

POINT-LIKE, SIMPLICIAL MAPPINGS OF A 3-SPHERE

ROSS FINNEY

1. Introduction. A *decomposition* of a topological space X is a partitioning of X into non-empty, disjoint sets called *elements* of the decomposition. An element of a decomposition is *non-degenerate* if it contains more than one point. Associated with each decomposition D of X is a topological space D^* , called the *hyperspace* of the decomposition. A classical problem on decompositions of topological spaces is to find conditions under which D^* is homeomorphic to X . Often decompositions arise from mappings: if g is a mapping of a space X onto a space Y , then $D = \{g^{-1}(y) \mid y \in Y\}$ is a decomposition of X . Moreover, if X is compact and if Y is a Hausdorff space, then D^* is homeomorphic to Y and we may solve the problem by finding conditions under which Y is homeomorphic to X . (By *mapping* we shall always mean *continuous function*, and by *space* we shall always mean T_1 -*space*.)

In 1925, R. L. Moore showed that if X is a 2-sphere, then Y is homeomorphic to X if and only if for each point y in Y the inverse image $g^{-1}(y)$ is a continuum which does not separate X **(3)**.

In 1938, J. H. Roberts and N. E. Stenrod showed that if X is a compact, connected 2-manifold, then Y is homeomorphic to X if and only if Y contains more than one point and the 1-dimensional Betti number (mod 2) of each of the sets $g^{-1}(y)$, where y is a point of Y , is zero **(4)**.

In 1936, G. T. Whyburn posed a question embodying a generalization of Moore's theorem **(5)**, asking whether Y is homeomorphic to X whenever X is a 3-sphere and g is point-like. A subset A of an n -sphere S^n is *point-like* if the space $(S^n - A)$ is homeomorphic to Euclidean n -space E^n . A mapping g of an n -sphere onto a space Y is *point-like* if the set $g^{-1}(y)$ is point-like for each point y in Y . Whyburn's question concerns a possible generalization of Moore's theorem because the point-like subsets of the 2-sphere are exactly those subsets which are continua that do not separate the sphere.

In 1957, R. H. Bing published an example of a point-like mapping of S^3 onto a space topologically different from S^3 **(1)**.

In 1958, O. G. Harrold, Jr. published sufficient conditions for a monotone image of a 3-sphere to be a 3-sphere. The conditions require that the closure of the set of points in the image-space which have non-degenerate inverse-images be totally disconnected, but are stronger and more interesting **(2)**.

Received June 13, 1962. This paper is part of a thesis submitted to the Graduate School of the University of Michigan in partial fulfillment of the requirements for the degree of Doctor of Philosophy. The thesis was written under the direction of Professor E. E. Moise. At the time, the author was supported by funds from the National Science Foundation.

Going in a different direction from Harrold's result, we prove the following theorem.

THEOREM. *Let M be a triangulated 3-sphere and let T be a triangulated topological space. If there exists a point-like, simplicial mapping of M onto T , then T is homeomorphic to M .*

Here a triangulated 3-sphere is a finite, simplicial complex whose geometric realization is homeomorphic to a 3-sphere. Throughout this paper, complex will mean finite, simplicial complex and a single symbol will denote both a complex and its associated topological space.

2. The proof in outline. Let f be the given point-like simplicial mapping of M onto T , and let $G = \{f^{-1}(t) \mid t \in T\}$. We see that the union of the non-degenerate elements of G is a subcomplex K of M . In fact, K is the union of all faces of all 3-simplices on which f fails to be one-to-one. If K is empty, then f is the required homeomorphism. We suppose henceforth that K is non-empty. Since f is one-to-one on at least one 3-simplex of M , the frontier of K is non-empty. We can find a 3-simplex σ in K which has the properties:

- (1) σ has a 2-face in $\text{Fr}(K)$;
- (2) if g is a non-degenerate element of G , then $\text{Cl}(g - \sigma)$ is empty or still point-like; and
- (3) $\text{Cl}(K - \sigma)$ is a subcomplex of M with fewer simplices than K .

Using σ we define a new decomposition G_1 of M as follows: g_1 is an element of G_1 if either g_1 is a point of $(M - \text{Cl}(K - \sigma))$ or g_1 is one of those sets $\text{Cl}(g - \sigma)$ which is non-empty, g being an element of G . The elements of G_1 are point-like, the hyperspace G_1^* is homeomorphic to G^* and hence to T , and the union of the non-degenerate elements of G_1 is a proper subcomplex K_1 of K .

In K_1 there will be a simplex σ_1 with properties analogous to those stated for σ . Just as we used σ to construct G_1 , we use σ_1 to construct a decomposition G_2 of M into point-like sets. As before, G_2^* is homeomorphic to G_1^* and hence to T , and the union K_2 of the non-degenerate elements of G_2 is a proper subcomplex of K_1 .

We continue to construct new decompositions (although σ and σ_1 must be 3-simplices, eventually 2-simplices may be used) until at last we construct a subcomplex K_n of K which can be reduced no further. While G_n is still a decomposition of M into point-like sets, and while G_n^* is still homeomorphic to T , the decomposition G_n now has only finitely many non-degenerate elements. A decomposition of the 3-sphere into point-like sets, which has only a finite number of non-degenerate elements, has a hyperspace homeomorphic to the 3-sphere. Hence G_n^* is homeomorphic to M as well as to T , and the theorem is proved.

The technique of constructing a new decomposition by deleting a simplex is an unpublished technique of E. E. Moise. The technique is formalized for

our purposes as the construction of D_1^* from D^* in Lemma 4.5. Once Lemma 4.5 has been proved, the burden of proof rests on showing that the construction may be applied repeatedly to G and K until G_n is reached.

