

# On the detection of internal interfacial layers in turbulent flows

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A novel approach to identify internal interfacial layers, or IILs, in wall-bounded turbulent flows is proposed. Using a fuzzy cluster method (FCM) on the streamwise velocity component, a unique and unambiguous grouping of the uniform momentum zones (UMZs) is achieved, thus allowing the identification of the IILs. The approach overcomes some of the key limitations of the histogram-based IIL identification methods. The method is insensitive to the streamwise domain length, can be used on inhomogeneous grids, uses all the available flow field data, is trivially extended to three dimensions and does not need user-defined parameters (e.g. number of bins) other than the number of zones. The number of zones for a given snapshot can be automatically determined by an *a priori* algorithm based on a kernel density estimation algorithm, or KDE. This automated approach is applied to compute the average number of UMZs as a function of Reynolds number  $Re_\tau$  in turbulent channel flows in several numerical simulations. This systematic approach reveals a dependence of the Reynolds number on the average number of UMZs in the channel flow; this supports previously reported observations in the boundary layer. The fuzzy clustering approach is applied to the turbulent boundary layer (experimental, planar particle image velocimetry) and channel flow (numerical, direct numerical simulation) at varying Reynolds numbers. The interfacial layers are characterized by a strong concentration of spanwise vorticity, with the outer-most layer located at the upper edge of the log layer. The three-dimensional interface identification reveals a streak-like organization. The large-scale motion (LSM) at the outer region of the channel flow boundary layer modulates the outer IIL. The corrugations of the outer IIL are aligned with the LSM and the conditional correlation of the inner and outer IIL height shows that extreme near-wall events leave their mark on the outer IIL corrugations.

**Key words:** boundary layer structure, turbulent boundary layers

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## 1. Introduction

The delineation between regions of different turbulence intensity is central to the study of turbulent flows. The most obvious boundary occurs at the interface between

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turbulent and non-turbulent regions in many free shear or wall-bounded flows such as jets, wakes, mixing and boundary layers. As the turbulent/non-turbulent interface (TNTI) bounds the turbulent region, the exchange of mass, momentum and energy between the turbulent and non-turbulent regions must occur through this interface. Consequently, the evolution of the flow properties can be understood and explained through the prism of the dynamics of the interfacial layer, as done in the seminal work by Corrsin & Kistler (1955) and many others since (see e.g. Bisset, Hunt & Rogers (2002), Westerweel *et al.* (2005), da Silva *et al.* (2014)).

Although not as obvious, an interfacial layer is also observed in wall-bounded turbulent flows. Meinhart & Adrian (1995) reported the existence of an internal interfacial layer (denoted here as IIL) inside the turbulent boundary layer which delineates the zones with relatively uniform streamwise momentum, also called uniform momentum zones or UMZs. IILs play an important role in momentum transport as the spanwise vorticity is localized near the interface, which results in a rapid change in the instantaneous streamwise velocity. Jumps in streamwise velocity are a common feature to both the TNTI (Bisset *et al.* 2002; Chauhan *et al.* 2014) and IIL (Kwon *et al.* 2014; de Silva *et al.* 2017). The existence of UMZs and IILs is also consistent with the prevailing understanding of coherent structures within wall-bounded turbulent flows. Adrian, Meinhart & Tomkins (2000) indicated that coherent alignment of hairpin vortices in the streamwise direction (or vortex packets) creates the appearance of UMZs. Recently, a representative model for large-scale motion (LSM) presented by Saxton-Fox & McKeon (2017) also results in a zonal-like structure of the turbulent boundary layer.

Although interfacial layers are central to our fundamental understanding of turbulent flow dynamics, the identification approaches – particularly for the IIL – are often ambiguous, arbitrary and plagued with interpretational uncertainties. A user-defined threshold on the magnitude of the enstrophy is widely accepted as a means to identify the TNTI in turbulent wake (Bisset *et al.* 2002), boundary layer (Borrell & Jiménez 2016) and other flows (Holzner & Lüthi 2011) as the turbulent and non-turbulent regions are rotational and irrotational, respectively. On the other hand, as IILs are embedded within turbulent – thus rotational – flow, the vorticity-based thresholding methods are ineffective at detecting the bounds of the UMZs. Eisma *et al.* (2015) identified IILs in a turbulent boundary layer and attempted to eliminate the influence of mean shear by a triple decomposition of vorticity following Kolar (2007). However, the threshold in their investigation is nonetheless selected empirically. Adrian *et al.* (2000) suggested that the local peak in a streamwise velocity histogram identifies the modal velocity representing a uniform momentum zone; the iso-surface of the streamwise velocity at the local minimum between the peaks corresponds to the interfacial layer. Following Adrian *et al.* (2000), de Silva, Hutchins & Marusic (2016) concluded that the number of UMZs increases log-linearly with the Reynolds number and the interface is characterized by an instantaneous streamwise velocity jump. However, the histogram peaks are sensitive to the number of bins, the streamwise domain ( $L_x$ ) and the selected flow region under consideration (many approaches neglect the near-wall and free-stream data when constructing the histogram). An incorrect selection of the number of bins or streamwise domain may lead to incorrect peaks in the histogram. Adrian *et al.* (2000) suggested that  $L_x \approx \delta$ , where  $\delta$  is the thickness of boundary layer, is needed for peak identification in the histogram method but de Silva *et al.* (2016) argued that this quantity should be selected based on inner scaling parameters. They determined that  $L_x^+ \approx 2000$  was appropriate for turbulent boundary layers and  $L_x^+$  introduces an implicit filter on the histogram. UMZs have

also been reported in turbulent channel flows (Kwon *et al.* 2014) where  $L_x = 1.2h$  (with  $h$  being the channel half-height) was selected after examining the modal velocity change with increasing  $L_x$ . Furthermore, the histogram approach cannot trivially be extended to three-dimensional interface identification as the spanwise corrugations of the velocity histogram act to smear out the visible peaks in the two-dimensional planar field of view.

We propose a unified approach to identify interfacial layers in two- or three-dimensional turbulent flow fields – obtained experimentally or numerically – using a fuzzy cluster method (FCM). This approach is repeatable, robust, unambiguous and can be used for either TNTI or IIL with varying levels of spatial resolution and/or grid spacing inhomogeneities. The novel clustering approach identifies the same IIL as the histogram-based identification method, but overcomes many of the limitations of the latter method. Most importantly, it can provide a full three-dimensional description of the internal interface which allows for a more detailed investigation of the conditional flow statistics at the boundaries of the UMZs. This work analyses publicly available planar particle image velocimetry (PIV) and three-dimensional direct numerical simulation (DNS) data. Our code is provided online for full repeatability and transparency of the obtained results. In this work, the details of the procedure are presented in § 2 and the results are summarized in § 3. The FCM is applied to experimental turbulent boundary layer data (§ 3.2) and to numerical three-dimensional turbulent channel flow data (§ 3.3). The increased statistical sample size of the three-dimensional data provides the opportunity to study the IILs with detailed conditional statistics and topological feature extraction. The sensitivity and robustness of the proposed method is investigated in § 4; it is shown that the method is robust against perturbations to the initial conditions, the initialization of the membership functions and the *a priori* selection of the number of zones.

## 2. Detection of interfacial layers based on cluster analysis

The following subsection describes the principles of a fuzzy clustering method (FCM) called fuzzy c-means clustering which is applied to the identification of internal zones. An additional method is also proposed, in § 2.2, to automatically determine the number of zones.

