|_2^2 = \liminf_{\epsilon \rightarrow 0^+} \limsup_{n \rightarrow +\infty} \eta \|v_n\|_{2^*}^{2^*} \leq \liminf_{\epsilon \rightarrow 0^+} \limsup_{n \rightarrow +\infty} \eta S^{-2^*/2} \|\nabla v_n\|_2^{2^*},$$

which implies that

$$R_0 \geq \liminf_{\epsilon \rightarrow 0^+} \limsup_{n \rightarrow +\infty} \|\nabla v_n\|_2 \geq \eta^{-\frac{N-2}{4}} S^{N/4}. \tag{4.9}$$

On the other hand, by the assumption (1.14), we have

$$R_0 < \eta^{-\frac{N-2}{4}} S^{N/4}. \tag{4.10}$$

Indeed, by the expression of r_0 in Equation (2.2), Equation (1.14) is equivalent to

$$r_0 < \eta^{-\frac{N-2}{4}} S^{\frac{N}{4}}. \tag{4.11}$$

Since $R_0 < r_0 < R_1$ (see §2), we obtain Equation (4.10), which contradicts Equation (4.9). So we must have Equation (4.8) for the case $p = 2^*$. The proof is complete. \square

Now, we give the compactness lemma.

Lemma 4.5. *Let N, a, η, p, q and h be as in Equation (1.1), $\epsilon \in (0, \epsilon_1)$, β be as in Lemma 4.4,*

$$0 < \rho_0 \leq \min \left\{ \Upsilon_{\infty, T, a} - \Upsilon_{max, T, a}, \frac{\beta^2}{a^2} (\Upsilon_{\infty, T, a} - \Upsilon_{max, T, a}) \right\},$$

and Equation (1.13) hold. If $p = 2^*$, we further assume that Equation (1.14) holds. Then, $E_{\epsilon, T}$ satisfies the $(PS)_c$ condition restricted to $S(a)$ if $c < \Upsilon_{max, T, a} + \rho_0$.

Proof. Let $\{u_n\} \subset S(a)$ be a $(PS)_c$ sequence of $E_{\epsilon, T}$ restricted to $S(a)$. Noting that $c < \Upsilon_{\infty, T, a} < 0$, by Lemma 4.2, $\{u_n\}$ is bounded in $H^1(\mathbb{R}^N)$. Let $u_n \rightharpoonup u_\epsilon$ in $H^1(\mathbb{R}^N)$. By Lemma 4.3, $u_\epsilon \not\equiv 0$. Set $v_n := u_n - u_\epsilon$. If $u_n \rightarrow u_\epsilon$ in $H^1(\mathbb{R}^N)$, the proof is complete.

If u_n does not converge to u_ϵ strongly in $H^1(\mathbb{R}^N)$ for some $\epsilon \in (0, \epsilon_1)$, by Lemma 4.4,

$$\limsup_{n \rightarrow +\infty} \|v_n\|_2 \geq \beta.$$

Set $b = \|u_\epsilon\|_2$, $d_n = \|v_n\|_2$ and suppose that $\|v_n\|_2 \rightarrow d$, then we get $d \geq \beta > 0$ and $a^2 = b^2 + d^2$. From $d_n \in (0, a)$ for n large enough, we have

$$c + o_n(1) = E_{\epsilon,T}(u_n) \geq E_{\epsilon,T}(v_n) + E_{\epsilon,T}(u_\epsilon) + o_n(1). \tag{4.12}$$

Since $v_n \rightharpoonup 0$ in $H^1(\mathbb{R}^N)$, similarly to the proof of Lemma 4.3, we deduce that

$$E_{\epsilon,T}(v_n) \geq J_{\infty,T}(v_n) - \delta C + o_n(1) \tag{4.13}$$

for any $\delta > 0$, where $C > 0$ is a constant independent of δ , ϵ and n . By (4.12) and (4.13), we obtain that

$$\begin{aligned} c + o_n(1) &= E_{\epsilon,T}(u_n) \geq J_{\infty,T}(v_n) + E_{\epsilon,T}(u_\epsilon) - \delta C + o_n(1) \\ &\geq \Upsilon_{\infty,T,d_n} + \Upsilon_{\max,T,b} - \delta C + o_n(1). \end{aligned}$$