3. Preliminary lemmas. If A is a subset of a topological space X , then $D(A)$ is the subset of X that is the union of those elements of the decomposition D which meet A . If $D(A)$ is closed whenever A is closed, D is *upper semi-continuous*. Thus each element d of an upper semi-continuous decomposition D of a T_1 -space is closed, for if x is a point in d , then $D(x) = d$ is closed.

The usefulness of upper semi-continuous decompositions is illustrated by the following assertions. If D is an upper semi-continuous decomposition of a metric space X into compact sets, then the convergence of points in D^* corresponds to the convergence of the elements of D , as subsets in X (Lemma 3.4). If D is upper semi-continuous and if X is normal, then D^* is a Hausdorff space (Lemma 3.2). In particular, if D is an upper semi-continuous decomposition of a compact Hausdorff space, then D^* is a (compact) Hausdorff space.

The lemmas are presented without proof.

LEMMA 3.1. *Let X be a compact topological space, and let g be a one-to-one mapping of X onto a topological space Y . If Y is a Hausdorff space, then g is a homeomorphism.*

LEMMA 3.2. *Let X be a topological space, and let D be an upper semi-continuous decomposition of X . If X is normal, then D^* is a Hausdorff space.*

LEMMA 3.3. *If D is a decomposition of a compact topological space, then D^* is compact.*

LEMMA 3.4. *Let D be an upper semi-continuous decomposition of a metric space X into compact sets. Let $\{s_i\}$ be a sequence of points of D^* . If A and B are compact subsets of X , then let*

$$z(A, B) = \inf_{\substack{a \in A \\ b \in B}} m(a, b),$$

where m is the given metric on X . Let s be a point of D^* . The sequence $\{s_i\}$ converges to s if and only if

$$\lim z(p^{-1}(s_i), p^{-1}(s)) = 0.$$

LEMMA 3.5. *Let X be a compact topological space, let Y be a Hausdorff space, let g be a mapping of X onto Y , and let $D = \{g^{-1}(y) \mid y \in Y\}$. Then D^* is homeomorphic to Y under the correspondence $p(d) \leftrightarrow f(d)$, where d is an element of D and p is the projection mapping of X onto D^* . Also, D is an upper semi-continuous decomposition of X .*

4. The structure of K . Suppose that L is a subcomplex of K and that each non-degenerate element of G meets L in either the empty set or in a

non-degenerate, point-like subset of M . Let D be the decomposition of M that consists of (1) each of the points of $(M - L)$, and (2) those of the sets $(g \cap L)$ which are non-empty. We note that L is the union of the non-degenerate elements of D , and that D is an upper semi-continuous decomposition of M .

When we reduce K according to the scheme mentioned before, the union K_i of the non-degenerate elements at the i th stage will have properties identical with those now hypothesized for L . What we deduce now about the structure of L will be used to reduce K_i to obtain K_{i+1} . Lemma 4.5 is a statement of the feasibility of the inductive step: if the subcomplex L of K contains a certain kind of simplex, then L and the decomposition D associated with L may be reduced to give a decomposition D_1 of M into point-like sets of which the non-degenerate elements form a proper subcomplex H of L and of which the hyperspace D_1^* is homeomorphic to D^* . In the section following this one we show how to use Lemma 4.5 to prove the theorem. Proofs of some of the simpler lemmas will be omitted.

Whenever σ^n is an n -simplex, $\text{Int } \sigma^n$ will denote the topological interior of σ^n , and $\text{Bdy } \sigma^n$ will denote $(\sigma^n - \text{Int } \sigma^n)$.

DEFINITION. *If L is a complex, then the 2-frontier $\text{Fr}_2(L)$ of L is the collection of those 2-simplices of L each of which lies in exactly one 3-simplex of L .*

LEMMA 4.1. *If σ^2 is a 2-simplex of L , and if $f(\sigma^2)$ is a 2-simplex, then σ^2 lies in a 3-simplex of L .*

Proof. Let σ_1^3 and σ_2^3 be the two 3-simplices of M that contain σ^2 , and let x be a point of $\text{Int}(\sigma^2)$. Since x lies in L , the set $f^{-1}(f(x))$ is a non-degenerate element of G . If $f(\sigma^2)$ is a 2-simplex, then $[f^{-1}(f(x)) \cap \sigma^2] = x$. If neither σ_1^3 nor σ_2^3 lies in L , then either $[f^{-1}(f(x)) \cap L] = x$, or $[f^{-1}(f(x)) \cap L]$ is not connected, and hence not point-like. Neither alternative is possible. Hence at least one of the two 3-simplices σ_1^3 , σ_2^3 lies in L .