### 2.1. Fuzzy cluster method

A novel approach is proposed which identifies the internal interfacial layers by grouping contiguous and non-contiguous zones according to common flow features. Here, we consider flow fields from an instantaneous snapshot of a large-eddy simulation (LES), direct numerical simulation (DNS) or particle image velocimetry (PIV, either planar or volumetric) database. The entirety of the flow data within a given snapshot forms a sequence of observations,  $\Phi = \{\Phi^m\}_{m=1}^N$ , where  $N$  represents the total number of grid points in the snapshot and  $\Phi$  a scalar quantity such as pressure or velocity component (Friedman, Hastie & Tibshirani 2001). As the clustering is done on the streamwise velocity in the current paper, we replace  $\Phi$  with  $U$  to simplify the notation. The cluster analysis aims at grouping the observations  $\{U^m\}_{m=1}^N$  into  $K$  clusters,  $\Pi_k$  (with  $k = 1, \dots, K$ ), based on their similar streamwise velocity. To quantify similar flow features, a distance metric between two observations is defined as  $D_{mn} = |U^m - U^n|$ , where the norm is in the Euclidean space. We adopt an FCM (Dunn 1973; Bezdek 1981) in which a membership coefficient  $u_{mk}$  represents

the probability of the observation  $U^m$  belonging to cluster  $\Pi_k$ . Based on this definition,  $\sum_{k=1}^K u_{mk} = 1$ . We define  $c^k$  as the centroid of cluster  $k$ , accordingly, it represents the characteristic velocity of the cluster. It corresponds to the average of all observations with the membership function  $u_{mk}$ :

$$c^k = \frac{\sum_{m=1}^N (u_{mk})^p U^m}{\sum_{m=1}^N (u_{mk})^p}, \tag{2.1}$$

where  $p \in [1, \infty)$  is the fuzziness parameter in FCM and is usually set to 2 in practice (Pal & Bezdek 1995). The cluster centroids form a centroid vector  $\mathbf{c} = (c^1, \dots, c^K)$ . The cluster centroid represents a characteristic velocity of each cluster and, as for the modal velocity in the histogram method, represents the characteristic velocity of each zone. Once  $\mathbf{c}$  and  $u_{mk}$  are determined, the variance can be defined as an object function

$$J_p(\mathbf{U}, \mathbf{c}) = \sum_{m=1}^N \sum_{k=1}^K (u_{mk})^p (D_{mk})^2. \tag{2.2}$$

The optimal  $\mathbf{c}$  is determined by the minimization of the objective function via the standard Lagrange multiplier method. As a result, the FCM is a bootstrapping algorithm which is summarized as follows:

- (1) initialize the membership coefficient  $u_{mk}$  for each observation;
- (2) compute the centroid of the clusters  $c^k$  with equation (2.1);
- (3) recompute the membership coefficient using the new  $c^k$

$$u_{mk} = \left( \sum_{j=1}^K (D_{mk}/D_{mj})^{2/(p-1)} \right)^{-1}; \tag{2.3}$$

- (4) execute steps 2 and 3 iteratively until  $|\mathbf{c} - \mathbf{c}_0| \leq \epsilon$ , where  $\epsilon$  is a pre-determined error threshold and  $\mathbf{c}_0$  is the centroid vector in the previous iteration.

Once converged, we assign the observation  $U^m$  to  $\Pi_k$  with the highest membership  $I_m = \arg \max_k (u_{mk})$ . Although it is reported that FCM can be sensitive to initial  $u_{mk}$  (Pham, Xu & Prince 2000), the present results are shown to be robust and invariant to the initialization. Naturally, the FCM algorithm requires a user-defined number of clusters  $K$ , and various approaches to determine the optimal  $K$  are possible. For example, Bezdek (1974) defined a partition coefficient to measure the ‘overlap’ between clusters and  $K$  is selected when the partition coefficient reaches a minimum. In the following section, we propose an algorithm, based on a kernel density estimation (KDE) approach, to automatically select the appropriate number of zones for a given dataset. The interface identification code and the method to identify the number of zones – both written in Python – as well as all the datasets used are freely accessible online.

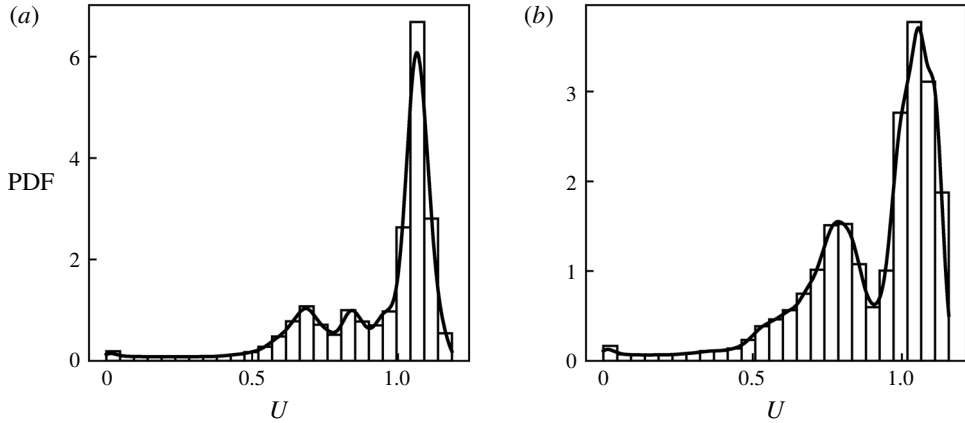


FIGURE 1. Kernel density estimation at two different streamwise locations of DNS channel flow data (Lee & Moser 2015).

### 2.2. Selection of the number of IILs

The clustering approach rests on the understanding that we have an *a priori* knowledge of the number of clusters or IILs in a given flow. At low Reynolds number, the number of internal zones can be inferred from a physical understanding of the various regions within wall-bounded turbulent flow. This simplistic approach breaks down when faced with higher-Reynolds-number wall-bounded turbulent flows for which the number of zones is dependent on the Reynolds number (de Silva *et al.* 2016). For this reason, we propose an alternative clustering approach that automatically determines the optimal number of zones based on the same streamwise velocity parameter as the FCM. The approach, which rests on a KDE algorithm, does suffer from some of the same shortcomings as the histogram-based approach (requires an adequate selection of domain length, inability to account for near-wall grid stretching etc.); in the current implementation it is only used to determine the number of zones, and by extension, the number of IILs.

Kernel density estimation is a statistical method which is used to estimate the underlying probability density function from a set of sampled data. A kernel is placed at each observation and the results are summed to produce a smooth probability density function which accounts for the density of the observed samples. Two important parameters of the KDE are the shape of the kernel and the bandwidth, which acts as a smoothing parameter. Although there are a variety of possible kernels which can be used, the bandwidth has a much more significant effect on the results of the KDE. In our analysis, we use a Gaussian kernel; more information on the density estimation can be found in Silverman (1998). Based on a minimization of the mean integrated squared error, the optimal bandwidth  $h$  for a normal kernel is calculated as (Scott 1992)

$$h = \sigma(4/3)^{1/5} n^{-1/5}, \quad (2.4)$$

where  $\sigma$  is the standard deviation and  $n$  is the number of observations.

An example of a KDE applied over the same window size at two different streamwise locations of DNS channel flow data from Lee & Moser (2015) is shown in figure 1. The automatic bandwidth determination allows for an accurate identification

of the number of internal zones. Similar to the histogram method, the KDE is conducted on a slice-by-slice basis. Although the number of peaks is defined without user input, the clustering would subsequently have to be performed on the thin region where the predicted number of zones is valid.

To group the data, a clustering approach based on KDE called mean shift clustering can be applied. Similar to KDE, the correct bandwidth selection has been studied and there are many recommendations, eliminating the need for the user to arbitrarily input a bandwidth. Despite promising results on PIV data, which has well-defined peaks, the mean shift clustering approach misidentifies the peaks in the presence of the smaller grid sizes near the wall in DNS results. The newly proposed fuzzy clustering method, presented in the previous subsection, does not have the same limitations.

Although the selection of the number of zones is a key input to the FCM, the correct identification of IIL is nonetheless possible if the selected number of zones is slightly incorrect (say  $\pm 1$ ), see §4, which discusses the sensitivity and robustness of our method to the selection of the number of zones. In other words, if a flow is composed of three internal zones (two IILs), the same two IILs will be identified by the method if we wrongly input three IILs. This robustness assures a correct identification of the dynamically significant parts of the flow; as the proposed method does not require any user input (other than the velocity data), it provides a systematic approach to estimate the number of zones in a given database.