Letting $n \rightarrow +\infty$, by Lemma 3.5 and the arbitrariness of $\delta > 0$, we obtain that

$$\begin{aligned} c &\geq \Upsilon_{\infty,T,d} + \Upsilon_{\max,T,b} \geq \frac{d^2}{a^2} \Upsilon_{\infty,T,a} + \frac{b^2}{a^2} \Upsilon_{\max,T,a} \\ &= \Upsilon_{\max,T,a} + \frac{d^2}{a^2} (\Upsilon_{\infty,T,a} - \Upsilon_{\max,T,a}) \\ &\geq \Upsilon_{\max,T,a} + \frac{\beta^2}{a^2} (\Upsilon_{\infty,T,a} - \Upsilon_{\max,T,a}), \end{aligned}$$

which contradicts $c < \Upsilon_{\max,T,a} + \frac{\beta^2}{a^2} (\Upsilon_{\infty,T,a} - \Upsilon_{\max,T,a})$. Thus, we must have $u_n \rightarrow u_\epsilon$ in $H^1(\mathbb{R}^N)$. □

In what follows, let us fix $\tilde{\rho}, \tilde{r} > 0$ satisfying:

- $\overline{B_{\tilde{\rho}}(a_i)} \cap \overline{B_{\tilde{\rho}}(a_j)} = \emptyset$ for $i \neq j$ and $i, j \in \{1, \dots, l\}$;
- $\cup_{i=1}^l B_{\tilde{\rho}}(a_i) \subset B_{\tilde{r}}(0)$;
- $K_{\frac{\tilde{\rho}}{2}} = \cup_{i=1}^l B_{\frac{\tilde{\rho}}{2}}(a_i)$.

We also set the function $Q_\epsilon : H^1(\mathbb{R}^N) \setminus \{0\} \rightarrow \mathbb{R}^N$ by

$$Q_\epsilon(u) := \frac{\int_{\mathbb{R}^N} \chi(\epsilon x) |u|^2 dx}{\int_{\mathbb{R}^N} |u|^2 dx},$$

where $\chi : \mathbb{R}^N \rightarrow \mathbb{R}^N$ is given by:

$$\chi(x) := \begin{cases} x, & \text{if } |x| \leq \tilde{r}, \\ \tilde{r} \frac{x}{|x|}, & \text{if } |x| > \tilde{r}. \end{cases}$$

The next two lemmas will be useful to get important *PS* sequences for $E_{\epsilon,T}$ restricted to $S(a)$.

Lemma 4.6. *Let N, a, η, p, q and h be as in Equations (1.1) and (1.13) hold. Then, there exist $\epsilon_2 \in (0, \epsilon_1], \rho_1 \in (0, \rho_0]$ such that if $\epsilon \in (0, \epsilon_2), u \in S(a)$ and $E_{\epsilon,T}(u) \leq \Upsilon_{\max,T,a} + \rho_1$, then*

$$Q_\epsilon(u) \in K_{\frac{\tilde{\rho}}{2}}.$$

Proof. If the lemma does not occur, there must be $\rho_n \rightarrow 0, \epsilon_n \rightarrow 0$ and $\{u_n\} \subset S(a)$ such that

$$E_{\epsilon_n,T}(u_n) \leq \Upsilon_{\max,T,a} + \rho_n \quad \text{and} \quad Q_{\epsilon_n}(u_n) \notin K_{\frac{\tilde{\rho}}{2}}. \tag{4.14}$$

Consequently,

$$\Upsilon_{\max,T,a} \leq J_{\max,T}(u_n) \leq E_{\epsilon_n,T}(u_n) \leq \Upsilon_{\max,T,a} + \rho_n,$$

then

$$\{u_n\} \subset S(a) \quad \text{and} \quad J_{\max,T}(u_n) \rightarrow \Upsilon_{\max,T,a}.$$

According to Lemma 3.6, we have two cases:

- (i) $u_n \rightarrow u$ in $H^1(\mathbb{R}^N)$ for some $u \in S(a)$,
- or
- (ii) There exists $\{y_n\} \subset \mathbb{R}^N$ with $|y_n| \rightarrow +\infty$ such that $v_n(x) = u_n(x + y_n)$ converges in $H^1(\mathbb{R}^N)$ to some $v \in S(a)$.