LEMMA 4.2. *If σ^3 is a 3-simplex of L one face of which is mapped by f onto a 2-simplex τ^2 of T , then $f(\sigma^3) = \tau^2$ and σ^3 has two 2-faces which are mapped by f onto τ^2 .*

LEMMA 4.3. *If σ^2 is a 2-simplex of L , and if $f(\sigma^2) = \tau^2$ is a 2-simplex of T , then every element of D which meets $\text{Int}(\sigma^2)$ is a polygonal arc. If σ^3 is a 3-simplex of L which f maps onto τ^2 , then $\text{Int}(\sigma^3)$ is decomposed into line-segments each of which*

(1) *is parallel to whichever edge of σ^3 it is that is mapped onto a vertex of τ^2 , and*

(2) *joins together the 2-faces of σ^3 that f maps onto τ^2 .*

LEMMA 4.4. *Let σ^2 be a 2-simplex of L which f maps onto a 2-simplex. Suppose that f maps n 3-simplices of L onto $f(\sigma^2)$; $n > 0$. The 3-simplices may be indexed to form a sequence $\{\sigma_i^3\}_{i=1}^n$ such that $(\sigma_i^3 \cap \sigma_{i+1}^3)$ is a 2-simplex which is mapped*

onto $f(\sigma^2)$. The set of the 2-simplices of L that are mapped onto $f(\sigma^2)$ can be indexed to form a sequence $\{\sigma_i^2\}_{i=0}^n$ such that, for $1 \leq i < n$, $\sigma_i^2 = (\sigma_i^3 \cap \sigma_{i+1}^3)$, $\sigma_0^2 \in \sigma_1^3$, $\sigma_n^2 \in \sigma_n^3$, and that both σ_0^2 and σ_n^2 lie in $\text{Fr}_2(L)$.

Proof. Let x be a point of $\text{Int}(\sigma^2)$, and let $\{s_i\}_{i=1}^n$ be the sequence formed by indexing the segments of the arc $\alpha = (f^{-1}f(x) \cap L)$ in one of their two possible linear orderings. Let σ_i^3 be the 3-simplex that contains the segment s_i . The sequence $\{\sigma_i^3\}_{i=1}^n$ includes each 3-simplex that is mapped by f onto $f(\sigma^2)$, because each 3-simplex which f maps onto $f(\sigma^2)$ contributes a segment to α (see Lemma 4.3). The ordering is independent of the choice of x . For if x' is another point of $\text{Int}(\sigma^2)$, then one of the two linear orderings $\{s'_i\}_{i=1}^n$ of the segments of the arc $(f^{-1}f(x') \cap L)$ has the property that s'_i belongs to σ_i^3 , and $n' = n$. Since σ_i^3 and σ_{i+1}^3 have a common point that lies in the interior of a 2-face of each, namely $(s_i \cap s_{i+1})$, they must have a 2-face in common. Let σ_i^2 be this face. Since f maps a point of $\text{Int}(\sigma_i^2)$ into the interior of $f(\sigma^2)$, $f(\sigma_i^2) = f(\sigma^2)$. Let σ_0^2, σ_n^2 be the face of σ_1^3, σ_n^3 that is mapped onto $f(\sigma^2)$ but does not lie in $\sigma_2^3, \sigma_{n-1}^3$. (Here we assume $n \geq 2$; if $n = 1$, the proof of the lemma is trivial.) The sequence $\{\sigma_i^2\}_{i=0}^n$ contains all of the 2-simplices of L that are mapped onto $f(\sigma^2)$; for by Lemma 4.1, each 2-simplex of L that is mapped onto $f(\sigma^2)$ lies in a 3-simplex of L which is mapped onto $f(\sigma^2)$, and the sequence $\{\sigma_i^3\}_{i=1}^n$ contains all such 3-simplices.

Let ρ be the other 3-simplex of M of which σ_0^2 is a face, and let y be a point of $\text{Int}(\sigma_0^2)$. If ρ belongs to L , then $f(\rho) = f(\sigma^2)$, by Lemma 4.2. If $f(\rho) = f(\sigma^2)$, then y lies in the interior of the arc $(f^{-1}f(y) \cap L)$. But y is an end-point of the arc. Hence ρ does not lie in L , and σ_0^2 lies in $\text{Fr}_2(L)$. A similar argument shows that σ_n^2 lies in $\text{Fr}_2(L)$.

DEFINITION. A simplex σ of L has property R if it lies in $\text{Fr}(L)$, if it is a proper face of exactly one simplex τ of L , and further, if σ and τ satisfy one of the following two sets of conditions:

- (1) σ is a 2-simplex, τ is a 3-simplex, and $f(\sigma) = f(\tau)$;
- (2) σ is a 1-simplex, τ is a 2-simplex, and $f(\sigma) = f(\tau)$.

LEMMA 4.5. Let σ be a simplex of L which has property R , and let τ be that simplex of L of which σ is a proper face. Let $E = \text{Int}(\sigma) \cup \text{Int}(\tau)$, and let H be the complex $(L - E)$. Let D_1 be the collection of subsets of M that consists of (1) each of the points of $(M - H)$ and (2) each of the sets $(d - E)$, where d is an element of D which lies in L . The collection D_1 is an upper semi-continuous decomposition of M into point-like sets. The union L_1 of the non-degenerate elements of D_1 is a subcomplex of H . Moreover, D_1^* is homeomorphic to D^* .

Proof. We shall furnish first a detailed proof of a special case of the lemma: σ is a 2-simplex σ^2 , τ is a 3-simplex τ^3 , and $f(\sigma^2) = f(\tau^3)$ is a 2-simplex. We shall then suggest analogous proofs for the other cases.

We know from Lemmas 4.3 and 4.4 that $E = \text{Int}(\sigma^2) \cup \text{Int}(\tau^3)$ is decomposed in D into parallel line-segments each of which is a half-open end line-

segment of a polygonal arc of D . It follows that every set in D_1 is either an element of D , a point, or a polygonal arc. Hence D_1 is a decomposition of M into point-like sets. That D_1 is an upper semi-continuous decomposition follows from the fact that $D_1(A) = \text{Cl}(A - H) \cup (D(A \cap H) \cap H)$ for each closed subset A of M .