### 3. Results and discussion

#### 3.1. Experimental and numerical databases

Three publicly accessible turbulent flow databases – one experimental (PIV), two numerical (DNS) – are used for the validation of the proposed method (a fourth turbulent channel flow DNS at  $Re_\tau = 750$ , on a small domain, was used to compute the average number of UMZs). Combined with our online accessible cluster algorithm ([https://github.com/mxyao/Interfacial\\_Layer\\_Clustering](https://github.com/mxyao/Interfacial_Layer_Clustering)), this assures a repeatable, transparent and generalizable assessment of our approach. First, we compare our cluster identification method against Adrian *et al.* (2000)'s histogram-based approach by examining the planar PIV dataset of a turbulent boundary layer by Tomkins (1997). Second, the organization and conditional sampling of the IILs are analysed using two snapshots of the incompressible channel flow DNS by Del Álamo *et al.* (2004) and two snapshots by Lee & Moser (2015). The friction velocity Reynolds number of the boundary layer (where  $h$  is the boundary layer thickness) is  $Re_\tau = u_\tau h/\nu = 2216$ . The snapshots of the channel flow (where now  $h$  is the channel half-height) are at 550, 950 (Del Álamo *et al.* 2004) and 1000, 5186 (Lee & Moser 2015). The extent of the spatial domain and grid resolution of the datasets are summarized in table 1; further details can be found in the corresponding references.

#### 3.2. Internal interface in the turbulent boundary layer

We first compare the IIL identification using the histogram and clustering approaches on the planar PIV data of a turbulent boundary layer. The algorithm proposed by de Silva *et al.* (2016) was used to identify the modal velocity of the UMZs based on the histogram peaks of the streamwise velocity. Two key features of de Silva *et al.* (2016)'s approach are: (1) the vector field above the TNTI and below  $y^+ = 100$  is excluded from the histogram; (2) the histogram is constructed on a constrained domain of  $L_x^+ = 2000$ . These imposed constraints on the histogram calculation are

	$Re_\tau$	$L_x$	$L_y$	$L_z$	$\Delta x^+$	$\Delta y^+$	$\Delta z^+$	References
Turb. BL PIV	2216	$2.9\delta$	$1.2\delta$	—	30	30	—	Tomkins (1997)
Channel DNS	550	$8\pi h$	$2h$	$3\pi h$	8.9	0.018–4.44	3.3	Del Álamo <i>et al.</i> (2004)
	950	$8\pi h$	$2h$	$3\pi h$	7.6	0.031–7.62	3.8	
Channel DNS	1000	$8\pi h$	$2h$	$3\pi h$	10.9	0.00276–6.22	4.601	Lee & Moser (2015)
	5186	$8\pi h$	$2h$	$3\pi h$	12.7	0.498–10.3	6.4	
Channel DNS	750	$2\pi h$	$2h$	$\pi h$	9.14	0.09–7.4	6.15	Current DNS

TABLE 1. Spatial domain and grid resolution of the boundary layer PIV measurements and the channel flow simulations. Note the ‘Current DNS’ is only used to estimate the number of UMZs in the following sections and not for the primary analysis.

well reported in the literature. The removal of the near-wall and irrotational flow regions is needed to clearly observe multiple peaks in the histogram distribution, otherwise skewed modal velocities and/or additional peaks are observed. Furthermore, previous PIV studies on IILs (de Silva *et al.* 2017) only cover a limited field of view (typically  $2h$ ), primarily due to the ambiguity of the histogram-based method over a large spatial extent despite that IILs have been shown to correlate with very large-scale motion (VLSM) having a streamwise length proportional to  $h$  (Adrian *et al.* 2000). Although the footprints of these VLSM are expected to be seen in the IIL, the limited field of view renders the detailed study of the interaction of these structures with the interfacial layers more difficult.

The proposed clustering algorithm overcomes the above-noted limitations of the histogram-based approach. The FCM only requires the *a priori* knowledge of the number of UMZs. The KDE algorithm, described in § 2.2, correctly identifies four UMZs without the need of any user input. The identified zones have a direct physical representation in this flow. Near the wall, in the viscous sublayer, the viscosity effects dominate the dynamics and the length scales are proportional to  $\nu/u_\tau$  (zone 1). In zone 2, the flow is still influenced by the near-wall turbulence and inner wall scalings but the relative importance of the viscosity is reduced; this usually corresponds to the logarithmic region in the mean velocity profile. At the outer edge of the boundary layer (zone 3), the velocity profile is defined by outer scaling parameters, typically  $\delta$ . Finally, the free-stream region of the boundary layer is non-turbulent and irrotational (zone 4 or FS). We note that the TNTI is identified at the interface between zones 3 and 4. Although the threshold-based TNTI identification methods are simple and straightforward, the cluster algorithm implicitly delineates this interface. The present cluster method can be used for TNTI identification when, for example, coarse experimental data at the outer boundary layer edge limit the ability to compute the local vorticity needed for the thresholding identification.

The direct comparison of histogram-based and cluster interface identification approaches is presented in figure 2(a), which corresponds to the PIV frame in Adrian *et al.* (2000) (figure 19 in their paper). The streamwise velocity histogram has a local minimum at  $U/U_\infty = 0.8$  (when  $L_x^+ = 2000$ ), see figure 2(c), which corresponds to the IIL delineating UMZs. In the cluster-based approach, we include all velocity vectors in the PIV frame and obtain the same interfaces (figure 2a) and modal velocities (figure 2c,d). The inspection of the instantaneous streamwise velocity profile at one  $x/\delta$  location in figure 2(b) reveals a step-like change at the identified interfacial layers; similar step-like shifts are observed at the interfaces of other streamwise