Analysis of (i): By the Lebesgue dominated convergence theorem,

$$Q_{\epsilon_n}(u_n) = \frac{\int_{\mathbb{R}^N} \chi(\epsilon_n x) |u_n|^2 dx}{\int_{\mathbb{R}^N} |u_n|^2 dx} \rightarrow \frac{\int_{\mathbb{R}^N} \chi(0) |u|^2 dx}{\int_{\mathbb{R}^N} |u|^2 dx} = 0 \in K_{\frac{\tilde{\rho}}{2}}.$$

From this, $Q_{\epsilon_n}(u_n) \in K_{\frac{\tilde{\rho}}{2}}$ for n large enough, which contradicts $Q_{\epsilon_n}(u_n) \notin K_{\frac{\tilde{\rho}}{2}}$ in Equation (4.14).

Analysis of (ii): Now, we will study two cases: (I) $|\epsilon_n y_n| \rightarrow +\infty$ and (II) $\epsilon_n y_n \rightarrow y$ for some $y \in \mathbb{R}^N$.

If (I) holds, the limit $v_n \rightarrow v$ in $H^1(\mathbb{R}^N)$ provides

$$\begin{aligned} E_{\epsilon_n,T}(u_n) &= \frac{1}{2} \int_{\mathbb{R}^N} |\nabla v_n|^2 dx - \frac{1}{q} \int_{\mathbb{R}^N} h(\epsilon_n x + \epsilon_n y_n) |v_n|^q dx \\ &\quad - \frac{\eta}{p} \tau(\|\nabla v_n\|_2) \int_{\mathbb{R}^N} |v_n|^p dx \\ &\rightarrow J_{\infty,T}(v). \end{aligned}$$

Since $E_{\epsilon_n, T}(u_n) \leq \Upsilon_{\max, T, a} + \rho_n$, we deduce that

$$\Upsilon_{\infty, T, a} \leq J_{\infty, T}(v) \leq \Upsilon_{\max, T, a},$$

which contradicts $\Upsilon_{\infty, T, a} > \Upsilon_{\max, T, a}$ in Lemma 4.1.

Now if (II) holds, then

$$\begin{aligned} E_{\epsilon_n, T}(u_n) &= \frac{1}{2} \int_{\mathbb{R}^N} |\nabla v_n|^2 \, dx - \frac{1}{q} \int_{\mathbb{R}^N} h(\epsilon_n x + \epsilon_n y_n) |v_n|^q \, dx \\ &\quad - \frac{\eta}{p} \tau(\|\nabla v_n\|_2) \int_{\mathbb{R}^N} |v_n|^p \, dx \\ &\rightarrow J_{h(y), T}(v), \end{aligned}$$

which combined with $E_{\epsilon_n, T}(u_n) \leq \Upsilon_{\max, T, a} + \rho_n$ gives that

$$\Upsilon_{h(y), T, a} \leq J_{h(y), T}(v) \leq \Upsilon_{\max, T, a}.$$

By Corollary 3.8, we must have $h(y) = h_{\max}$ and $y = a_i$ for some $i = 1, 2, \dots, l$. Hence,

$$\begin{aligned} Q_{\epsilon_n}(u_n) &= \frac{\int_{\mathbb{R}^N} \chi(\epsilon_n x) |u_n|^2 \, dx}{\int_{\mathbb{R}^N} |u_n|^2 \, dx} = \frac{\int_{\mathbb{R}^N} \chi(\epsilon_n x + \epsilon_n y_n) |v_n|^2 \, dx}{\int_{\mathbb{R}^N} |v_n|^2 \, dx} \\ &\rightarrow \frac{\int_{\mathbb{R}^N} \chi(y) |v|^2 \, dx}{\int_{\mathbb{R}^N} |v|^2 \, dx} = a_i \in K_{\frac{\tilde{\rho}}{2}}, \end{aligned}$$

which implies that $Q_{\epsilon_n}(u_n) \in K_{\frac{\tilde{\rho}}{2}}$ for n large enough. That contradicts Equation (4.14).