Let ρ be the other 3-simplex of M of which σ^2 is a face. Since σ^2 has property R , the simplex ρ does not lie in L . Let v_1, v_2 , and v_3 be the vertices of σ^2 . Let v_0 be the remaining vertex of τ^3 , and let v_4 be the remaining vertex of ρ . Let $'\sigma^2 = (v_0v_2v_3)$. We may suppose with no loss of generality that the line-segments into which $\text{Int}(\sigma^3)$ is decomposed in D are parallel to (v_0v_1) . Thus $'\sigma^2$ is decomposed in D into the individual points of $'\sigma^2$. Let $C = \text{Int}(\rho)$, and let $C_1 = \text{Int}(\rho \cup \tau^3)$. Note, for later reference, that $C = (C_1 - E)$. (See Fig. 1.) Let p be the projection mapping of M onto D^* , and let p_1 be the projection mapping of M onto D_1^* .

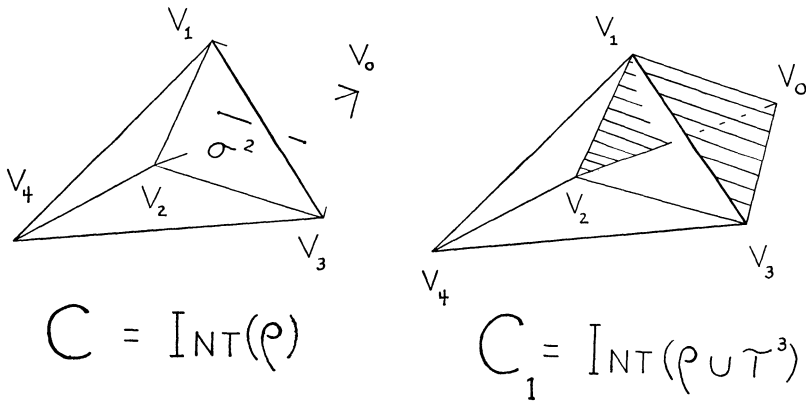


FIGURE 1

To show that D_1^* is homeomorphic to D^* we shall first construct a homeomorphism h of $(D^* - p(C))$ onto $(D_1^* - p_1(C_1))$ which maps $\text{Bdy}(p(\text{Cl}(C)))$ onto $\text{Bdy}(p_1(\text{Cl}(C_1)))$. We then show that $p_1(\text{Cl}(C_1))$ is a 3-cell. Since $p(\text{Cl}(C))$ is also a 3-cell, the homeomorphism $h|_{\text{Bdy}(p(\text{Cl}(C)))}$ can be extended to a homeomorphism h' of $p(\text{Cl}(C))$ onto $p_1(\text{Cl}(C_1))$. The mapping

$$g = \begin{cases} h & \text{on } D^* - p(C), \\ h' & \text{on } p(\text{Cl}(C)) \end{cases}$$

will then be the required homeomorphism of D^* onto D_1^* .

Let $D | (M - C) = \{d | d \in D; d \subset (M - C)\}$.

The collection $D | (M - C)$ is an upper semi-continuous decomposition of $(M - C)$. Certainly $D|(M - C)$ is a decomposition of $(M - C)$, because each point of C is an element of D . Let F be a closed subset of $(M - C)$. The set F is also closed in M . Hence $D(F)$ is closed in M . Since $D(F)$ and C have no point in common, $D(F)$ is closed in $(M - C)$. For the same reason, $D(F)$ is

the union of those elements of $D|(M - C)$ which meet F . Therefore, $D|(M - C)$ is an upper semi-continuous decomposition.

The space $(D^* - p(C))$, with the relative topology, is the hyperspace of $D|(M - C)$. The mapping $\pi = p|(M - C)$ throws $(M - C)$ onto $D|(M - C)$. Let S be a subset of $D|(M - C)$. If $\pi^{-1}(S)$ is open in $(M - C)$, then $(\pi^{-1}(S) \cup C)$ is open in M . Since $(\pi^{-1}(S) \cup C) = p^{-1}(S \cup p(C))$, the set $(S \cup p(C))$ is open in D^* , and S is open in the relative topology of $(D^* - p(C))$. Now let S be an open subset of $(D^* - p(C))$. Then the set $(S \cup p(C))$ is open in D^* , and the set $p^{-1}(S \cup p(C))$ is open in M . Moreover, $p^{-1}(S \cup p(C)) = (p^{-1}(S) \cup C)$. Therefore, $p^{-1}(S)$ is open in $(M - C)$. Since $\pi^{-1}(S) = p^{-1}(S)$, the set $\pi^{-1}(S)$ is open in $(M - C)$. Thus the relative topology for $(D^* - p(C))$ is exactly the topology induced on $D|(M - C)$ by π , and π is the projection mapping of $D|(M - C)$ onto $(D^* - p(C))$.

In a similar manner it can be proved that

$$D_1|(M - C_1) = \{d_1 \mid d_1 \in D_1, d_1 \subset (M - C_1)\}$$

is an upper semi-continuous decomposition of $(M - C_1)$, and that

$$\pi_1 = p_1 \mid (M - C_1)$$

is the projection mapping of $D_1|(M - C_1)$ onto $(D_1^* - p_1(C_1))$.

For each point x in $(D^* - p(C))$, let $h(x) = \pi_1(\pi^{-1}(x) - E)$.

For each x in $(D^* - p(C))$, $h(x)$ is a well-defined point. Let x_1 and x_2 be points of $(D^* - p(C))$. If $\pi_1(\pi^{-1}(x_1) - E)$ is not equal to $\pi_1(\pi^{-1}(x_2) - E)$, then

$$\begin{aligned} (\pi^{-1}(x_1) - E) &\neq (\pi^{-1}(x_2) - E), \\ \pi^{-1}(x_1) &\neq \pi^{-1}(x_2), \end{aligned}$$

and $x_1 \neq x_2$.