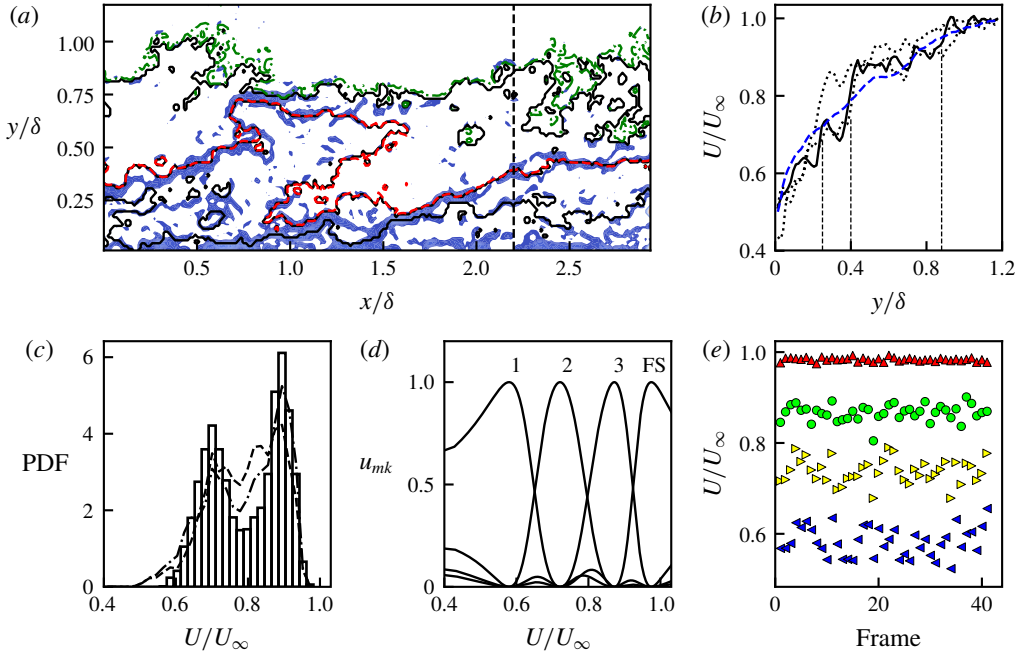


FIGURE 2. (Colour online) (a) Comparison of the following interfacial layer identification algorithms on a turbulent boundary layer PIV frame: cluster-based algorithm (solid black lines), histogram-based IIL (dashed red line) and threshold-based TNTI (solid green line). The approach by de Silva *et al.* (2016) is used for the IIL detection. For the TNTI, a threshold on the local turbulent kinetic energy is used as proposed by Chauhan *et al.* (2014). The magnitude of the local spanwise vorticity is overlaid (minimum threshold on the non-dimensionalized vorticity magnitude is set to  $10^{-4}U_\infty/\delta$  to highlight the vorticity concentration). (b) Instantaneous streamwise velocity profile (solid line) at  $x/\delta = 2.2$  (shown as a dashed vertical line in *a*) and mean velocity computed over the PIV frame are overlaid (dots). (c) Histogram of streamwise velocity based on streamwise domain length of  $L_x^+ = 2000$  (bins), 4000 (dashed line) and 6000 (dashed-dotted line). (d) Cluster membership function,  $u_{mk}$ , for zones 1, 2, 3 and FS. (e) Cluster centroid in all available PIV frames (41 in total) using FCM, zone 1 ( $\blacktriangleleft$ ), zone 2 ( $\blacktriangleright$ ), zone 3 ( $\bullet$ ) and zone FS ( $\blacktriangle$ ).

locations (not shown). As the IILs are conceptually thought to represent thin shear layers (Meinhart & Adrian 1995), we note a vorticity concentration in their vicinity (figure 2a); the vorticity is observed at all of the three interfacial layers separating the four zones of the flow.

As noted by de Silva *et al.* (2016), the histogram-based IIL identification method is sensitive to the streamwise domain under consideration. By increasing the domain length from  $L_x^+ = 2000$  to 4000, a third peak emerges in the histogram, see figure 2(c); this additional peak vanishes when the domain length is extended to  $L_x^+ = 6000$ . Additionally, by considering the data points near the wall ( $y^+ < 100$ ) or in the free stream, the streamwise velocity histogram cannot uniquely identify the IIL on this dataset. In view of these constraints and limitations of the histogram method, the unambiguous identification of histogram peaks is only successful in approximately half of the PIV frames in the database (41 planar PIV frames are available). In



many frames, clear modal peaks cannot be deciphered. However, hairpin structures and vortex packets can be observed in most frames. If we accept that UMZs are the result of these structures, UMZs and IILs should exist even when the histogram method fails. The modal velocities computed from the cluster-based method show an expected frame-to-frame variation but a high consistency, especially for zones 3 and FS, is noted among all PIV frames as shown figure 2(e). The lower resolution near the wall may account for the relatively higher variation in modal velocities of zones 1 and 2.

### 3.3. Interfacial layer in a turbulent channel flow

As shown in the previous subsection, the TNTI and IILs are unambiguously identified with a robust and repeatable cluster algorithm in a turbulent boundary layer. The interfaces obtained by clustering match those from the histogram (IIL) and turbulence threshold (TNTI) methods while overcoming many of the limitations of these classical approaches. Despite their three-dimensional nature, the IILs have historically been identified from two-dimensional, experimental data. Unlike the TNTI identification which is trivially extended to three dimensions (Bisset *et al.* 2002; Hickey, Hussain & Wu 2013; Borrell & Jiménez 2016), a surface IIL identification on volumetric data suffers from conceptual and practical limitations when using a histogram-based approach. As highlighted by Kwon *et al.* (2014) (figure 3f), the modal velocity peaks (used to identify the UMZs) are not detected in the streamwise velocity histogram in the three-dimensional channel flow. Only the very prominent modal velocity of the quiescent core is observed. Although the velocity histogram helps in the identification of the quiescent core, the detection of interfacial layers is impeded. Additionally, if we consider all numerical simulations, the local grid refinement near the wall gives rise to an artificial peak in the histogram due to a larger cell count of near-wall, lower-velocity points. The current cluster-based approach can be extended to unambiguously identify these three-dimensional, internal interfacial surfaces from numerical databases. In this section, we apply the cluster algorithm to three-dimensional, incompressible channel flow DNS data. First, we relate the number of UMZs to the Reynolds number of the flow (§ 3.3.1), then we compute the statistical features of the IILs (§ 3.3.2) and, finally, relate the geometric properties of the IIL to the large-scale organized motion in the channel flow (§ 3.3.3).

#### 3.3.1. Number of UMZs

Unlike the turbulent boundary layer, which is typically bounded by an irrotational, free-stream region, the turbulent channel flow is fully turbulent. Based on this, we assume that a typical low-Reynolds-number channel flow consists of three zones: a viscous-dominated near-wall region (zone 1), a wall-turbulence-dominated region (zone 2) and an outer-scale-dominated region (zone 3). Zone 3 can also be called the ‘quiescent core’ although the exact definition used here differs somewhat from Kwon *et al.* (2014). This zonal delineation is supported by the results of the automatic KDE-based algorithm to determine the number of zones which is presented in § 2 for the low-Reynolds-number cases.

For high-Reynolds-number flows, the interfacial layers have thus far only been investigated using experimental data. The difficulty in obtaining near-wall experimental data with a sufficient spatial and temporal resolution over a large, three-dimensional field means that analysis of these IILs has been limited. Furthermore, existing histogram-based approaches are ill-suited for use on non-homogeneous grid spacing,

as the grid refinement artificially affects the probability distribution of the streamwise velocity. Here we study IILs in the turbulent channel flow by Lee & Moser (2015) which is computed up to  $Re_\tau \approx 5200$  using a Fourier–Galerkin pseudo-spectral method in the streamwise and spanwise directions and a B-spline collocation method in the wall-normal direction. The details of the resolution are provided in table 1 and further information can be found in Lee & Moser (2015).

Uniform momentum zones are defined as regions of uniform streamwise velocity typically found within the logarithmic region of the turbulent boundary layer (Meinhart & Adrian 1995; de Silva *et al.* 2016). When the full range of data in our method is used, we identify an IIL very close to the wall which bounds the viscous-dominated near-wall region (zone 1). However, this zone is inconsistent with the definition of a UMZ, which is typically found in the outer regions of the boundary layer. As such, in our analysis of UMZs, we do not consider this very near-wall zone to be a UMZ but it is nonetheless a delineated zone. For example, as we can see from figure 1, a small peak emerges at  $U \approx 0$ ; this peak is not counted in the average number of UMZ computations below.

The number of UMZs has been shown to scale with the Reynolds number in boundary layer flows (de Silva *et al.* 2016). Applying the KDE approach to an ensemble of two-dimensional slices to each of the turbulent channel flows in our database, we unambiguously and automatically identify the average number of UMZs as a function of the  $Re_\tau$ . For the analysis, we first randomly select individual slices in the three-dimensional snapshots, then we define a streamwise extent of  $L_x = 2000$  wall units and, finally, we run the KDE algorithm; the total number of peaks is recorded and averaged among all the slices for a given Reynolds number. As the KDE approach is based on an adaptive binning procedure, there was no user input required, thus making the approach robust and repeatable for all datasets. Figure 3 compares the computed number of UMZs from the channel flow database with the previously reported turbulent boundary layer (de Silva *et al.* 2016). The variation of the number of zones with Reynolds number in the channel flow follows the same trend and slope as in the boundary layer, with the notable exception that the channel flow has fewer zonal hierarchies due to the constrained nature of the set-up. The limited  $Re_\tau$ -range of our datasets, especially between 1000 and 5000 but also above 5200, limits our ability to make any further claims on the observed difference in the channel and boundary layer flows.