The proof is complete. □

From now on, we will use the following notations:

- $\theta_\epsilon^i := \{u \in S(a) : |Q_\epsilon(u) - a_i| \leq \tilde{\rho}\};$
- $\partial\theta_\epsilon^i := \{u \in S(a) : |Q_\epsilon(u) - a_i| = \tilde{\rho}\};$
- $\beta_\epsilon^i := \inf_{u \in \theta_\epsilon^i} E_{\epsilon, T}(u);$
- $\tilde{\beta}_\epsilon^i := \inf_{u \in \partial\theta_\epsilon^i} E_{\epsilon, T}(u).$

Lemma 4.7. *Let N, a, η, p, q and h be as in Equations (1.1) and (1.13) hold, ϵ_2 and ρ_1 be obtained in Lemma 4.6. Then, there exists $\epsilon_3 \in (0, \epsilon_2]$ such that*

$$\beta_\epsilon^i < \Upsilon_{\max, T, a} + \frac{\rho_1}{2} \quad \text{and} \quad \beta_\epsilon^i < \tilde{\beta}_\epsilon^i, \quad \text{for any } \epsilon \in (0, \epsilon_3).$$

Proof. Let $u \in S(a)$ be such that

$$J_{\max, T}(u) = \Upsilon_{\max, T, a}.$$

For $1 \leq i \leq l$, we define

$$\hat{u}_\epsilon^i(x) := u\left(x - \frac{a_i}{\epsilon}\right), \quad x \in \mathbb{R}^N.$$

Then, $\hat{u}_\epsilon^i \in S(a)$ for all $\epsilon > 0$ and $1 \leq i \leq l$. Direct calculations give that

$$E_{\epsilon,T}(\hat{u}_\epsilon^i) = \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u|^2 \, dx - \frac{1}{q} \int_{\mathbb{R}^N} h(\epsilon x + a_i) |u|^q \, dx - \frac{\eta}{p} \tau(\|\nabla u\|_2) \int_{\mathbb{R}^N} |u|^p \, dx,$$

and then

$$\lim_{\epsilon \rightarrow 0^+} E_{\epsilon,T}(\hat{u}_\epsilon^i) = J_{h(a_i),T}(u) = J_{\max,T}(u) = \Upsilon_{\max,T,a}. \tag{4.15}$$

Note that

$$Q_\epsilon(\hat{u}_\epsilon^i) = \frac{\int_{\mathbb{R}^N} \chi(\epsilon x + a_i) |u|^2 \, dx}{\int_{\mathbb{R}^N} |u|^2 \, dx} \rightarrow a_i \text{ as } \epsilon \rightarrow 0^+.$$

So $\hat{u}_\epsilon^i \in \theta_\epsilon^i$ for ϵ small enough, which combined with Equation (4.15) implies that there exists $\epsilon_3 \in (0, \epsilon_2]$ such that

$$\beta_\epsilon^i < \Upsilon_{\max,T,a} + \frac{\rho_1}{2}, \quad \text{for any } \epsilon \in (0, \epsilon_3).$$

For any $v \in \partial\theta_\epsilon^i$, that is, $v \in S(a)$ and $|Q_\epsilon(v) - a_i| = \tilde{\rho}$, we obtain that $|Q_\epsilon(v) \notin K_{\frac{\tilde{\rho}}{2}}$. Thus, by Lemma 4.6,

$$E_{\epsilon,T}(v) > \Upsilon_{\max,T,a} + \rho_1, \quad \text{for all } v \in \partial\theta_\epsilon^i \text{ and } \epsilon \in (0, \epsilon_3),$$

which implies that

$$\tilde{\beta}_\epsilon^i = \inf_{v \in \partial\theta_\epsilon^i} E_{\epsilon,T}(v) \geq \Upsilon_{\max,T,a} + \rho_1, \quad \text{for all } \epsilon \in (0, \epsilon_3).$$

Thus,

$$\beta_\epsilon^i < \tilde{\beta}_\epsilon^i, \quad \text{for all } \epsilon \in (0, \epsilon_3).$$

□

Now we are ready to prove Theorem 1.1.