The function h throws $(D^* - p(C))$ into $(D_1^* - p_1(C_1))$. For if x is a point of $(D^* - p(C))$, then $(\pi^{-1}(x) - E)$ is an element of $D_1|(M - C_1)$.

The function h throws $(D^* - p(C))$ onto $(D_1^* - p_1(C_1))$. Let y be a point of $(D_1^* - p_1(C_1))$. Then $\pi_1^{-1}(y)$ is an element of $D_1|(M - C_1)$. Moreover, $\pi_1^{-1}(y)$ lies in an element d of $D|(M - C)$ such that $(d - E) = \pi_1^{-1}(y)$. If $\pi_1^{-1}(y)$ does not meet $\text{Int}(\sigma^2)$, then the element d is the set $\pi_1^{-1}(y)$ itself. If $\pi_1^{-1}(y)$ meets $\text{Int}(\sigma^2)$, then $(\pi_1^{-1}(y) \cap \text{Int}(\sigma^2))$ is a point q , because σ^2 is decomposed into individual points. Moreover, if $\pi_1^{-1}(y)$ meets $\text{Int}(\sigma^2)$, then d is the polygonal arc $(f^{-1}(f(q)) \cap L)$ which has an end line-segment joining σ^2 to $\text{Int}(\sigma^2)$ and lies parallel to (v_0v_1) . Thus if $\pi_1^{-1}(y)$ meets $\text{Int}(\sigma^2)$, then,

$$\pi_1^{-1}(y) = (f^{-1}(f(q)) \cap H) = (d - E).$$

In either case, there is a point x in $(D^* - p(C))$ such that $d = \pi^{-1}(x)$, and $y = h(x)$.

The function h is one-to-one. If x_1 and x_2 are points of $(D^* - p(C))$, then

$$\pi^{-1}(x_1) \cap \pi^{-1}(x_2) = \emptyset,$$

and

$$(\pi^{-1}(x_1) - E) \cap (\pi^{-1}(x_2) - E) = \emptyset.$$

The sets $(\pi^{-1}(x_1) - E)$ and $(\pi^{-1}(x_2) - E)$ are distinct elements of $D_1|(M - C_1)$, and they have distinct images under π_1 .

The function h^{-1} is continuous. Let $\{x_i\}_{i=1}^\infty$ be a sequence of points converging to a point x in $(D_1^* - p_1(C_1))$. By Lemma 3.4,

$$\lim z(\pi_1^{-1}(x_i), \pi_1^{-1}(x)) = 0.$$

The set $\pi_1^{-1}(x_i)$ lies in an element d_i of $D|(M - C)$, and $\pi_1^{-1}(x)$ lies in an element d of $D|(M - C)$. For each i ,

$$z(\pi_1^{-1}(x_i), \pi_1^{-1}(x)) \geq z(d_i, d).$$

Therefore, $\lim z(d_i, d) = 0$. Therefore, by another application of Lemma 3.4, the sequence $\{\pi(d_i)\}_{i=1}^\infty$ converges to $\pi(d)$ in $(D^* - p(C))$. Since $\pi(d_i) = h^{-1}(x_i)$, and since $\pi(d) = h^{-1}(x)$, the sequence $\{h^{-1}(x_i)\}_{i=1}^\infty$ converges to the point $h^{-1}(x)$.

The function h is a homeomorphism. By Lemma 3.3, the space $(D_1^* - p_1(C_1))$ is compact. By Lemma 3.1, the mapping h^{-1} is a homeomorphism, for, by Lemma 3.2, $(D^* - p(C))$ is a Hausdorff space.

The next few paragraphs show that the set $p_1(\text{Cl}(C_1))$ is a closed 3-cell.

In E^3 , let $w_0 = (0, 0, 1)$, $w_1 = (0, 0, 0)$, $w_2 = (0, 1, 0)$, $w_3 = (1, 0, 0)$, and $w_4 = (0, 0, -1)$. Let $\rho' = (w_1w_2w_3w_4)$, $\tau' = (w_0w_1w_2w_3)$, $\sigma_1 = (w_1w_2w_3)$, and $\sigma_2 = (w_0w_2w_3)$. Map $\text{Cl}(C_1)$ onto $(\rho' \cup \tau')$ with the simplicial homeomorphism l that sends v_i onto w_i . Line-segments parallel to (v_0v_1) are mapped onto line-segments parallel to (w_0w_1) in the z -axis.

Let b be the barycentre of σ_2 , let Σ be the union of the affine 2-simplices (w_1w_3b) and (w_1w_2b) , and let τ'' be the affine 3-simplex $(w_1w_2w_3b)$. (See Fig. 2.)