### 3.3.2. Statistics of IILs

The three-dimensional identification of IILs means that converged statistical properties on these interfacial layers can be collected from datasets. The probability distribution function of the IIL height,  $y_I$ , for  $Re_\tau = 550$  and 950 cases is shown in figure 4(a,b). To a first order, the interfacial height has a log-normal distribution with a mean equal to  $\ln(Y_I/h) = -1.48/-1.53$  and standard deviation of 0.62/0.61 for the  $Re_\tau = 550/950$  cases. Further away from the wall, the height of the TNTI has been reported to follow a Gaussian distribution in the turbulent boundary layer (Chauhan *et al.* 2014) and other flows (Bisset *et al.* 2002; Hickey *et al.* 2013). However, a positive skewness  $-0.645/0.641$  – is noted in the IIL height distribution. This implies, not too surprisingly, that the presence of the wall has a greater influence on the IIL than on the TNTI which has a skewness that is nearly zero. As a result, a log-normal fit as seen in figure 4(a,b) provides a better description of the IIL height distribution.

The comparison of the mean interfacial height in the  $Re_\tau = 550$  and 950 cases suggests an  $Re$ -dependence. The normalized height of the interface decreases with  $Re_\tau$ ,

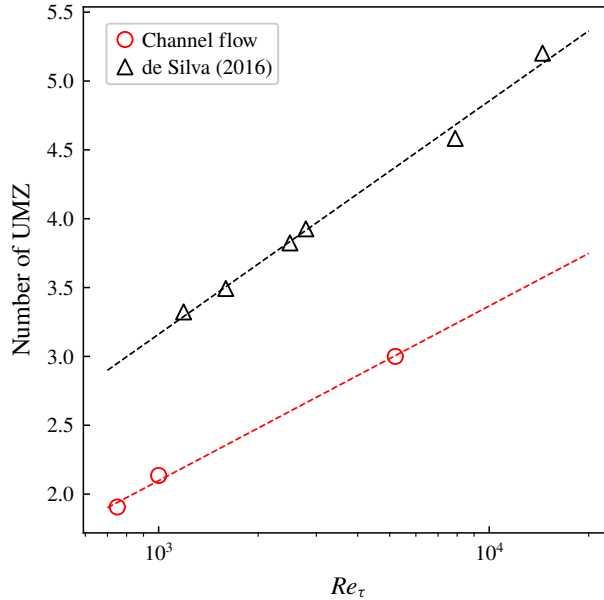


FIGURE 3. (Colour online) Average number of UMZs in turbulent channel flow databases computed based on the KDE algorithm. The comparative number of zones for the turbulent boundary layer, computed by de Silva *et al.* (2016), is shown in black.

a result which is consistent with Kwon *et al.* (2014)'s observation that the thickness of the quiescent core increases with  $Re_\tau$ , an observation in line with the previous subsection. The mean location of the IIL normalized by the viscous unit is overlaid on the mean streamwise velocity profile (see figure 4c). As noted earlier, zone 2 is associated with the logarithmic layer and the location of the IIL (between zones 2 and 3) defines the top of logarithmic layer in the mean profile. The connection between IILs/UMZs and the logarithmic layer has been postulated by Meinhart & Adrian (1995) but their detailed investigation was unable to provide evidence of this connection, partially because of a lack of a robust and unambiguous IIL detection method. The present approach will allow us to address many of these lingering issues.

The conditional averages are computed across the interfacial layer (between zones 2 and 3) and provide further statistical evidence of their importance. Here the conditional averages are computed at a relative distance from the interfacial layer,  $y^+ - y_i^+$  (where  $y^+ - y_i^+ < 0$  indicates a location below the interfacial layer). Figure 5(a) shows the large streamwise velocity jump across the interfacial layer which has been reported in previous works (Eisma *et al.* 2015; de Silva *et al.* 2017). At the IIL, a very clear peak in the spanwise vorticity is observed from the conditional statistics in figure 5(b). Interestingly, the shear-like nature of the IIL may also result in a differential wall-normal velocity relative to the interface, as shown in figure 5(c). These conditional statistics support the understanding that the IIL acts as a strong shear layer in the wall turbulence.

Given the cluster algorithm's ability to unambiguously extract the three-dimensional interface, the topology of the IIL is examined in the large-spanwise-domain channel flow simulation. We recall that the three-dimensional interface is not defined based on a streamwise iso-velocity contour (as is the case for the histogram approach);

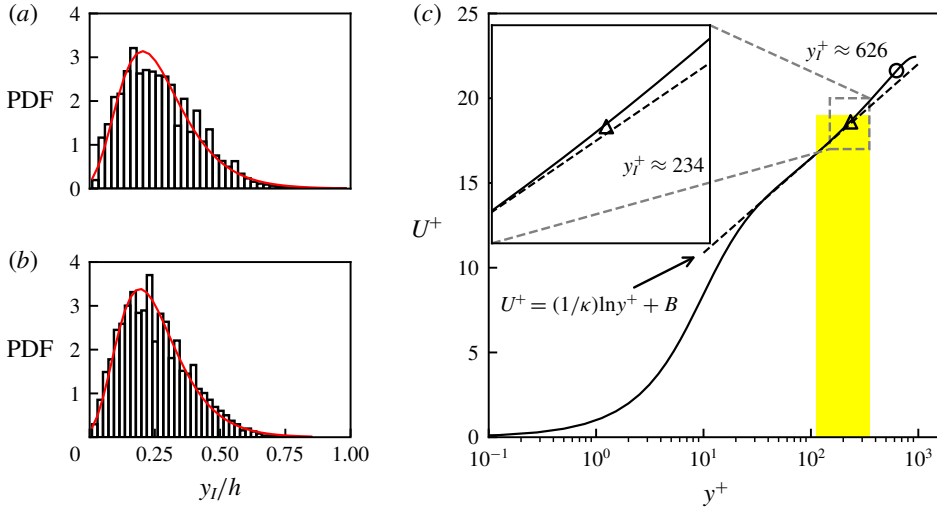


FIGURE 4. (Colour online) The distribution of the height of the IIL (between zones 2 and 3) for a turbulent channel flow at  $Re_\tau = 550$  (a) and 950 (b). The solid red lines correspond to a fitted log-normal probability distribution function. (c) Mean streamwise velocity profile (normalized in wall units) is shown relative to the mean height of IIL between zone 2 and 3 for  $Re_\tau = 950$ . The log law  $U^+ = (1/\kappa) \ln(y^+) + B$  (dashed line) is obtained by a linear fit of data between  $y^+ = 3Re_\tau^{1/2}$  and  $0.15Re_\tau$  ( $\kappa = 0.41$ ) following Marusic *et al.* (2013). The mean height is highlighted by  $\Delta$  and  $\circ$  corresponds to the height of the quiescent core interface of Kwon *et al.* (2014). The width of the vertical bar denotes the standard deviation of the interface height.