Proof of Theorem 1.1. Set $\epsilon_0 := \epsilon_3$, where ϵ_3 is obtained in Lemma 4.7. Let $\epsilon \in (0, \epsilon_0)$. By Lemma 4.7, for each $i \in \{1, 2, \dots, l\}$, we can use the Ekeland’s variational

principle to find a sequence $\{u_n^i\} \subset \theta_\epsilon^i$ satisfying:

$$E_{\epsilon,T}(u_n^i) \rightarrow \beta_\epsilon^i \quad \text{and} \quad \|E_{\epsilon,T}'|_{S(a)}(u_n^i)\| \rightarrow 0, \quad \text{as } n \rightarrow +\infty,$$

that is, $\{u_n^i\}_n$ is a $(PS)_{\beta_\epsilon^i}$ sequence for $E_{\epsilon,T}$ restricted to $S(a)$. Since $\beta_\epsilon^i < \Upsilon_{\max,T,a} + \rho_0$, it follows from Lemma 4.5 that there exists u^i such that $u_n^i \rightarrow u^i$ in $H^1(\mathbb{R}^N)$. Thus

$$u^i \in \theta_\epsilon^i, \quad E_{\epsilon,T}(u^i) = \beta_\epsilon^i \quad \text{and} \quad E_{\epsilon,T}'|_{S(a)}(u^i) = 0.$$

As

$$Q_\epsilon(u^i) \in \overline{B_{\bar{\rho}}(a_i)}, \quad Q_\epsilon(u^j) \in \overline{B_{\bar{\rho}}(a_j)},$$

and

$$\overline{B_{\bar{\rho}}(a_i)} \cap \overline{B_{\bar{\rho}}(a_j)} = \emptyset, \quad \text{for } i \neq j,$$

we conclude that $u^i \not\equiv u^j$ for $i \neq j$ while $1 \leq i, j \leq l$. Therefore, $E_{\epsilon,T}$ has at least l non-trivial critical points for all $\epsilon \in (0, \epsilon_0)$.

As $E_{\epsilon,T}(u^i) < 0$ for any $i = 1, 2, \dots, l$, by Lemma 4.2, u^i ($i = 1, 2, \dots, l$) is in fact the critical point of E_ϵ on $S(a)$ with $E_\epsilon(u^i) < 0$ and then there exists $\lambda_i \in \mathbb{R}$ such that

$$-\Delta u^i = \lambda_i u^i + h(\epsilon x)|u^i|^{q-2}u^i + \eta|u^i|^{p-2}u^i, \quad x \in \mathbb{R}^N.$$

By using $E_\epsilon(u^i) = \beta_\epsilon^i < 0$ and $E'_\epsilon(u^i)u^i = \lambda_i a^2$, we obtain that

$$\frac{1}{2}\lambda_i a^2 = E_\epsilon(u^i) + \left(\frac{1}{q} - \frac{1}{2}\right) \int_{\mathbb{R}^N} h(\epsilon x)|u^i|^q \, dx + \left(\frac{1}{p} - \frac{1}{2}\right) \int_{\mathbb{R}^N} |u^i|^p \, dx,$$

which implies that $\lambda_i < 0$ for $i = 1, 2, \dots, l$. The proof is complete. □

5. Stability

In this section, we investigate the stability of the solutions obtained in Theorem 1.1. For any $i = 1, 2, \dots, l$, we define

$$\begin{aligned} \Omega_i &:= \{v \in \theta_\epsilon^i : E_{\epsilon,T}'|_{S(a)}(v) = 0, \quad E_{\epsilon,T}(v) = \beta_\epsilon^i\} \\ &= \{v \in \theta_\epsilon^i : E_\epsilon'|_{S(a)}(v) = 0, \quad E_\epsilon(v) = \beta_\epsilon^i, \quad \|\nabla v\|_2 \leq R_0\}. \end{aligned} \tag{5.1}$$

Next we show the stability of the sets Ω_i ($i = 1, \dots, l$) in two cases $p < 2^*$ or $p = 2^*$.