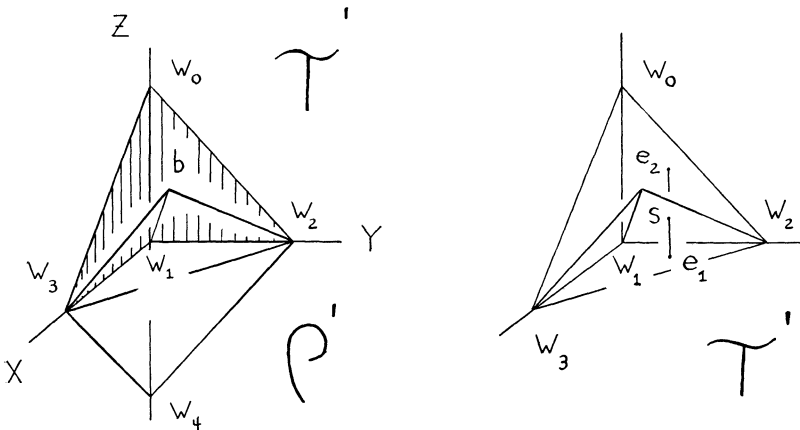


FIGURE 2

Let S be a line-segment in τ' joining σ_1 to σ_2 and parallel to the z -axis. Let $(S \cap \sigma_i) = e_i$ ($i = 1, 2$), and let $(S \cap \Sigma) = s$. Map S into itself by mapping e_1 onto e_1 , by mapping e_2 onto s , and by mapping the linear interval $[e_2, e_1]$ linearly onto the linear interval $[s, e_1]$. Call this mapping π_s .

Map $(\rho' \cup \tau')$ onto $(\rho' \cup \tau'')$ by keeping the points of ρ' fixed and mapping x onto $\pi_s(x)$ if x does not lie in ρ' . Call this mapping k .

The mapping $p_1 l^{-1} k^{-1}$ is a homeomorphism of the 3-cell $(\rho' \cup \tau'')$ onto $p_1(\text{Cl}(C_1))$.

Now that we know that D is upper semi-continuous and that D_1^* is homeomorphic to D^* , it remains to show that L_1 is a subcomplex of H . Let ρ^3 be the other 3-simplex of M that contains σ^2 (see page 596). We divide the proof into two parts, according to whether ρ^3 lies in L .

(1) Suppose that ρ^3 does not belong to L . Then by Lemma 4.4, no other 3-simplex of L maps onto $f(\sigma^2)$, and by Lemma 4.3, if an element d of D has a non-empty intersection with $\text{Int}(\sigma^2)$ then d is a line-segment joining σ^2 to ρ^3 and lying parallel to that edge of τ^3 which does not meet $(\sigma^2 \cap \rho^3)$. Thus, if d meets $\text{Int}(\sigma^2)$, then $(d - E)$ is a point of $\text{Int}(\rho^3)$ and if $(d \cap \text{Int}(\sigma^2))$ is empty, then $(d - E) = d$. Hence $L_1 = (H - \text{Int}(\rho^3))$.

(2) If ρ^3 lies in L , then, by Lemma 3.3, $f(\rho^3) = f(\sigma^2)$, and $L_1 = H$.

In either case, L_1 is a subcomplex of H , and we have proved Lemma 4.5 for the case $\sigma = \sigma^2$, $\tau = \tau^3$, and $f(\sigma) = f(\tau)$ is a 2-simplex.

With a very few alterations, the preceding arguments establish Lemma 4.5 for the (less complicated) cases in which σ is a 2-simplex, τ is a 3-simplex, and $f(\sigma) = f(\tau)$ is either a 1-simplex or a vertex. Define

$$\rho, C = \text{Int}(\rho), C_1 = \text{Int}(\rho \cup \tau), p, p_1, \pi, \pi_1, \text{ etc.},$$

as before. Then $h(x) = \pi_1(\pi^{-1}(x) - E)$ is a homeomorphism of $(D^* - p(C))$ onto $(D_1^* - p_1(C_1))$, the sets $p(\text{Cl}(C))$ and $p_1(\text{Cl}(C_1))$ are closed 3-cells, and the homeomorphism $h|_{\text{Bdy}(\text{Cl}(C))}$ may be extended to a homeomorphism h' of $p(\text{Cl}(C))$ onto $p_1(\text{Cl}(C_1))$ in order to give a homeomorphism g of D^* onto D_1^* .

If σ is a 1-simplex, and if τ is a 2-simplex, however, the cells C and C_1 must be constructed in some other way. A suitable construction is the following. (See Fig. 3.)

Let v_1 and v_2 be the vertices of σ , and let v_0 be the other vertex of τ . Let A be the complex consisting of the faces of all the simplices of M of which σ is an edge. The complex A is a 3-cell, and $(A \cap L)$ lies in $(\text{Bdy}(A) \cup \tau)$. The 3-simplices of A may be ordered cyclically around σ to form a sequence $\sigma_1^3, \dots, \sigma_n^3$ such that σ_1^3 and σ_n^3 are the two 3-simplices of M of which τ is a face. For each i ($1 \leq i < n$) let $\sigma_i^2 = (\sigma_i^3 \cap \sigma_{i+1}^3)$, and let b_i be the barycentre of σ_i^2 . Let $\rho_1^3 = (v_0 v_1 v_2 b_1)$. For each i ($1 < i < n$) let $\rho_i^3 = (b_i b_{i-1} v_1 v_2)$. Let $\rho_n^3 = (b_{n-1} v_0 v_1 v_2)$. The set $Z = \cup \rho_i^3$ is a 3-cell such that $(Z \cap L) = \tau$. (See Fig. 4.)