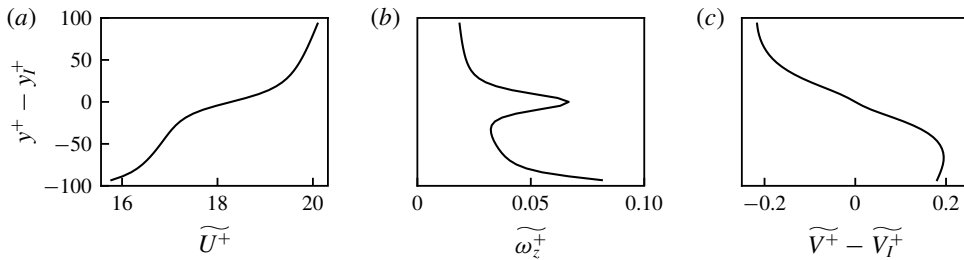


FIGURE 5. Conditional average across the IIL between zones 2 and 3 of the (a) streamwise velocity, (b) spanwise vorticity and (c) relative wall-normal velocity in the channel flow at  $Re_\tau = 950$ .

instead, the fuzzy clustering allows a delineation that is more representative of the underlying physics. A streamwise-aligned organization of the interfacial height is clearly visible in figure 6(a). The autocorrelation function of the interfacial height in the streamwise ( $R_{hh}(x)$ ) and spanwise ( $R_{hh}(z)$ ) directions further supports this visual observation (figure 6b). The spanwise length scale is approximately  $0.5h$  whereas the streamwise length scale is more than  $3h$ . The distribution and correlations of the height underscore a streak-like feature of the IIL which has been believed to be related to the well-established streaky structure in the buffer layer. Kwon *et al.* (2014) identified an IIL as the  $0.95U_{CL}$  iso-surface ( $U_{CL}$  is the centreline velocity)

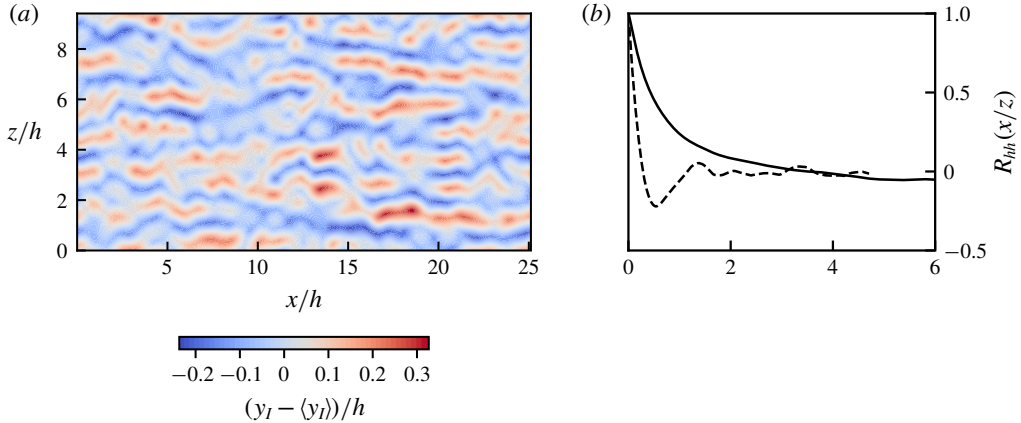


FIGURE 6. (Colour online) (a) Fluctuations of the IIL (between zones 2 and 3) normalized height for the channel flow at  $Re_\tau = 950$  (Del Álamo *et al.* 2004). The raw data are low-pass filtered and re-sampled onto a coarser grid ( $\Delta x \times \Delta z = 0.1h \times 0.1h$ ). (b) Streamwise (solid) and spanwise (dashed) autocorrelations of the IIL height fluctuation (computed using the raw data).

in the channel flow simulation at  $Re_\tau = 1000$  and also observed similar streak-like features. These very long streamwise length scales support the observation of Adrian *et al.* (2000) that UMZs are the natural results of LSMs or vortex packets.

### 3.3.3. Interfacial layers and large-scale motion

The connection between interfacial layers and the large-scale motion (LSM) is investigated through the three-dimensional interfacial identification in the flow. The LSM is known to play an integral role in wall-bounded turbulent flows, and given its dynamic importance in the outer region, it has been shown that the LSM acts to modulate the TNTI in turbulent boundary layer flows (Lee, Sung & Zaki 2017). Many researchers, most notably Adrian *et al.* (2000), have proposed conceptual frameworks to relate the UMZs, and ultimately LSM, to an alignment of hairpin vortices forming a hairpin packet; many of the foundational concepts of UMZs rest on Townsend's understanding of a hierarchy of attached eddies (de Silva *et al.* 2016). Underpinning many of these conceptual models is the idea that near-wall perturbations can be responsible for the dynamics within the outer region of wall-bounded flows.

The LSM, being primarily located in the outer region of the boundary layer, should also play a role in the modulation of the interfacial layers between the outer UMZs. Qualitatively, the LSMs are easily identified through any classical near-wall turbulent visualization approaches. Here, we rely on the formal streak detection algorithm proposed by Lee *et al.* (2014) to quantitatively identify the LSMs in order to relate them to the three-dimensional IILs. The streak detection rests on sequential data filtering of the streamwise velocity fluctuations (Gaussian followed by a long-wavelength-pass filter) and structure detection algorithms which are detailed in the referenced paper (Lee *et al.* 2014). We investigate the channel flow at  $Re_\tau = 1000$  (Lee & Moser 2015) by extracting the characteristic splines (CS) which are located within a characteristic plane (CP); these splines are related to underlying characteristic structures, such as hairpin vortices (Lee *et al.* 2014). Figure 7(a) shows the location of the positive (+) and negative (○) characteristic

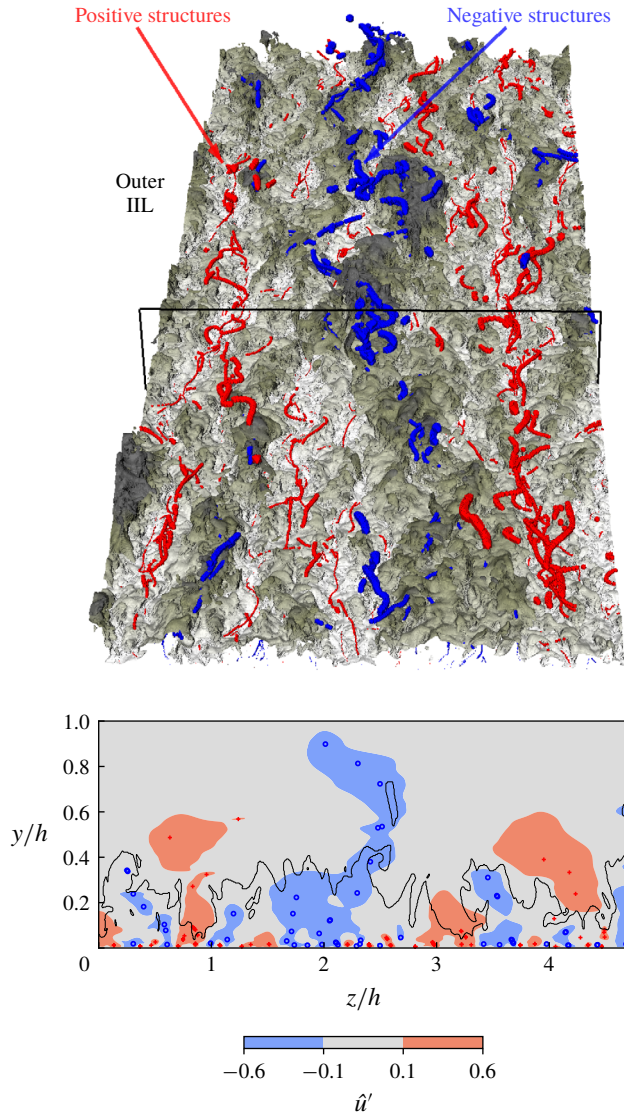


FIGURE 7. (Colour online) The cores of turbulent structures with a positive (+) and negative (○) streamwise velocity fluctuations identified following the approach by Lee *et al.* (2014) on the turbulent channel flow at  $Re_\tau = 1000$  (Lee & Moser 2015). (a) Identified structure cores overlaid on the three-dimensional outer IIL; the IIL is coloured by the height relative to the wall. (b) Spanwise slice of the outer IIL taken at  $x = 8.0$  (identified in a); regions of positive and negative streamwise velocity fluctuations are shown for clarity.

splines in three dimensions; the outer interfacial layer (between zones 2 and 3) – identified through our clustering algorithm – is shown coloured by its height from the wall. Here, we clearly identify the very long positive and negative streamwise velocity regions in the flow. The three-dimensional visualizations show that in the valleys of the IIL, an alignment of coherent structures with a positive streamwise velocity

fluctuation is found. Conversely, structures with a negative streamwise fluctuation concentrate along the ridges of the IIL. This observation correlates with the ejection and sweep-type mechanisms that are typical for these types of near-wall structures. The ability to define three-dimensional interfaces supports the postulated relationship between the near-wall structures and the interfacial layers in wall-bounded turbulence (de Silva *et al.* 2017).