Proof of Theorem 1.4. Letting r_1 be such that $\bar{g}_a(r_1) = \beta_\epsilon^i$, and considering Equation (2.6), the definition of Ω_i and $\beta_\epsilon^i < 0$, we know that

$$\|\nabla v\|_2 \leq r_1 < R_0, \quad \text{for any } v \in \Omega_i.$$

Let $a_1 > a$ be such that $\bar{g}_{a_1}(R_0) = \frac{\beta_\epsilon^i}{2}$. There exists $\delta > 0$ such that if

$$u_0 \in H^1(\mathbb{R}^N) \quad \text{and} \quad \text{dist}_{H^1(\mathbb{R}^N)}(u_0, \Omega_i) < \delta,$$

then

$$\|u_0\|_2 \leq a_1, \quad \|\nabla u_0\|_2 \leq r_1 + \frac{R_0 - r_1}{2}, \quad E_{\epsilon,T}(u_0) \leq \frac{2}{3}\beta_\epsilon^i.$$

Denoting by $\psi(t, \cdot)$ the solution to Equation (1.17) with initial value u_0 and denoting by $[0, T_{\max})$ the maximal existence interval for $\psi(t, \cdot)$, we have classically that either $\psi(t, \cdot)$ is globally defined for positive times, or $\|\nabla\psi(t, \cdot)\|_2 = +\infty$ as $t \rightarrow T_{\max}^-$, see ([38], Section 3). Set $\tilde{a} = \|u_0\|_2$. Note that $\|\psi(t, \cdot)\|_2 = \|u_0\|_2$ for all $t \in (0, T_{\max})$ by the conservation of the mass. If there exists $\tilde{t} \in (0, T_{\max})$ such that $\|\nabla\psi(\tilde{t}, \cdot)\|_2 = R_0$, then

$$E_\epsilon(\psi(\tilde{t}, \cdot)) = E_{\epsilon,T}(\psi(\tilde{t}, \cdot)) \geq \bar{g}_{\tilde{a}}(R_0) \geq \bar{g}_{a_1}(R_0) = \frac{\beta_\epsilon^i}{2},$$

which contradicts the conservation of the energy:

$$E_\epsilon(\psi(t, \cdot)) = E_\epsilon(u_0) \leq \frac{2}{3}\beta_\epsilon^i, \quad \text{for all } t \in (0, T_{\max}).$$

Thus,

$$\|\nabla\psi(t, \cdot)\|_2 < R_0, \quad \text{for all } t \in [0, T_{\max}), \tag{5.2}$$

which implies that $\psi(t, \cdot)$ is globally defined for positive times.

Next we prove that Ω_i is stable. The validity of Lemma 4.5 for complex valued function can be proved exactly as in Theorem 3.1 in [13]. Thus, the stability of Ω_i can be proved by modifying the classical Cazenave–Lions argument [10] (see also [24]). For the completeness, we give the proof here. Suppose by contradiction that there exist sequences $\{u_{0,n}\} \subset H^1(\mathbb{R}^N)$ and $\{t_n\} \subset \mathbb{R}^+$ and a constant $\theta_0 > 0$ such that for all $n \geq 1$,

$$\inf_{v \in \Omega_i} \|u_{0,n} - v\| < \frac{1}{n} \tag{5.3}$$

and

$$\inf_{v \in \Omega_i} \|\psi_n(t_n, \cdot) - v\| \geq \theta_0, \tag{5.4}$$

where $\psi_n(t, \cdot)$ is the solution to (1.17) with initial value $u_{0,n}$. By Equation (5.2), there exists n_0 such that for $n > n_0$ it holds that $\|\nabla\psi_n(t, \cdot)\|_2 < R_0$ for all $t \geq 0$.