Recall that $E = \text{Int}(\sigma) \cup \text{Int}(\tau)$. The argument for the preceding cases can now be carried out for σ and τ by defining $C = (\text{Int}(Z) - E)$ and

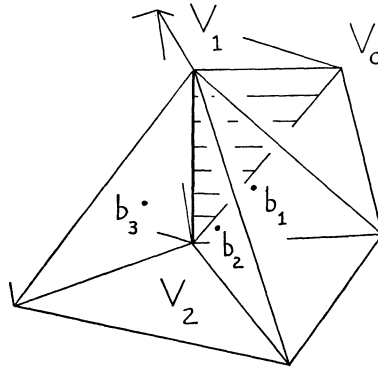


FIGURE 3

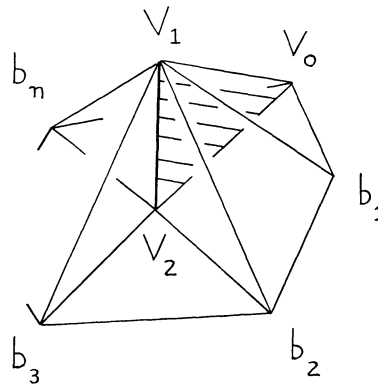


FIGURE 4

$C_1 = \text{Int}(Z)$, and by using the fact that, since $f(\tau)$ is a 1-simplex, τ is decomposed into line-segments parallel, say, to (v_0v_1) . (Compare this last definition of C and of C_1 with the definition on page 596.)

5. Applying Lemma 4.5. Since we have assumed K to be non-empty, the following lemma shows that $\text{Fr}_2(K)$ is non-empty.

LEMMA 5.1. *The mapping f is one-to-one on some 3-simplex of M .*

Proof. The space T cannot consist of a single point, because then f would not be point-like. Nor can T consist entirely of 1-simplices, for then some pair of points would separate T and their inverses would separate M . Hence T contains a 2-simplex τ . If $\text{Cl}(f^{-1}(\text{Int}(\tau))) = C$ is a 2-simplex, then f is one-to-one on each of the two 3-simplices of M of which C is a face. If C is not a 2-simplex, then f maps at least one other 2-simplex of M onto τ , and by applying Lemma 4.4, with $L = K$, we find that C contains a 2-simplex σ in $\text{Fr}(K)$. Then f is one-to-one on the other 3-simplex of M that contains σ .

Remark. Lemma 5.1 generalizes to n dimensions using the Vietoris mapping theorem.

LEMMA 5.2. *The construction of Lemma 4.5 may be applied to G and K .*

Proof. The decomposition G and the complex K satisfy the hypotheses of the preceding section for D and L , respectively. Also, $\text{Fr}_2(K)$ is non-empty, and each 2-simplex of $\text{Fr}_2(K)$ has property R . Let σ be a 2-simplex of $\text{Fr}_2(K)$, let τ be the 3-simplex of K that contains σ , and let ρ be the other 3-simplex of M that contains σ . Since σ belongs to $\text{Fr}_2(K)$, the simplex ρ does not lie in K . Hence $f(\rho)$ is a 3-simplex and $f(\sigma)$ is a 2-simplex. The simplices σ and τ satisfy the requirements in the definition of property R .

Let G_i be the decomposition obtained from the first $i > 0$ applications of the construction of Lemma 4.5, and let K_i be the union of the non-degenerate elements of G_i .

LEMMA 5.3. *The decomposition G_i is an upper semi-continuous decomposition of M into point-like sets, K_i is a proper subcomplex of K_{i-1} , and G_i^* is homeomorphic to G^* .*

COROLLARY. *If K_i contains a simplex with property R , then the construction of Lemma 4.5 may be applied to G_i and to K_i .*

Proof. The lemma follows easily by mathematical induction and from Lemma 4.5, the corollary from observing that G_i and K_i satisfy the hypotheses of Lemma 4.5 whenever K_i contains a simplex with property R .

DEFINITION. *If K_n contains no simplex with property R , then K_n is minimal.*

That a minimal complex K_n exists follows from the facts that (1) K is a finite complex, and (2) for each $i > 0$, the complex K_i is a proper subcomplex of K_{i-1} .

LEMMA 5.4. *If K_n is minimal, then K_n is the union of a finite number of disjoint, point-like sets.*

Proof. We first show that K_n contains no 3-simplex.

Suppose that C is a component of K_n which contains a 3-simplex. Since $(M - K) \neq \emptyset$ (see Lemma 5.1), the set $(M - C)$ is non-empty. Hence $\text{Fr}_2(C)$ is non-empty. Let σ^2 be a 2-simplex lying in $\text{Fr}_2(C)$, and let τ^3 be the 3-simplex of C that contains σ^2 . If $f(\sigma^2)$ is a 2-simplex, then, by Lemma 4.2,

$f(\sigma^2) = f(\tau^3)$, the simplex σ^2 has property R , and K_n is not minimal. Hence $f(\sigma^2)$ is either a 1-simplex or a vertex. If $f(\sigma^2)$ is a 1-simplex, then $f(\tau^3)$ must be a 2-simplex, for otherwise K_n again fails to be minimal. But if $f(\tau^3)$ is a 2-simplex, then, by Lemma 4.4, τ^3 is one of a sequence of 3-simplices mapped onto $f(\tau^3)$, one of these 3-simplices has a 2-face that both maps onto $f(\tau^3)$ and lies in $\text{Fr}(K_n)$, this 2-face has property R , and K_n is not minimal. Thus every 2-simplex of $\text{Fr}_2(\mathcal{C})$ is mapped onto a vertex by f .

Let B be the component of $\text{Fr}_2(\mathcal{C})$ that contains σ^2 . Since $f(\sigma^2)$ is a vertex, σ^2 lies in some element g of G_n . Since B is connected, and since each simplex of B is mapped by f onto a vertex, each simplex of B is mapped onto $f(\sigma^2)$, and B is a subset of g .

Let x be a point of $(M - K)$. Since $g \subset K_n \subset K$, the point x does not lie in g . Let y be a point of $\text{Int}(\tau^3)$. The component B separates x from y . Hence g separates x from y , unless y belongs to g . Because g is point-like, g cannot separate two points of M . Therefore, y does lie in g . Hence

$$f(\tau^3) = f(g) = f(\sigma^2),$$

and K_n is not minimal. Hence K_n contains no 3-simplex.