The connection between the outer IIL and LSM is clearly seen in the  $y/z$  slice at a constant streamwise location in figure 7(b). By overlaying locally filtered regions of positive and negative streamwise velocity, we show that the IIL is modulated by the LSM in the outer layer of the boundary. Based on these qualitative observations, it is also expected that these same LSMs modulate the near-wall IIL. To this end, we compute the cross-correlation coefficient of the IIL height of the inner and outer IIL. A slightly positive correlation coefficient (0.103) is observed between the height of both layers, which can be explained by the skewness resulting from the presence of the wall. A small correlation is not too surprising as the interfacial heights at these two very distant locations in the boundary layer should be, for the most part, dynamically independent. By conditionally sampling the data to only consider the locations of peak near-wall events – where the height of the inner IIL is greater than one standard deviation from the mean – a significantly higher correlation is noted (0.22). In other words, near-wall events that significantly modify the local interfacial height can be felt in the outer part of the near-wall boundary layer in these flows.

#### 4. Sensitivity and robustness of the identification method

The advantages of the FCM with respect to the standard histogram-based approach have been detailed in the previous sections and it has been shown how the method can be extended to three-dimensional surface identification. Here, we evaluate the sensitivity and robustness of the proposed IIL identification method. More specifically, we evaluate the sensitivity of the method to the *a priori* selection of the number of zones, to the initialization of the membership function and to a stochastic perturbation on the raw data (representing experimental error or numerical noise).

##### 4.1. Sensitivity to the number of IILs

The FCM requires a user-defined number of internal zones,  $K$ , as an *a priori* input for clustering. In § 2, we proposed a method to automatically determine the number of internal zones in a given flow snapshot based on a kernel density estimation (KDE). The question then arises: how sensitive is the FCM identification if the wrong number of internal zones,  $K$ , is provided as input? It is understood that if the incorrect number of zones is selected as an input to the algorithm for a given snapshot, the physical interpretation of the UMZs would be incorrect. Nonetheless, we show that the identification of the most important internal layers is insensitive to the number of zones if the error in  $K$  is  $\pm 1$ . Figure 8 shows the IILs of a single slice of the high-Reynolds-number channel flow DNS by Lee & Moser (2015) using three ( $K = 3$ , full line) and four ( $K = 4$ , dashed line) internal zones (with respectively two and three IILs). The same two IILs are identified using a different number of clusters: very near the wall and at the outer edge of the boundary layer. When clustering on four zones (three IILs) instead of three (two IILs), an additional interface is identified. In other words, the approach remains robust to a small error in the *a priori* quantification of the number of zones. This same analysis was also conducted using five zones with similar results. It should be noted that on lower-Reynolds-number datasets, the result

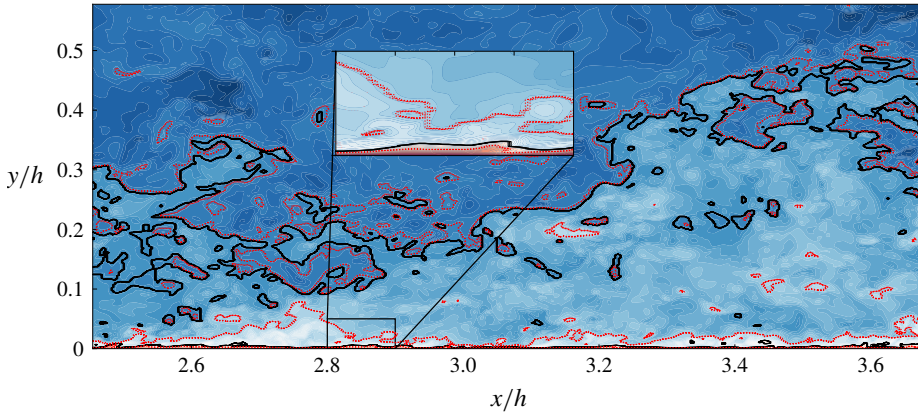


FIGURE 8. (Colour online) The IIL overlaid on the streamwise velocity contour plot for a high-Reynolds-number channel flow (Lee & Moser 2015). The black solid lines are the identified IILs initialized with three internal zones and the red dotted lines are the identified IILs initialized with four internal zones.

showed a slightly greater sensitivity to the error. Although this sensitivity analysis highlights the robustness of the algorithm to the selection of the number of zones, the physical interpretation of the results would differ greatly if an incorrect number of zones were used. Therefore, it is essential to carefully conduct an *a priori* KDE analysis to assess the correct number of zones for a given snapshot in a dataset.

#### 4.2. Sensitivity to initialization

One of the shortcomings of many data clustering approaches lies in the sensitivity of the final cluster to the initialization. In order to initiate the fuzzy cluster algorithm, the membership functions,  $u_{mk}$ , must be initialized. The number of membership functions is the same as the *a priori* determined number of clusters,  $K$ . Suppose we have three clusters ( $K=3$ ), the sum of all of the membership functions at each  $m$  grid points is

$$u_{m1} + u_{m2} + u_{m3} = 1. \quad (4.1)$$

To study the sensitivity of the FCM, we randomly select the initial membership function centroids in order to test the robustness of the method to the initialization. A three-dimensional Dirichlet probability distribution is used to randomly select the centroids for initialization. The Dirichlet distribution is fully defined by three independent parameters  $(\alpha_1, \alpha_2, \alpha_3)$ , and under the proper normalization, the sum of the membership functions is unity. Figure 9 shows the tested Dirichlet probability distributions for initialization; each point in the triangle must have a value constrained between 0 and 1 in each dimension and must sum up to one. Irrespective of our selected initialization, exactly the same IILs (height, statistics and centroids) are identified for the channel flow simulation at  $Re_\tau = 950$  (centreplane slice). The statistics on the modal velocities, the normalized height of the interface ( $\mu/h$ ) and its standard deviation  $\sigma/h$  are shown in table 2. These results clearly show that the method remains robust to the initialization of the problem.



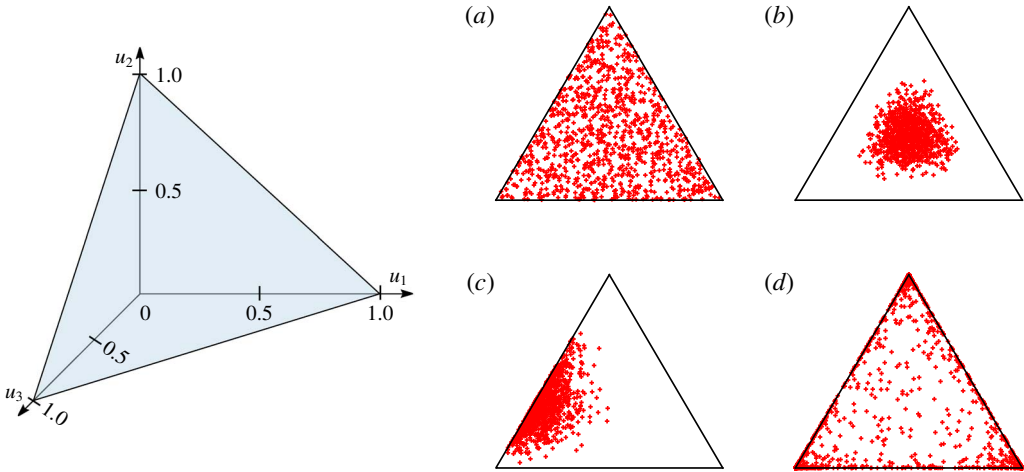


FIGURE 9. (Colour online) The Dirichlet distribution of the membership function initialization where each side of the triangle represents the initialization of one of the membership functions. The points in the triangle must simultaneously satisfy two constraints: the value must be constrained between 0 and 1 in each dimension and must sum up to 1 (see illustration on left side). The parameters used to defined the Dirichlet probability distribution are  $\alpha_1, \alpha_2, \alpha_3$ . The above distributions represent (see table 2): (a) Case 1; (b) Case 2; (c) Case 3; and (d) Case 4.