By Equation (5.3), there exists $\{v_n\} \subset \Omega_i$ such that

$$\|u_{0,n} - v_n\| < \frac{2}{n}. \tag{5.5}$$

That $\{v_n\} \subset \Omega_i$ implies that $\{v_n\} \subset \theta_\epsilon^i$ is a $(PS)_{\beta_\epsilon^i}$ sequence of $E_{\epsilon,T}$ restricted to $S(a)$. From the proof of Theorem 1.1, there exists $v \in \Omega_i$ such that

$$\lim_{n \rightarrow +\infty} \|v_n - v\| = 0,$$

which combined with (5.5) gives that

$$\lim_{n \rightarrow +\infty} \|u_{0,n} - v\| = 0. \tag{5.6}$$

Hence,

$$\lim_{n \rightarrow +\infty} \|u_{0,n}\|_2 = \|v\|_2 = a, \quad \lim_{n \rightarrow +\infty} E_\epsilon(u_{0,n}) = E_\epsilon(v) = \beta_\epsilon^i < \tilde{\beta}_\epsilon^i.$$

Then by the conservation of mass and energy, we obtain that

$$\lim_{n \rightarrow +\infty} \|\psi_n(t, \cdot)\|_2 = a, \quad \lim_{n \rightarrow +\infty} E_\epsilon(\psi_n(t, \cdot)) = \beta_\epsilon^i, \quad \text{for any } t \geq 0. \tag{5.7}$$

Define

$$\varphi_n(t, \cdot) = \frac{a\psi_n(t, \cdot)}{\|\psi_n(t, \cdot)\|_2}, \quad t \geq 0.$$

Then $\varphi_n(t, \cdot) \in S(a)$ and

$$\|\varphi_n(t, \cdot) - \psi_n(t, \cdot)\| \rightarrow 0 \text{ as } n \rightarrow +\infty \text{ uniformly in } t \geq 0, \tag{5.8}$$

which combined with Equation (5.6) gives that

$$\lim_{n \rightarrow +\infty} \|\varphi_n(0, \cdot) - v\| = \lim_{n \rightarrow +\infty} \left\| \frac{au_{0,n}}{\|u_{0,n}\|_2} - v \right\| = 0.$$

Hence, $\varphi_n(0, \cdot) \in \theta_\epsilon^i \setminus \partial\theta_\epsilon^i$ for n large enough because $v \in \theta_\epsilon^i \setminus \partial\theta_\epsilon^i$. Using the method of continuity, $\lim_{n \rightarrow +\infty} E_\epsilon(\varphi_n(t, \cdot)) = \beta_\epsilon^i$ for all $t \geq 0$, and $\beta_\epsilon^i < \tilde{\beta}_\epsilon^i$, we obtain that:

$$\text{for } n \text{ large enough, } \varphi_n(t, \cdot) \in \theta_\epsilon^i \setminus \partial\theta_\epsilon^i \quad \text{for all } t \geq 0. \tag{5.9}$$

From (5.7)–(5.9), $\{\varphi_n(t_n, \cdot)\} \subset \theta_\epsilon^i$ is a minimizing sequence of $E_{\epsilon,T}$ at level β_ϵ^i , and from the proof of Theorem 1.1, there exists $\tilde{v} \in \theta_\epsilon^i$ such that

$$\lim_{n \rightarrow +\infty} \|\varphi_n(t_n, \cdot) - \tilde{v}\| = 0, \tag{5.10}$$

which combined with (5.8) gives that

$$\lim_{n \rightarrow +\infty} \|\psi_n(t_n, \cdot) - \tilde{v}\| = 0.$$

That contradicts (5.4). Hence Ω_i is stable for any $i = 1, 2, \dots, l$. □

Proof of Theorem 1.5. The proof can be done by modifying the arguments of §3 and 4 in [18] and using the arguments of the proof of Theorem 1.4, so we omit it. □

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