We show next that every 2-simplex of K_n is mapped by f onto a vertex.

Let σ^2 be a 2-simplex lying in K_n . The simplex $f(\sigma^2)$ cannot be a 2-simplex, for if it were, then by Lemma 4.1, σ^2 would belong to a 3-simplex of K_n . If $f(\sigma^2)$ is a 1-simplex σ' , then $\text{Fr}(K)$ contains a 1-simplex with property R . To see this, let y be a point of $\text{Int}(\sigma')$, and let H be the set of all points of K_n that are mapped by f onto y . Since K_n contains no 3-simplex, H is the union of a finite number of line-segments, one from each 2-simplex of K_n that is mapped onto σ' . The line-segments meet only at their end-points, and H contains no 1-sphere because H , being an element of G_n , is point-like. We shall call an end-point of a line-segment of H a "free vertex" if it belongs to only that one line-segment. It is well known that a finite, 1-dimensional complex which contains no 1-sphere has at least two free vertices. Let σ'' be an edge of K_n which contains a free vertex of H . The simplex σ'' belongs to exactly one 2-simplex σ'^2 of K_n , and $f(\sigma'') = f(\sigma'^2)$. Therefore, σ'' has property R . Since K_n contains no such simplex, f must map each 2-simplex of K_n onto a vertex.

We can now show that every 1-simplex of K_n is mapped by f onto a vertex. If σ is a 1-simplex of K_n , then $f(\sigma)$ is either a 1-simplex or a vertex. If σ is an edge of a 2-simplex τ^2 of K_n , then $f(\sigma) = f(\tau^2)$ is a vertex. If σ lies in no 2-simplex of K_n , then $f(\sigma)$ must still be a vertex, for if $f(\sigma)$ were a 1-simplex, each point of $\text{Int}(\sigma)$ would be an element of G_n , contrary to the fact that K_n contains only non-degenerate elements of G_n .

Since every 1-simplex of K_n is mapped by f onto a vertex of Y , each component of K_n is mapped onto some vertex of Y and must therefore be an element of G_n . Elements of G_n are point-like, components of K_n are disjoint, and Lemma 5.4 is proved.

Remark. After seeing that a minimal K_n contains no 3-simplex, one might try to show that it also contains no 2-simplex. One could then continue the reduction of the one-dimensional K_n to a finite set of vertices, and there would be no need for Lemma 5.5. However, a minimal K_n may contain a 2-dimensional component each edge of which lies in more than one 2-simplex (e.g., a pleated disk). One cannot reduce such a component. Fortunately, all components of a minimal K_n are already point-like.

It remains to state one more lemma before proceeding to the proof of the theorem.

LEMMA 5.5. *If D is a decomposition of a 3-sphere into point-like sets, and if D has only finitely many non-degenerate elements, then D^* is homeomorphic to the sphere.*

Remark. This lemma is a special case of the following, which is easy to prove: If D is a decomposition of an n -manifold N into cellular sets and if D has only finitely many non-degenerate elements, then D^* is homeomorphic to N . A subset of an n -manifold is *cellular* if there exist closed n -cells C_i ($i = 1, 2, \dots$) in N such that $A = \bigcap C_i$, and such that, for each i , the cell C_{i+1} is contained in the interior of the cell C_i . The concepts *cellular* and *point-like* are equivalent for subsets of S^n .

6. The proof of the theorem.

THEOREM. *Let M be a triangulated 3-sphere and let T be a triangulated topological space. If there exists a point-like, simplicial mapping of M onto T , then T is homeomorphic to M .*

Apply the construction of Lemma 4.5 to G and K until a hyperspace G_n^* with a minimal complex K_n is obtained. The complex K_n will be the union of a finite number of point-like elements of G_n (Lemma 5.4) and hence G_n^* will be homeomorphic to M (Lemma 5.5). But G^* is homeomorphic to G_n^* (Lemma 5.3) and T is homeomorphic to G^* (Lemma 3.5). Thus T is homeomorphic to M .

Remark. A mapping g of an n -manifold N is called *cellular* if the set $g^{-1}(x)$ is cellular for each point x in $g(N)$. The arguments of this paper are easily modified to show that if there exists a cellular, simplicial mapping of a triangulated compact 3-manifold M onto a triangulated topological space T , then T is homeomorphic to M .

I should like to close with the following question. Can every orientation-preserving, point-like, simplicial mapping of the 3-sphere be factored into a product of simplicial mappings of the sphere onto itself each of which identifies exactly two vertices, those bounding a 1-simplex?

REFERENCES

1. R. H. Bing, *A decomposition of E^3 into points and tame arcs such that the decomposition space is topologically different from E^3* , Ann. of Math., 65 (1957), 484–500.
2. O. G. Harrold, Jr., *A sufficient condition that a monotone image of the three-sphere be a topological three-sphere*, Proc. Amer. Math. Soc., 9 (1958), 846–850.
3. R. L. Moore, *Concerning upper semi-continuous collections of continua*, Trans. Amer. Math. Soc., 27 (1925), 416–428.
4. J. H. Roberts and N. E. Steenrod, *Monotone transformations of two-dimensional manifolds*, Ann. of Math., 39 (1938), 851–862.
5. G. T. Whyburn, *On the structure of continua*, Bull. Amer. Math. Soc., 42 (1936), 49–73.

*Massachusetts Institute of Technology,
Cambridge, Massachusetts, and
University of Michigan*