	$\alpha_1$	$\alpha_2$	$\alpha_3$	$c/U_b$	$\mu/h$	$\sigma/h$
Case 1	1	1	1	(0.129, 0.648, 0.930)	0.332515	0.108964
Case 2	10	10	10	(0.129, 0.648, 0.930)	0.332515	0.108964
Case 3	1	5	10	(0.129, 0.648, 0.930)	0.332515	0.108964
Case 4	0.2	0.2	0.2	(0.129, 0.648, 0.930)	0.332515	0.108964

TABLE 2. Dirichlet distribution parameters, converged cluster centroid and statistics ( $\mu$  and  $\sigma$  are respectively the mean and standard deviation of the interfacial height) of the IIL between zones 2 and 3 for Cases 1, 2, 3 and 4.

### 4.3. IIL identification under stochastic perturbations

As the clustering approach remains agnostic of the underlying physics of the flow, we test the robustness of the interfacial identification to initial perturbations to the data. Such perturbations could arise from experimental noise or discretization errors. Using the same initial membership functions (with a defined number of clusters), we perturb the raw data with white noise; here we use the channel flow at  $Re_\tau = 1000$  for reporting the analysis; similar findings are observed on the other data. We perturb the numerical data with up to 50% white noise based on the bulk velocity of the flow. To show the robustness of the method, the perturbations are not damped down to the wall, thus creating a non-physical noise. Figure 10(a) shows the effect of the white noise on the identification of the cluster centres (which correspond to the modal velocities of internal zones); under 15% noise, very little variation in the modal velocity is noted. The effect of the added noise on the average height of the IIL is presented in figure 10(b). The average height of the interface and its standard deviation remains constant up to 15% white noise. Figure 10(c) shows the outer

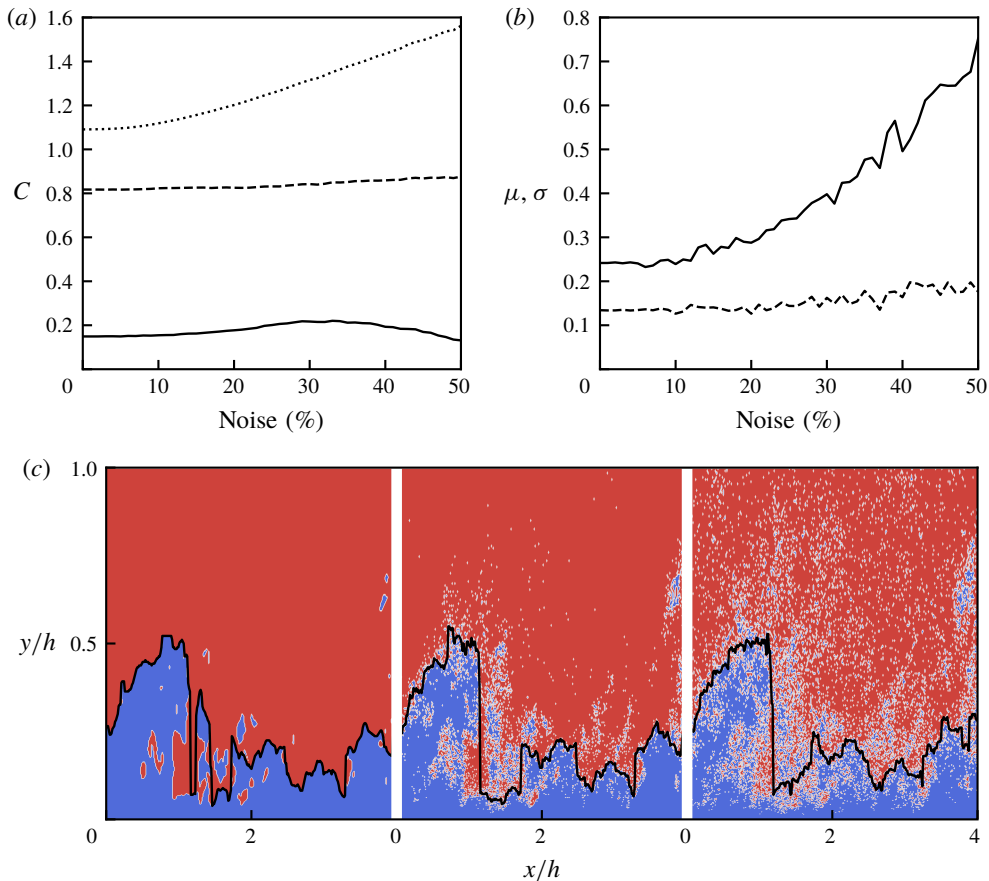


FIGURE 10. (Colour online) Robustness of the FCM against initial perturbations to the data. (a) Shows the effect of white noise on the identified cluster centres centroids; each line corresponds to the modal velocity of the UMZs. As the amplitude of the noise increases (above, say, 15%), the ability to capture the cluster centre decreases. (b) Shows the average height of the IIL between zones 2 and 3 (solid line) and the standard deviation (dashed line) as a function of the imposed noise to the data. (c) Shows the IIL between zones 2 and 3 under 0% (solid), 5% (dash-dotted), 10% (dotted), and 30% (dashed) white noise. (c) Shows the IIL between zones 2 and 3 under 0%, 5% and 10% noise (from left to right) at the same streamwise plane view. Grid points are coloured based on the zones and the solid black line represents the outer envelope of the IIL.

envelope of the ILL, between zones 2 and 3, under 0% (left), 5% (centre), and 10% (right) random perturbations. We note that similar interface geometries can be captured despite the added noise.

## 5. Conclusion

We propose a novel cluster-based algorithm to identify interfacial layers in turbulent flows using a fuzzy cluster method (FCM). The approach is unambiguous, robust and repeatable. Most importantly, it overcomes some of the limitations of the well-established histogram-based identification approaches. The new approach is invariant to the streamwise domain size, inhomogeneous near-wall grid spacing

and/or number of bins used in the histogram approach. Furthermore, it can be extended, without limitations, to three-dimensional flow fields. The only user-defined quantity is the number of uniform momentum zones (UMZs) to be extracted. We also propose an algorithm based on a kernel density estimation (KDE) to automatically identify the number of UMZs for a given dataset; the KDE algorithm is only used for an *a priori* estimation of the number of UMZs. Using this systematic approach, we computed the relationship between the number of UMZs and Reynolds number in the channel flow. The variation compares favourably to the boundary layer, except that fewer UMZs are identified due to the constrained nature of the channel flow. We evaluated the sensitivity of the cluster algorithm to an error in the number of UMZs, initialization of the membership functions and stochastic perturbations of raw data; the sensitivity results highlight the robustness of the proposed method. The FCM was successfully applied to boundary layer data (experimental, PIV) and recovers the layers identified by the classical histogram- (IIL) and threshold-based (TNTI) approaches. The new method identifies the interfaces for all datasets, whereas the histogram method only functions on about half the available PIV frames. As the proposed method can be extended to three dimensions, the additional sampling data of the extracted IILs in a turbulent channel flow (numerical, DNS) is used to better understand the relationship between the interfacial layer and mean flow profile. We find that the mean interfacial height is located at the end of the log layer and shows a strong Reynolds-number dependence. The three-dimensional structures of the interface show a strong streamwise coherence, revealing a streaky-like structural pattern. We show that the large- and very large-scale motion within the boundary is correlated to the three-dimensional undulations of the IIL. Finally, the conditional sampling reveals a very strong peak of spanwise vorticity at the interface. The proposed identification method will be applied to large-scale, transitional flow data by Wu *et al.* (2017) for further insight into the dynamics of interfacial layers.

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